



# On Trans-Sasakian Manifolds with the Schouten-van Kampen Connection

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## Abstract

The object of the present paper is to characterize 3-dimensional trans-Sasakian manifolds with respect to the Schouten-van Kampen connection.

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## 1. Introduction

Trans-Sasakian manifolds arose in a natural way from the classification of almost contact metric structures by Chinae and Gonzales [4]. These type of manifolds appear as a natural generalization of both Sasakian and Kenmotsu manifolds. In the Gray-Hervella classification of almost Hermitian manifolds [6], there appears a class,  $W_4$ , of Hermitian manifolds which are closely related to locally conformal Kaehler manifolds [3]. An almost contact metric structure on a manifold  $M$  is called a trans-Sasakian structure [12] if the product manifold  $M \times \mathbb{R}$  belongs to the class  $W_4$ . The class  $C_6 \oplus C_5$  [11] coincides with the class of the trans-Sasakian structures of type  $(\alpha, \beta)$ . In [11], local nature of the two subclasses, namely,  $C_5$  and  $C_6$  structures of trans-Sasakian structures are characterized completely.

We note that trans-Sasakian structures of type  $(0, 0)$ ,  $(0, \beta)$  and  $(\alpha, 0)$  are cosymplectic [2],  $\beta$ -Kenmotsu [8] and  $\alpha$ -Sasakian [8], respectively. Also it is proved that trans-Sasakian structures are generalized quasi-Sasakian [8]. Thus, trans-Sasakian structures also provide a large class of generalized quasi-Sasakian structures.

On the other hand the Schouten-van Kampen connection is one of the most natural connections adapted to a pair of complementary distributions on a differentiable manifold endowed with an affine connection [1, 7, 9, 14]. Solov'ev investigated hyperdistributions in Riemannian manifolds using the Schouten-van Kampen connection [15, 16, 17, 18]. Then Olszak studied the Schouten-van Kampen connection to an almost contact metric structure and characterized some classes of almost contact metric manifolds with the Schouten-van Kampen connection and found certain curvature properties of this connection on these manifolds [13]. Also, Yıldız studied projectively flat and conharmonically flat 3-dimensional  $f$ -Kenmotsu manifolds with the Schouten-van Kampen connection [19].

The present paper is organized as follows: After preliminaries, we give some basic information about the Schouten-van Kampen connection and trans-Sasakian manifolds. Then we adapt the Schouten-van Kampen connection on 3-dimensional trans-Sasakian manifolds. In section 5, we consider projectively flat and conharmonically flat 3-dimensional trans-Sasakian manifolds with respect to the Schouten-van Kampen connection. In the last section, we give an example of a 3-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection.

## 2. Preliminaries

Let  $M$  be a connected almost contact metric manifold with an almost contact metric structure  $(\phi, \xi, \eta, g)$ , that is,  $\phi$  is an  $(1, 1)$ -tensor field,  $\xi$  is a vector field,  $\eta$  is a 1-form and  $g$  is the compatible Riemannian metric such that

$$\phi^2(X) = -X + \eta(X)\xi, \quad \eta(\xi) = 1, \quad \phi\xi = 0, \quad \eta \circ \phi = 0, \quad (2.1)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (2.2)$$

$$g(X, \phi Y) = -g(\phi X, Y), \quad g(X, \xi) = \eta(X), \tag{2.3}$$

for all  $X, Y \in TM$  [2]. The fundamental 2-form  $\Phi$  of the manifold is defined by

$$\Phi(X, Y) = g(X, \phi Y), \tag{2.4}$$

for  $X, Y \in TM$ .

