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Experimental Optimization of Drilling Parameters in Tooling for Euro 7 Nozzle Production

Hakan Küçüktürk^{1*}, Gökhan Küçüktürk², Şükran Katmer³, Çağlar Yavaş⁴, Ulvi Şeker⁵

0000-0001-8200-6841, 0000-0002-2978-8968, 0000-0002-3641-2328, 0000-0002-2242-8425, 0000-0001-6455-6858

¹ Gazi University, Graduate School of Natural and Applied Sciences, Department of Manufacturing Engineering, 06500 Ankara/Turkey

² Gazi University, Faculty of Engineering, Department of Mechanical Engineering,06500 Ankara, Turkey

³ Gazi University, Graduate School of Natural and Applied Sciences, Mechanical Education, Teknikokullar 06500 Ankara/Turkey

⁴ Karcan Cutting Tools Industry and Trade Inc. 26110 Eskişehir/ Turkey

⁵ Gazi University, Faculty of Technology, Department of Manufacturing Engineering, 06500 Ankara/Turkey

Abstract

Within the scope of Euro 7 emission norms, new types of injectors and engine parts are produced in order to reduce fuel consumption to minimum levels in diesel engine vehicles and accordingly to reduce emission rates. The complex geometry, high precision and high strength required by the nozzle design that will meet the requirements of the aforementioned norms have made the production of the required nozzles on existing production platforms difficult and the manufacturers have faced serious problems. Manufacturing companies needed the development of tooling systems suitable for the existing production platform rather than investing in the high-cost machine park. In this study, it is aimed to increase the tool life by choosing the most appropriate machining parameters for the surface quality obtained in the production of a single nozzle, which is designed and manufactured using six different tools, which will enable the use of existing machining platforms in the production of Euro 7 nozzles. The average surface roughness value on the nozzle surfaces was determined as $Ra = 0.34 \mu m$ and it was observed that the desired surface quality was achieved. Performance tests have shown that the design and production activities are successful and that the developed tooling system can be used for the production of Euro 7 Nozzle from existing production platforms.

Keywords: Nozzle manufacturing, Drilling, Tooling, Force analysis

1. Introduction

It is known that new type injection nozzles are planned to be used in new-generation diesel engines. Although it is designed by giant companies in the sector, there are many problems in the prototype production of the nozzle. In order to reduce carbon emission rates in diesel engines, new types of injectors and diesel engine parts are developed by minimizing fuel consumption. In Euro 7 nozzles, it is necessary to produce 4 times higher surface quality than the previous Euro 6 type nozzles, more radial passages in the nozzle inner area for easier flow of fuel, and all these dimensions should also be produced with 4 times narrower tolerance and desired surface roughness values. Thus, the compression ratio, that is the pressure in the injectors and nozzles, can reach high levels. Thus, the compression ratio, that is the pressure in the injectors and nozzles, can reach high levels. High-strength materials that can serve in these conditions are needed. There is an increasing tendency to use Cr and Ni alloyed materials in recently developed products. Although this trend improves the high-pressure resistance of the parts and the friction-wear behavior under high pressure, it makes the machining of the part in the required high precision forms extremely difficult. Especially, it is expected that the production will be done economically with the optimum tool number and desired tolerances with conventional machines. Drilling is one of the main conventional machining methods used for many manufacturing areas [1]. Therefore, the development of tool design in this field and the theoretical and experimental study of machining parameters have an important place in the literature. In particular, theoretical studies on drilling have focused on the optimization of parameters by developing mathematical models for parameters that affect tool geometry and cutting forces, such as tool material, notch angle, drill diameter and coating [2-6]. Sambhav