An almost contact metric struce  $(\phi, \xi, \eta, g)$  on a connected manifold  $M$  is called trans-Sasakian structure [12] if  $(M \times \mathbb{R}, J, G)$  belongs to the class  $W_4$  [6], where  $J$  is the almost complex structure on  $M \times \mathbb{R}$  defined by

$$J(X, fd/dt) = (\phi X - f\xi, \eta(X)d/dt),$$

for all vector fields  $X$  on  $M$  and smooth function  $f$  on  $M \times \mathbb{R}$ , and  $G$  is the product metric on  $M \times \mathbb{R}$ . This may be expressed by the condition [3]

$$(\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\phi X, Y)\xi - \eta(Y)\phi X), \tag{2.5}$$

for smooth functions  $\alpha$  and  $\beta$  on  $M$ . Here we say that the trans-Sasakian structure is of type  $(\alpha, \beta)$ . From the formula (2.5) it follows that

$$\nabla_X \xi = -\alpha\phi X + \beta(X - \eta(X)\xi), \tag{2.6}$$

$$(\nabla_X \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y). \tag{2.7}$$

An explicit example of 3-dimensional proper trans-Sasakian manifold was constructed in [10]. In [5], the Ricci tensor and curvature tensor for 3-dimensional trans-Sasakian manifolds were studied and their explicit formulae were given.

From [5] we know that for a 3-dimensional trans-Sasakian manifold

$$2\alpha\beta + \xi\alpha = 0, \tag{2.8}$$

$$S(X, \xi) = (2(\alpha^2 - \beta^2) - \xi\beta)\eta(X) - X\beta - (\phi X)\alpha, \tag{2.9}$$

$$\begin{aligned} S(X, Y) &= \left(\frac{\tau}{2} + \xi\beta - (\alpha^2 - \beta^2)\right)g(X, Y) \\ &\quad - \left(\frac{\tau}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(X)\eta(Y) \\ &\quad - (Y\beta + (\phi Y)\alpha)\eta(X) - (X\beta + (\phi X)\alpha)\eta(Y), \end{aligned} \tag{2.10}$$

and

$$\begin{aligned} R(X, Y)Z &= \left(\frac{\tau}{2} + 2\xi\beta - 2(\alpha^2 - \beta^2)\right)(g(Y, Z)X - g(X, Z)Y) \\ &\quad - g(Y, Z)\left[\left(\frac{\tau}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(X)\xi \right. \\ &\quad \left. - \eta(X)(\phi grad\alpha - grad\beta) + (X\beta + (\phi X)\alpha)\xi\right] \\ &\quad + g(X, Z)\left[\left(\frac{\tau}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(Y)\xi \right. \\ &\quad \left. - \eta(Y)(\phi grad\alpha - grad\beta) + (Y\beta + (\phi Y)\alpha)\xi\right] \\ &\quad - [(Z\beta + (\phi Z)\alpha)\eta(Y) + (Y\beta + (\phi Y)\alpha)\eta(Z) \\ &\quad + \left(\frac{\tau}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(Y)\eta(Z)]X \\ &\quad + [(Z\beta + (\phi Z)\alpha)\eta(X) + (X\beta + (\phi X)\alpha)\eta(Z) \\ &\quad + \left(\frac{\tau}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(X)\eta(Z)]Y, \end{aligned} \tag{2.11}$$

where  $S$  is the Ricci tensor,  $R$  is the curvature tensor and  $\tau$  is the scalar curvature of the manifold  $M$ , respectively.

For constants  $\alpha$  and  $\beta$  are the above relations become

$$\begin{aligned} S(X, Y)Z &= \left(\frac{\tau}{2} - 2(\alpha^2 - \beta^2)\right)(g(Y, Z)X - g(X, Z)Y) \\ &\quad - \left(\frac{\tau}{2} - 3(\alpha^2 - \beta^2)\right)(g(Y, Z)\eta(X)\xi - g(X, Z)\eta(Y)\xi \\ &\quad + \eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y), \end{aligned} \tag{2.12}$$

$$S(X, Y) = \left(\frac{\tau}{2} - (\alpha^2 - \beta^2)\right)g(X, Y) - \left(\frac{\tau}{2} - 3(\alpha^2 - \beta^2)\right)\eta(X)\eta(Y), \tag{2.13}$$

$$S(X, \xi) = 2(\alpha^2 - \beta^2)\eta(X), \tag{2.14}$$

$$R(X, Y)\xi = (\alpha^2 - \beta^2)(\eta(Y)X - \eta(X)Y), \tag{2.15}$$

$$QX = \left(\frac{\tau}{2} - (\alpha^2 - \beta^2)\right)X - \left(\frac{\tau}{2} - 3(\alpha^2 - \beta^2)\right)\eta(X)\xi. \tag{2.16}$$

From (2.8) it follows that if  $\alpha$  and  $\beta$  are constants, then the manifold is either  $\alpha$ -Sasakian or  $\beta$ -Kenmotsu or cosymplectic.

### 3. The Schouten-van Kampen connection

Let  $M$  be a connected pseudo-Riemannian manifold of an arbitrary signature  $(p, n-p)$ ,  $0 \leq p \leq n$ ,  $n = \dim M \geq 2$ . By  $g$  and  $\nabla$  we denote the pseudo-Riemannian metric and Levi-Civita connection induced from the metric  $g$  on  $M$  respectively. Assume that  $H$  and  $V$  are two complementary, orthogonal distributions on  $M$  such that  $\dim H = n-1$ ,  $\dim V = 1$ , and the distribution  $V$  is non-null. Thus  $TM = H \oplus V$ ,  $H \cap V = \{0\}$  and  $H \perp V$ . Assume that  $\xi$  is a unit vector field and  $\eta$  is a linear form such that  $\eta(\xi) = 1$ ,  $g(\xi, \xi) = \varepsilon = \pm 1$  and

$$H = \ker \eta, \quad V = \text{span}\{\xi\}. \quad (3.1)$$

We can always choose such  $\xi$  and  $\eta$  at least locally (in a certain neighborhood of an arbitrary chosen point of  $M$ ). We also have  $\eta(X) = \varepsilon g(X, \xi)$ . Moreover, it holds that  $\nabla_X \xi \in H$ .

For any  $X \in TM$ , by  $X^h$  and  $X^v$  we denote the projections of  $X$  onto  $H$  and  $V$ , respectively. Thus, we have  $X = X^h + X^v$  with

$$X^h = X - \eta(X)\xi, \quad X^v = \eta(X)\xi. \quad (3.2)$$

The Schouten-van Kampen connection  $\tilde{\nabla}$  associated to the Levi-Civita connection  $\nabla$  and adapted to the pair of the distributions  $(H, V)$  is defined by [1]

$$\tilde{\nabla}_X Y = (\nabla_X Y^h)^h + (\nabla_X Y^v)^v, \quad (3.3)$$

and the corresponding second fundamental form  $B$  is defined by  $B = \nabla - \tilde{\nabla}$ . Note that the condition (3.3) implies the parallelism of the distributions  $H$  and  $V$  with respect to the Schouten-van Kampen connection  $\tilde{\nabla}$ .

From (3.2), one can compute

$$\begin{aligned} (\nabla_X Y^h)^h &= \nabla_X Y - \eta(\nabla_X Y)\xi - \eta(Y)\nabla_X \xi, \\ (\nabla_X Y^v)^v &= (\nabla_X \eta)(Y)\xi + \eta(\nabla_X Y)\xi, \end{aligned}$$

which enables us to express the Schouten-van Kampen connection with the help of the Levi-Civita connection in the following way [15]

$$\tilde{\nabla}_X Y = \nabla_X Y - \eta(Y)\nabla_X \xi + (\nabla_X \eta)(Y)\xi. \quad (3.4)$$

Thus, the second fundamental form  $B$  and the torsion  $\tilde{T}$  of  $\tilde{\nabla}$  are [15, 16]

$$B(X, Y) = \eta(Y)\nabla_X \xi - (\nabla_X \eta)(Y)\xi,$$

and

$$\tilde{T}(X, Y) = \eta(X)\nabla_Y \xi - \eta(Y)\nabla_X \xi + 2d\eta(X, Y)\xi.$$

With the help of the Schouten-van Kampen connection (3.4), many properties of some geometric objects connected with the distributions  $H$ ,  $V$  can be characterized [15, 16, 17]. Probably, the most spectacular is the following statement:  $g$ ,  $\xi$  and  $\eta$  are parallel with respect to  $\tilde{\nabla}$ , that is,  $\tilde{\nabla}\xi = 0$ ,  $\tilde{\nabla}g = 0$ ,  $\tilde{\nabla}\eta = 0$ .