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* Corresponding author

hakan.kucukturk@gazi.edu.tr

Address: Graduate School of Natural and

Applied Sciences, Department of Manu-

facturing Engineering, 06500 Ankara/

Hakan Küçüktürk

Tel:+ 903122028600

Turkey



et al. presented a methodology for modeling the geometry of helical drills and drilling forces with the general tip geometry [7]. As a result of the experimental studies made after the changes made in the drill bit design especially for drilling highstrength steels, a decrease in cutting forces and moment has been observed and it is stated that tool breakage is reduced [8]. Gökçe et al. examined drill designs widely used in the industry and modeled a unique drill geometry based on parametric and mathematical equations for its manufacture [9]. Bahçe et al. [10] investigated the changes of burr heights in the hole exit area during the drilling of Al-5005 material. In the experimental studies, it was observed that different values of burr height were obtained while the drill bit geometries increase in the speed and feed rate. Yağmur et al. [11] drillability of AISI 1050 materials, widely used in industrial applications, examined the temperature alteration during metal removal based on hole type, cutting parameters, and cutting tool type. Uzun et al. [12] studied the drillability of Ti-6Al-4V alloys. They predicted that tool wear was the main reason for the change in cutting forces and hole quality as cutting speed and cutting time changed. Lin [13], stated that variable feed rate and variable rotational speed machining is an important method to improve cutting performance in hard and difficult to machine materials. Balaji et al. [14], studied the effect of cutting parameters such as cutting speed, feed rate and helix angle on tool life. The effects of cutting parameters were analyzed by evaluating the amplitude of drill bit vibration and surface roughness.

Austenitic stainless steels are widely used as engineering materials due their high strength, high corrosion and oxidation resistance properties and high chromium content as well as being used in the production of daily items. Although the quality of the holes in the drilling process depends on the machining parameters and the cutting tool and workpiece configurations, it is known that physical and metallurgical properties are important in the selection of machining parameters of AISI 304 austenitic stainless steels. Günay et al. studied on drilling of AISI 430 ferritic stainless steel in respect of the burr height, thrust force, and surface roughness by using Taguchi method combined with Grey Relational Grade (GRG). Furthermore, the mathematical models were developed for the machining outputs with response surface methodology [15]. Korkmaz et al. investigated the drilling process of AISI 420 martensitic stainless steel material in terms of feed force, moment, and tool temperature with the finite element method. And it was emphasized that the feed force and moment values increased as the feed rate increased, and these values tended to decrease with the increase in cutting speed [16].

Chatterjee et al. investigated the effect of drilling parameters, spindle rotation speed, feed rate and drill bit diameter on burr height and the hole quality in drilling AISI 304 austenitic stainless steels using a parametric evaluation [17]. It is emphasized in some studies that multi-layer coatings applied on cutting tools have an effect on cutting forces and hole diameter in the drilling of AISI 304 austenitic stainless steel [18, 19]. Nanocomposite coated and uncoated tungsten carbide tools were examined in terms of surface roughness and tool wear when drilling AISI-

304L austenitic stainless steel workpieces, and it was stated that less damage occurred in coated tools [20]. During dry drilling operations, it is known that coated tools are more successful in reducing tool wear and improving the surface roughness of the workpiece, depending on parameter changes such as cutting speed and feed rate [21, 22]. Given the effect of cutting parameters on surface roughness and chip formation during drilling of Inconel718 superalloy with coated and uncoated carbide drills, the best results in terms of surface roughness were obtained with holes drilled with an uncoated tool [23].

As a result of the literature review, the researchers generally conducted studies on the drilling of austenitic stainless steels with drilling bits with different material structures and coated with different materials. It has been determined that in particular to AISI 304 austenitic stainless steel, studies have been carried out to prevent tool wear encountered during machining, to increase hole quality, to determine optimum machining parameters and to compare them with existing tools. These studies focused on the values that affect the hole quality such as surface roughness, burr height, and conic hole formation. They also focused on machining parameters such as cutting speed, feed rate, rotation speed, and tool properties such as the drill tip angle and the tool material and type of coatings. Although there are studies in the literature on drilling holes in AISI 304 austenitic stainless steel, there is a deficiency for studies to determine the production process of Euro 7 nozzle holes. Within this scope, there is a need for studies to determine the issues to be considered in the design of the tool geometry and to develop different tool geometries. Surface roughness is an indicator of surface quality, which is the main requirement of the automotive parts that need precise production such as nozzles. Since the compression ratio, so the service pressure, in injectors and nozzles will be at high levels, the surface roughness will be one of the most important parameters that directly affect the friction coefficient and the flow quality. Proper tool design and parameter selection become an important issue in the production of Euro 7 type nozzles in order to obtain proper nozzle surface roughness, which is an important factor in reducing emission values. In this study, it is aimed to increase the tool life by choosing the most suitable machining parameters for the surface quality of many nozzles produced using six different tools.

2. Experimental Study:

Pilot tests of prototype tools were carried out with a vertical machining center (ARION IMM-1100 Vertical Machining Center) with a maximum spindle speed of 8000 rpm and a drive motor of 11/7.5 kW (Fig. 1). Chemical properties for AISI 304 austenitic stainless steel material are given in Table 1.