### 4. Trans-Sasakian manifolds with respect to the Schouten-van Kampen connection

Let  $M$  be a 3-dimensional trans-Sasakian manifold with  $\alpha$  and  $\beta$  are constants with respect to the Schouten-van Kampen connection. Then using (2.6) and (2.7) in (3.4), we get

$$\tilde{\nabla}_X Y = \nabla_X Y + \alpha\{\eta(Y)\phi X - g(\phi X, Y)\xi\} + \beta\{g(X, Y)\xi - \eta(Y)X\}. \quad (4.1)$$

Let  $R$  and  $\tilde{R}$  be the curvature tensors of the Levi-Civita connection  $\nabla$  and the Schouten-van Kampen connection  $\tilde{\nabla}$

$$R(X, Y) = [\nabla_X, \nabla_Y] - \nabla_{[X, Y]}, \quad \tilde{R}(X, Y) = [\tilde{\nabla}_X, \tilde{\nabla}_Y] - \tilde{\nabla}_{[X, Y]}.$$

Using (4.1), by direct calculations, we obtain the following formula connecting  $R$  and  $\tilde{R}$  on a 3-dimensional trans-Sasakian manifold  $M$

$$\begin{aligned} \tilde{R}(X, Y)Z &= R(X, Y)Z \\ &+ \alpha^2\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y + \eta(X)\eta(Z)Y \\ &- \eta(Y)\eta(Z)X - g(Y, Z)\eta(X)\xi + g(X, Z)\eta(Y)\xi\} \\ &+ \beta^2\{g(Y, Z)X - g(X, Z)Y\}. \end{aligned} \quad (4.2)$$

We will also consider the Riemann curvature  $(0, 4)$ -tensors  $\tilde{R}, R$ , the Ricci tensors  $\tilde{S}, S$ , the Ricci operators  $\tilde{Q}, Q$  and the scalar curvatures  $\tilde{\tau}, \tau$  of the connections  $\tilde{\nabla}$  and  $\nabla$  are given by

$$\begin{aligned} \tilde{R}(X, Y, Z, W) &= R(X, Y, Z, W) \\ &+ \alpha^2\{g(\phi Y, Z)g(\phi X, W) - g(\phi X, Z)g(\phi Y, W) \\ &+ g(Y, W)\eta(X)\eta(Z) - g(X, W)\eta(Y)\eta(Z) \\ &- g(Y, Z)\eta(X)\eta(W) + g(X, Z)\eta(Y)\eta(W)\} \\ &+ \beta^2\{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\}, \end{aligned} \quad (4.3)$$

$$\tilde{S}(Y, Z) = S(Y, Z) + 2\beta^2 g(Y, Z) - 2\alpha^2 \eta(Y)\eta(Z), \quad (4.4)$$

$$\tilde{Q}X = QX + 2\beta^2 X - 2\alpha^2 \eta(X)\xi, \quad (4.5)$$

$$\tilde{\tau} = \tau - 2\alpha^2 + 6\beta^2, \quad (4.6)$$

respectively, where  $\tilde{R}(X, Y, Z, W) = g(\tilde{R}(X, Y)Z, W)$  and  $R(X, Y, Z, W) = g(R(X, Y)Z, W)$ .

### 5. Main results

In this section, we give some geometric results on 3-dimensional trans-Sasakian manifolds with  $\alpha$  and  $\beta$  are constants with respect to the Schouten-van Kampen connection.

The *Projective curvature tensor* is an important tensor from the differential geometric point of view. If there exists a one-to-one correspondence between each coordinate neighbourhood of  $M$  and a domain in Euclidean space such that any geodesic of the Riemannian manifold corresponds to a straight line in the Euclidean space, then  $M$  is said to be locally projectively flat. For  $n \geq 1$ ,  $M$  is locally projectively flat if and only if the projective curvature tensor  $P$  vanishes. In fact  $M$  is projectively flat if and only if it is of constant curvature [2]. Thus the projective curvature tensor is the measure of the failure of a Riemannian manifold to be of constant curvature.

In a 3-dimensional trans-Sasakian manifold, the projective curvature tensor with respect to the Schouten-van Kampen connection is given by

$$\tilde{P}(X, Y)Z = \tilde{R}(X, Y)Z - \frac{1}{2}\{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y\}. \tag{5.1}$$

If  $\tilde{P} = 0$ , then the manifold  $M$  is called *projectively flat* with respect to the Schouten-van Kampen connection.

Let  $M$  be projectively flat manifold with respect to the Schouten-van Kampen connection. From (5.1), we have

$$\tilde{R}(X, Y)Z = \frac{1}{2}\{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y\},$$

i.e.

$$\tilde{R}(X, Y, Z, W) = \frac{1}{2}\{\tilde{S}(Y, Z)g(X, W) - \tilde{S}(X, Z)g(Y, W)\}. \tag{5.2}$$

Then using (4.3) and (4.4) in (5.2), we get

$$\begin{aligned} &R(X, Y, Z, W) + \beta^2\{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\} \\ &+ \alpha^2\{g(\phi Y, Z)g(\phi X, W) - g(\phi Y, W)g(\phi X, Z) + g(Y, W)\eta(X)\eta(Z) \\ &- g(X, W)\eta(Y)\eta(Z) - g(Y, Z)\eta(X)\eta(W) + g(X, Z)\eta(Y)\eta(W)\} \\ = &\frac{1}{2}\{[S(Y, Z) + 2\beta^2g(Y, Z) - 2\alpha^2\eta(Y)\eta(Z)]g(X, W) \\ &- [S(X, Z) + 2\beta^2g(X, Z) - 2\alpha^2\eta(X)\eta(Z)]g(Y, W)\}. \end{aligned} \tag{5.3}$$

Taking  $W = \xi$  and using (2.15) in (5.3), we obtain

$$0 = S(Y, Z)\eta(X) + 2\beta^2g(Y, Z)\eta(X) - 2\alpha^2\eta(Y)\eta(Z)\eta(X) - S(X, Z)\eta(Y) - 2\beta^2g(X, Z)\eta(Y) + 2\alpha^2\eta(Y)\eta(Z)\eta(X),$$

i.e.

$$0 = \{S(Y, Z)\eta(X) - S(X, Z)\eta(Y) + 2\beta^2g(Y, Z)\eta(X) - 2\beta^2g(X, Z)\eta(Y)\}. \tag{5.4}$$

Again taking  $X = \xi$  in (5.4), we have

$$S(Y, Z) = S(\xi, Z)\eta(Y) - 2\beta^2g(Y, Z) + 2\beta^2\eta(Y)\eta(Z). \tag{5.5}$$

Using (2.14) in (5.5), we obtain

$$S(Y, Z) = -2\beta^2g(Y, Z) + 2\alpha^2\eta(Y)\eta(Z). \tag{5.6}$$

Now using (5.6) in (4.4), we get

$$\tilde{S}(Y, Z) = 0.$$

Thus the manifold  $M$  is the Ricci-flat with respect to the Schouten-van Kampen connection. From (5.2), we have

$$\tilde{R} = 0.$$

Now we can say the manifold  $M$  is flat with respect to the Schouten-van Kampen connection.

Conversely, if  $M$  is flat manifold with respect to the Schouten-van Kampen connection then  $M$  is the Ricci-flat with respect to the Schouten-van Kampen connection. From (5.1),  $M$  is projectively flat with respect to the Schouten-van Kampen connection.