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Element	Composition (% wt.).
С	0.059
Si	0.581
Mn	1.080
Р	0.029
S	0.001
Cr	18.060
Ni	8.150
Мо	0.064
Cu	0.150
Fe	Balance

Table 1. Chemical composition of AISI 304 austenitic stainless steel

Experimental studies were prepared by cutting 80x80x40 mm blocks in order to perform serial processing. On each block, it is aimed to drill numbers of 25 and 50 Euro7 diesel injector nozzle geometries serially with 6 tools, so as considering not to be affected by the thermal changes that will occur during machining. After the tool designs and analyzes of the drilling bits used in the experiments were made, they were produced in Karcan Cutting Tools Industry and Trade Inc. (Fig. 2). Surface control has achieved by milling the hole entry surfaces of the target material and controlling the radial runout of the tools. All experiments were carried out in wet conditions, similar to the applications in the field, and boron oil emulsion with 6% concentration was used as cutting fluid. The tool runout measurements and bench setup processes of the drill bits were completed and machining experiments were carried out within the framework of the usage order of the tools with the generated CAM program (Fig. 3).



Fig. 1. CNC Vertical Machining Center used for experimental studies



Fig. 2. Tooling system developed for Euro7 Nozzle and tools [24]



Fig. 3. (a) tool run-out control attached to the spindle; and (b) workpiece surface cleaning

3. Evaluation of Drilling Performance

3.1. The determination of appropriate drilling parameters

Four types of parameter groups have been determined for the experimental optimization of drilling parameters. The parameters and success conditions determined for six tools and the machining parameters determined for life determination are presented in Table 2. It was observed whether the nozzle structure for 49 nozzle holes was successfully drilled by using the planned parameter sets on the target material (Fig. 4).





Fig. 4. (a) Hole design and (b) final nozzles on block work pieces

It was carried out by measuring the hole inlet and bottom diameters on the test samples and these diameters were verified. In order to verify the nozzle geometries and surface quality obtained in the drilling tests, the samples were cut using a wire electro erosion machine based on the hole axis (Fig. 5). Average surface roughness measurements were made on the nozzle surfaces after cutting and R_a values were determined.

When the revolution speed is increased, the amount of flank wear on the tools increased excessively and this caused the tools to have a shorter life. Fig. 6 shows the change in tool according to the specified parameter sets. The increase in speed caused an increase in surface roughness values for 49 holes on the target part.



Fig. 5. The view of nozzles after cutting with wire electro erosion

In order to achieve tool life targets, FW results were obtained much lower than the accepted (<0.06 mm) values (Fig. 7). In the study performed with four different parameter sets in the drilling process with Tool 1, the best flank wear value of 0.003 mm was obtained with 1500 rpm and 0.02 mm/tooth. The flank wear values were found to be 0.015 mm, 0.027 mm and 0.042 mm, respectively, when the feed rate was kept constant and the revolution speeds were 3000 rpm, 4000 rpm and 6000 rpm.

It is aimed to find the optimum values as a result of processing in two steps with Tool 2. Successful holes were drilled with 0.02 mm/tooth and 0.015 mm/tooth parameters at 2800 rpm, and these values were accepted as optimum values since the best flank wear result obtained in terms of flank wear was 0.009 mm. Since the surface roughness values are too high in other machining parameters, they are not shown in the chart.

Tool flank wear was measured as 0.004 mm as a result of machining parameter values for Tool 3, which was performed in two operations, at 2800 rpm and 0.01 mm/tooth in the first operation, and 0.02 mm/tooth at 2800 rpm in the second operation. Similarly, other parameter values were not accepted. As a result of a single operation, machining with Tool 4 was carried out in four different machining parameters. Accepted flank wear values of 0.005 mm, 0.027 mm and 0.060 mm are respectively revolution speed and feed rate 6000 rpm for 0.05 mm/tooth, measured for 6000 rpm for 0.0625 mm/tooth and 7000 rpm for 0.0625 mm/tooth. Because the flank wear values were too high, 8000 rpm for 0.0625 mm/tooth was not taken into account.