Thus we have the following:

**Theorem 5.1.** *Let  $M$  be a 3-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection. Then the following statements are equivalent: i)  $M$  is projectively flat with respect to the Schouten-van Kampen connection, ii)  $M$  is the Ricci flat with respect to the Schouten-van Kampen connection, iii)  $M$  is flat with respect to the Schouten-van Kampen connection.*

In a 3-dimensional trans-Sasakian manifold the *conharmonic curvature tensor* with respect to the Schouten-van Kampen connection is given by

$$\tilde{K}(X, Y)Z = \tilde{R}(X, Y)Z - \{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y + g(Y, Z)\tilde{Q}X - g(X, Z)\tilde{Q}Y\}. \tag{5.7}$$

If  $\tilde{K} = 0$ , then the manifold  $M$  is called *conharmonically flat* manifold with respect to the Schouten-van Kampen connection. Then we have

$$\tilde{R}(X, Y)Z = \{\tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y + g(Y, Z)\tilde{Q}X - g(X, Z)\tilde{Q}Y\}. \tag{5.8}$$

Let  $M$  be conharmonically flat trans-Sasakian manifold with respect to the Schouten-van Kampen connection. Then using (4.3), (4.4) and (4.5) in (5.8), we get

$$\begin{aligned}
 & R(X, Y, Z, W) + \beta^2 \{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\} \\
 & + \alpha^2 \{g(\phi Y, Z)g(\phi X, W) - g(\phi Y, W)g(\phi X, Z) + g(Y, W)\eta(X)\eta(Z) \\
 & - g(X, W)\eta(Y)\eta(Z) - g(Y, Z)\eta(X)\eta(W) + g(X, Z)\eta(Y)\eta(W)\} \\
 = & S(Y, Z)g(X, W) - S(X, Z)g(Y, W) \\
 & + S(X, W)g(Y, Z) - S(Y, W)g(X, Z) \\
 & + 4\beta^2 \{g(Y, Z)g(X, W) - g(X, Z)g(Y, W)\} \\
 & - 2\alpha^2 \{g(X, W)\eta(Y)\eta(Z) - g(Y, W)\eta(X)\eta(Z) \\
 & + g(Y, Z)\eta(X)\eta(W) - g(X, Z)\eta(Y)\eta(W)\}.
 \end{aligned} \tag{5.9}$$

Taking  $W = \xi$  in (5.9), we obtain

$$\begin{aligned}
 & R(X, Y, Z, \xi) + (\beta^2 - \alpha^2) \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\} \\
 = & S(Y, Z)\eta(X) - S(X, Z)\eta(Y) + g(Y, Z)S(X, \xi) - g(X, Z)S(Y, \xi) \\
 & + (4\beta^2 - 2\alpha^2) \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\},
 \end{aligned} \tag{5.10}$$

i.e.

$$0 = S(Y, Z)\eta(X) - S(X, Z)\eta(Y) + 2\beta^2 \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\}. \tag{5.11}$$

Again taking  $X = \xi$  and using (2.14) in (5.11), we have

$$S(Y, Z) = -4\beta^2 g(Y, Z) + 2(\alpha^2 + \beta^2)\eta(Y)\eta(Z). \tag{5.12}$$

Now using (5.12) in (4.4), we get

$$\tilde{S}(Y, Z) = 0.$$

Thus the manifold  $M$  is the Ricci-flat with respect to the Schouten-van Kampen connection. From (5.8), we have

$$\tilde{R} = 0.$$

Now we can say the manifold  $M$  is flat with respect to the Schouten-van Kampen connection.

Conversely, if  $M$  is flat manifold with respect to the Schouten-van Kampen connection then  $M$  is the Ricci-flat with respect to the Schouten-van Kampen connection. From (5.7),  $M$  is conharmonically flat with respect to the Schouten-van Kampen connection.

Thus we have the following:

**Theorem 5.2.** *Let  $M$  be a 3-dimensional trans-Sasakian manifold with respect to the Schouten-van Kampen connection. Then the following statements are equivalent: i)  $M$  is conharmonically flat with respect to the Schouten-van Kampen connection, ii)  $M$  is the Ricci flat with respect to the Schouten-van Kampen connection, iii)  $M$  is flat with respect to the Schouten-van Kampen connection.*