Fig. 6. The view Change in tool wear due to cutting speed after fifty holes

In drilling trials with Tool 5, the flank wear results of four different rotational speeds increasing with a single 0.015 mm/tooth feed value were measured as 0.004 mm, 0.01 mm, 0.018 mm and 0.018 mm, respectively. The best parameter value was obtained as a result of 4500 rpm and 0.015 mm/tooth parameter. Machining was carried out with tool 6 at 0.01 mm/tooth feed rate and four different rotational speeds. Since the flank wear results for 6000 rpm and 8000 rpm are relatively high, only the 0.006 mm and 0.013 mm flank wear values obtained at 3000 rpm and 4500 rpm are taken into account. As a result, it was decided that the best parameter set is suitable as 0.001 mm/tooth feed for 3000 rpm.

The nozzle inner average surface roughness values obtained with the most suitable parameter sets are presented in Fig. 7. As a result of the studies carried out with Parameter Set 1 (PS1), the best tool flank wear amount was obtained, and the lowest internal surface roughness values were also obtained with this set. Although the surface roughness after machining with Parameter Set 2 (PS2) and Parameter Set 3 (PS3) were at acceptable values, studies were continued with the parameters in which the best



tool flank wear was obtained (Table 3).



Fig. 7. Change in surface roughness in specified parameter sets

	Speed [rpm] (1st operation)	Feed rate [mm/ tooth]	Result	Operation notes	Speed [rpm] (2nd operation)	Feed rate [mm/ tooth]	Result	Operation notes	
TOOL 1 (single operation)	1500	0.02	successful		-	-	-		
TOOL 1 (two operation)	3000 4000 6000	0.02	successful	-	1500 2000 3000	0.02	successful	-	
					-	=	-		
TOOL	2800		£-1		2800	0.015	successful		
TOOL 2	2800	0.02	successiui	3 mm	2800	0.03	unsuccessful	3 mm	
(two	4000	0.02		pecking	4000			pecking	
operation)	6000		unsuccessful	1 0	6000				
	2800				2800	0.01	successful		
TOOL 3	2800	0.01		successful	0.7 mm	2800			0.4 mm
(two	4000			pecking	4000	0.02	unsuccessful	final pass	
operation)	6000		unsuccessful		6000			1	
	6000	0.05							
TOOL 4	6000	0100	successful						
(two	7000	0.0625		-	-	-	-	-	
operation)	8000		unsuccessful	ul					
TOOL 5 (two operation)	4500 6000 7000 8000	0.015	successful	0.5 mm pecking	-	-	-		
TOOL 6	3000 4500	0.01	successful	0.1 s stand					
operation)	6000 8000	0.01	unsuccessful	bottom	_	-	-	-	



Table 3. Recommended drilling parame	eters for tool life estimation
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Tool	Speed [rpm]	Feed rate [mm/tooth]	Operation notes		
1st tool	1500	0.020			
2nd tool	2800 0.020		3 mm pecking		
2110 1001	2800	0.015	5 min peeking		
3rd tool	2800	0.010	0.7 mm pecking		
	2800	0.010	0.4 mm final pass		
4th tool	6000	0.050			
5th tool	4500	0.015	0.5 mm pecking		
6th tool	3000	0.010	0.1 s stand at the bottom		

3.2. Performance tests

AISI 304 austenitic stainless steel material with the same chemical composition as the target material has been used for the pilot performance tests of the prototype cutting tools. In order to perform serial processing in performance tests and to be suitable for the dynamometer used in force/moment measurements, test samples were prepared by cutting 80x80x40 mm block sizes. It aimed that 25 Euro7 diesel injector nozzle geometry were drilled serially with 6 different tools in each block at a distance that would not be affected by the thermal changes that occur during machining. As can be seen in Fig. 8, numbers of 25 nozzles have successfully drilled.

Kistler type 9272 dynamometer and Kistler type 5070 amplifier operating on the basis of quartz crystal, capable of measuring three shear force components (F_x , F_y , F_z) and moment (M_z) simultaneously, were used in the experimental determination of shear forces and moments.

Experiments were carried out in order to determine the performance indicators of each tool with the machining parameters accepted as suitable, with tool flank wear and nozzle surface roughness values. During the experiments, shear forces (Fx, Fy, and Fz) and moment (Mz) values were measured and recorded for each



Fig. 8. Holes drilled with performance tests

operation and each nozzle hole. Average force and moment values were measured from the graphs evaluated with Kistler Dynaware software. The performance tests of the tools were repeated, and numbers of 25 Euro7 nozzle geometries were obtained by working successively on each sample. Apart from pecking recommended for tools with high chip load, drilling operations were found suitable to be completed in two stages as in field applications. All drilling tests after the Design/Production validation activities have carried out using the same device and hardware as in the first pilot trials. The only difference is that the dynamometer is attached to the bench vise instead of directly to the benchtop. Thus, the preloads in the Fz direction are reduced.

For tool 1, it was observed that the values of Fz=239.80 N and Mz=263 N.cm increased due to the increased number of holes as a result of serial processing of the nozzles in a single operation (Fig. 9).

It has been observed that the Fz and Mz values for tool 2, which was processed in two different stages, increased with the number of holes. These values were measured as maximum Fz = 33.6 N and Mz = 248 N.cm in the first stage, and as Fz = 55.42 N and Mz = 234.6 Ncm in the second stage. Considering the nozzle and tool geometry the reason for the significant decrease in the thrust force while compared to the machining values of the first tool is understood (Fig. 10).

The highest values were measured as Fz = 36.65 N and Mz=121 N.cm in the first step, and as Fz=34.78 N and Mz=265 N.cm in the second step in the drillings where tool 3 was used. As a result of all drillings, the average drilling force values were measured as 34.25 N and 103.84 N.cm in the first stage and 30.69 N and 258.80 N.cm in the second stage. Some fluctuations in forces have been attributed to the material's nickel content which is resulting in a tendency for the chip to become entangled in the tool and to re-cut (Fig. 11).





Fig. 9. Variation in torque and thrust forces for tool 1 depending on the number of holes

As a result of machining using Tool 4, a change as in Fig. 12 was obtained. The highest Fz and Mz values, obtained as a result of machining all holes in a single operation, were 68.42 N and 121 N.cm, respectively, while the average values were 68.36 N and 118 N.cm. It was interpreted that the increase in Fz force compared to the previous tooling increased with the diameter expansion in the nozzle, and similarly, the decrease in Mz moment was due to the decrease in the forces in the Fx and Fy directions resulting from the diameter expansion.

In the drillings where tool 5 was used, the highest values were measured as Fz = 39.46 N and Mz=44 N.cm in the first stage, and as Fz=34.58 N and Mz=23 N.cm in the second stage. As a result of all drillings, the average hole drilling values were measured as 34.04 N and 36.33 Ncm in the first stage and 33.13 N and 19.67 N.cm in the second stage (Fig. 13).

Nozzle geometry is finalized after machining with the last tool in a single operation. The highest Fz and Mz values were determined as 40.76N and 272 N.cm, respectively, while the average values were determined as 34.66 N and 209.13 N.cm.

Depending on the increase in the number of holes, an increasing trend in the Fz force, in general, is observed when the graphics are examined. However, this increasing trend did not reach a level that would negatively affect tool performance (Fig. 14).



Fig. 10. (a) Change in torque and thrust forces depending on the number of holes in the 1st stage for Tool 2 (b) Change in torque and thrust forces depending on the number of holes in the 2nd stage for Tool 2





Fig. 11. (a) Change in torque and thrust forces depending on the number of holes in the 1st stage for Tool 3 (b) Change in torque and thrust forces depending on the number of holes in the 2nd stage for Tool 3



Fig. 12. Variation in torque and thrust forces for tool 4 depending on the number of holes



Fig. 13. (a) Change in torque and thrust forces depending on the number of holes in the 1st stage for Tool 3 (b) Change in torque and thrust forces depending on the number of holes in the 2nd stage for Tool 5



Fig. 14. Variation in torque and thrust forces for tool 4 depending on the number of holes



This shows that the design and production activities are successful. The most stable data in terms of thrust force (Fz) were observed in the number 4 tool, the reaming tool. This has been attributed to the low depth of cut left to the reaming tools, as the nature of the reaming process. When the moment (Mz) graphs were evaluated, it has seen that the general trend was parallel to the trend in the Fz force. Since the torsional moment values have affected by the Fx and Fy forces depending on the chip load of each tool, they spread over a wider range and tended to increase slightly in parallel with the increase in the number of holes.

4. Tool Life

After parameter determination and performance tests, a total of 295 nozzles have machined with each tool one after the other. With the help of the curves in the graph given in Fig. 15, it was understood that the flank wear values were at reasonable levels (≤ 0.06 mm) and the tool life values determined for the tools can be reached.

In addition, the measured surface roughness values of the nozzle inner surface made measurable by the wire electro-erosion method are shown in Fig. 16. In the study, it has seen that the roughness values of the nozzle surface obtained after drilling 295 holes were at an acceptable level.