## 6. Example

We consider the 3-dimensional manifold  $M = \{(x, y, z) \in \mathbb{R}^3, z \neq 0\}$ , where  $(x, y, z)$  are the standard coordinates in  $\mathbb{R}^3$ . The vector fields

$$e_1 = z \frac{\partial}{\partial x}, \quad e_2 = z \frac{\partial}{\partial y}, \quad e_3 = z \frac{\partial}{\partial z}$$

are linearly independent at each point of  $M$ . Let  $g$  be the Riemannian metric defined by

$$\begin{aligned}
 g(e_1, e_3) &= g(e_2, e_3) = g(e_1, e_2) = 0, \\
 g(e_1, e_1) &= g(e_2, e_2) = g(e_3, e_3) = 1.
 \end{aligned}$$

Let  $\eta$  be the 1-form defined by  $\eta(Z) = g(Z, e_3)$  for any  $Z \in \chi(M)$ . Let  $\phi$  be the (1, 1) tensor field defined by  $\phi(e_1) = -e_2$ ,  $\phi(e_2) = e_1$ ,  $\phi(e_3) = 0$ . Then using linearity of  $\phi$  and  $g$  we have

$$\eta(e_3) = 1, \quad \phi^2 Z = -Z + \eta(Z)e_3,$$

$$g(\phi Z, \phi W) = g(Z, W) - \eta(Z)\eta(W),$$

for any  $Z, W \in \chi(M)$ . Thus for  $e_3 = \xi$ ,  $(\phi, \xi, \eta, g)$  defines an almost contact metric structure on  $M$ . Now, by direct computations we obtain

$$[e_1, e_2] = 0, \quad [e_2, e_3] = -e_2, \quad [e_1, e_3] = -e_1.$$

The Riemannian connection  $\nabla$  of the metric tensor  $g$  is given by the Koszul's formula which is

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]). \tag{6.1}$$

Using (6.1), we have

$$\begin{aligned} 2g(\nabla_{e_1}e_3, e_1) &= 2g(-e_1, e_1), \\ 2g(\nabla_{e_1}e_3, e_2) &= 0 = 2g(-e_1, e_2), \\ 2g(\nabla_{e_1}e_3, e_3) &= 0 = 2g(-e_1, e_3). \end{aligned}$$

Hence  $\nabla_{e_1}e_3 = -e_1$ . Similarly,  $\nabla_{e_2}e_3 = -e_2$  and  $\nabla_{e_3}e_3 = 0$ . (6.1) further yields

$$\begin{aligned} \nabla_{e_1}e_2 &= 0, & \nabla_{e_1}e_1 &= e_3, \\ \nabla_{e_2}e_2 &= e_3, & \nabla_{e_2}e_1 &= 0, \\ \nabla_{e_3}e_2 &= 0, & \nabla_{e_3}e_1 &= 0. \end{aligned} \quad (6.2)$$

We see that

$$\begin{aligned} (\nabla_{e_1}\phi)e_1 &= \nabla_{e_1}\phi e_1 - \phi\nabla_{e_1}e_1 = -\nabla_{e_1}e_2 - \phi e_3 = -\nabla_{e_1}e_2 = 0 \\ &= 0(g(e_1, e_1)e_3 - \eta(e_1)e_1) - 1(g(\phi e_1, e_1)e_3 - \eta(e_1)\phi e_1). \end{aligned} \quad (6.3)$$

$$\begin{aligned} (\nabla_{e_1}\phi)e_2 &= \nabla_{e_1}\phi e_2 - \phi\nabla_{e_1}e_2 = -\nabla_{e_1}e_1 - 0 = e_3 \\ &= 0(g(e_1, e_2)e_3 - \eta(e_2)e_1) - 1(g(\phi e_1, e_2)e_3 - \eta(e_2)\phi e_1). \end{aligned} \quad (6.4)$$

$$\begin{aligned} (\nabla_{e_1}\phi)e_3 &= \nabla_{e_1}\phi e_3 - \phi\nabla_{e_1}e_3 = 0 + \phi e_1 = -e_2 \\ &= 0(g(e_1, e_3)e_3 - \eta(e_3)e_1) - 1(g(\phi e_1, e_3)e_3 - \eta(e_3)\phi e_1). \end{aligned} \quad (6.5)$$

By (6.3), (6.4) and (6.5) we see that the manifold satisfies (2.5) for  $X = e_1$ ,  $\alpha = 0$ ,  $\beta = -1$ , and  $e_3 = \xi$ . Similarly, it can be shown that for  $X = e_2$  and  $X = e_3$  the manifold also satisfies (2.5) for  $\alpha = 0$ ,  $\beta = -1$ , and  $e_3 = \xi$ . Hence the manifold is a trans-Sasakian manifold of type  $(0, -1)$ . Using (6.2), we get

$$\begin{aligned} R(e_1, e_2)e_1 &= e_2, & R(e_1, e_2)e_2 &= -e_1, & R(e_1, e_2)e_3 &= 0, \\ R(e_1, e_3)e_1 &= e_3, & R(e_1, e_3)e_2 &= 0, & R(e_1, e_3)e_3 &= -e_1, \\ R(e_2, e_3)e_1 &= 0, & R(e_2, e_3)e_2 &= e_3, & R(e_2, e_3)e_3 &= -e_2. \end{aligned} \quad (6.6)$$

Now we consider the Schouten-van Kampen connection to this example. Using (4.1) and (6.2), we calculate

$$\begin{aligned} \tilde{\nabla}_{e_1}e_1 &= (\beta + 1)e_3, & \tilde{\nabla}_{e_1}e_2 &= \alpha e_3, & \tilde{\nabla}_{e_1}e_3 &= (\beta + 1)e_1 - \alpha e_2, \\ \tilde{\nabla}_{e_2}e_1 &= -\alpha e_3, & \tilde{\nabla}_{e_2}e_2 &= (\beta + 1)e_3, & \tilde{\nabla}_{e_2}e_3 &= \alpha e_1 - (\beta + 1)e_2, \\ \tilde{\nabla}_{e_3}e_1 &= 0, & \tilde{\nabla}_{e_3}e_2 &= 0, & \tilde{\nabla}_{e_3}e_3 &= 0. \end{aligned} \quad (6.7)$$

Thus using (4.2) and (6.6), we get

$$\begin{aligned} \tilde{R}(e_1, e_2)e_1 &= (1 - \alpha^2 - \beta^2)e_2, & \tilde{R}(e_1, e_2)e_2 &= (-1 + \alpha^2 + \beta^2)e_1, \\ \tilde{R}(e_1, e_2)e_3 &= 0, & \tilde{R}(e_1, e_3)e_1 &= (1 - \alpha^2 - \beta^2)e_3, \\ \tilde{R}(e_1, e_3)e_2 &= 0, & \tilde{R}(e_1, e_3)e_3 &= (-1 - \alpha^2 + \beta^2)e_1, \\ \tilde{R}(e_2, e_3)e_1 &= 0, & \tilde{R}(e_2, e_3)e_2 &= (1 - \alpha^2 - \beta^2)e_3, \\ \tilde{R}(e_2, e_3)e_3 &= (-1 - \alpha^2 + \beta^2)e_2. \end{aligned} \quad (6.8)$$

From (6.7), we can see that  $\tilde{\nabla}_{e_i}e_j = 0$  ( $1 \leq i, j \leq 3$ ) for  $\xi = e_3$  and  $\alpha = 0$ ,  $\beta = \mp 1$ . Hence  $M$  is a 3-dimensional trans-Sasakian manifold of type  $(0, -1)$  with respect to the Schouten-van Kampen connection. Also using (6.8), it can be seen that  $\tilde{R} = 0$ . Thus the manifold  $M$  is flat manifold with respect to the Schouten-van Kampen connection. Since a flat manifold is the Ricci-flat manifold with respect to the Schouten-van Kampen connection, the manifold  $M$  is both projectively flat and conharmonically flat 3-dimensional  $\beta$ -Kenmotsu manifold with respect to the Schouten-van Kampen connection. So, from Theorem 5.1 and Theorem 5.2, the manifold  $M$  is an  $\eta$ -Einstein manifold with respect to the Levi-Civita connection.

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