Fig. 15. Change in tool flank wear depending on the number of holes in tool life tests



Fig. 16. Change in nozzle surface roughness depending on the number of holes in tool life tests

4.1. Modelling

A linear model was applied for surface roughness and tool flank wear values by the graphical simulation method. A mathematical model was generated using the graphical simulation method for the tool flank wear values shown in Table 4. Linear graphs have drawn using the linear simulation method, using the flank wear values that change depending on the number of holes in each tool, as shown in Fig. 17.

Number of Holes	Tool 1	Tool 2	Tool 3	Tool 4	Tool 5	Tool 6
50	0.003	0.009	0.004	0.005	0.004	0.006
99	0.008	0.009	0.016	0.007	0.006	0.009
148	0.013	0.013	0.031	0.009	0.008	0.010
197	0.024	0.032	0.035	0.018	0.010	0.017
246	0.034	0.035	0.047	0.026	0.015	0.021
295	0.043	0.043	0.051	0.031	0.022	0.028

Table 4. Tool flank wear amounts according to the number of holes







Fig. 17. Experimentally and theoretically the change in tool wear depending on the number of holes of the tools

Table 5. R^2 values calculated for each tool			
	\mathbb{R}^2		
Tool 1	0.978		
Tool 2	0.913		
Tool 3	0.969		
Tool 4	0.946		
Tool 5	0.916		
Tool 6	0.953		

When these values were examined, it has seen that the model is matching with over 90% accuracy for each cutting tool.

Using these data, the coefficients of determination (R^2) values given in Table 5 have calculated. Generated mathematical models for each tool flank wear are presented below:

Wear amount of Tool 1 = -0.00824+0.000168513 x Number of Holes

Wear amount of Tool 2. = -0.00336+0.000155685 x Number of Holes

Wear amount of Tool 3. = -0.00273+0.000193586 x Number of Holes

Wear amount of Tool 4. = -0.00371+0.000114286 x Number of Holes

Wear amount of Tool 5. = -0.00114+0.0000693878 x Number of Holes

Wear amount of Tool 6. = 0.000222546+0.0000892128 x Number of Holes

Another output of the experimental studies was the surface roughness. The graph of the model showing the average surface roughness values depending on the number of holes is shown in Fig. 18. It has been observed that the determination coefficient R2 value calculated by following the steps in the same direction as the models generated for tool flank wear was very close to 1. Generated mathematical mode emerged as:

Ra = 0.33256+0.00090584 x Number of Holes

In addition, studies continue on models based on the obtained parameter sets in order to determine the most appropriate parameter values.





Fig. 18. Change in surface roughness depending on the number of holes

5. Conclusions

As a result, experimental studies were performed to determine the issues that need to be evaluated in the tool design to be used in drilling holes during the production of Euro7 nozzles and to develop different tool geometries. In serial nozzle hole drilling processes using cutting tools with six different geometries, a large number of drilling operations have carried out depending on the surface roughness, various cutting speeds and feed rates. The main contribution of the study is to find optimum drilling conditions suitable for minimum surface roughness and tool flank wear by drilling many holes with the same drills. Modeling and optimization studies have shown that the number of experimental studies can be reduced and provided a systematic and effective methodology. The estimated and measured values from the modeling results have found quite close. This showed that the developed model could be used effectively to predict surface roughness and tool flank wear. A significant saving in time and cost has been achieved by using this model.

In the performance tests, depending on the increase in the number of holes, there was an increase in the Fz force in general, but it was observed that the tool flank wear and the inner surface quality of the nozzle were at acceptable levels. It is understood that the changes in the moment (Mz) occur in a wider range as a result of the forces acting perpendicular to the tool's advance direction and increase depending on the number of holes. The average surface roughness Ra values obtained on the inner surfaces of the nozzles are $0.34 \,\mu$ m, and similarly, the success of the design and production experiment showed that it can be used for Euro7 nozzle production.

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Conflict of Interest Statement

The authors declare that there is no conflict of interest in the study.

CRediT Author Statement

Hakan Küçüktürk: Investigation, Validation, Software, Writing-original draft,

Gökhan Küçüktürk: Visualization, Writing - review & editing,

Şükran Katmer: Visualization, Writing - review & editing, Çağlar Yavaş: Investigation, Validation, Software, Ulvi Şeker: Methodology, Supervision,

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