

On the Generalized of p -Harmonic Maps

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(Communicated by Kazım İlarıslan)

ABSTRACT

In this paper, we extend the definition of p -harmonic and p -biharmonic maps between Riemannian manifolds. We present some new properties for the generalized stable p -harmonic maps.

Keywords: p -harmonic maps, p -biharmonic maps, stable p -harmonic maps.

AMS Subject Classification (2020): Primary: 53C20; 58E20.

1. Introduction

Consider a smooth map $\varphi : (M, g) \rightarrow (N, h)$ between Riemannian manifolds, and let p be a smooth positive function on M such that $p(x) \geq 2$ for all $x \in M$. For any compact domain D of M the $p(\cdot)$ -energy functional of φ is defined by

$$E_{p(\cdot)}(\varphi; D) = \int_D \frac{|d\varphi|^{p(x)}}{p(x)} v_g, \quad (1.1)$$

where $|d\varphi|$ is the Hilbert-Schmidt norm of the differential $d\varphi$ and v^g is the volume element on (M, g) . A map is called $p(\cdot)$ -harmonic if it is a critical point of the $p(\cdot)$ -energy functional over any compact subset D of M . $p(\cdot)$ -harmonic maps is a natural generalization of harmonic map ([1, 5]) and p -harmonic map ([2, 3, 6]). We denote by

$$\tau(\varphi) = \text{trace}_g \nabla d\varphi = \sum_{i=1}^m \{ \nabla_{e_i}^\varphi d\varphi(e_i) - d\varphi(\nabla_{e_i}^M e_i) \}. \quad (1.2)$$

the tension field of φ , where $\{e_i\}_{i=1}^m$ is an orthonormal frame on (M, g) , ∇^M is the Levi-Civita connection of (M, g) , and ∇^φ denote the pull-back connection on $\varphi^{-1}TN$.

In this paper, we investigate some properties for $p(\cdot)$ -harmonic maps between two Riemannian manifolds. In particular, we present the first and the second variation of the $p(\cdot)$ -energy. We also extend the definition of p -biharmonic maps between two Riemannian manifolds ([8]).

2. $p(\cdot)$ -Harmonic Maps

Theorem 2.1 (The first variation of the $p(\cdot)$ -energy). *Let $\varphi : (M, g) \rightarrow (N, h)$ be a smooth map between two Riemannian manifolds, $\{\varphi_t\}_{t \in (-\epsilon, \epsilon)}$ a smooth variation of φ supported in compact domain D of M . Then*

$$\frac{d}{dt} E_{p(\cdot)}(\varphi_t; D) \Big|_{t=0} = - \int_D h(v, \tau_{p(\cdot)}(\varphi)) v_g, \quad (2.1)$$

where $\tau_{p(\cdot)}(\varphi)$ denotes the $p(\cdot)$ -tension field of φ given by

$$\tau_{p(\cdot)}(\varphi) = \text{trace}_g \nabla |d\varphi|^{p(x)-2} d\varphi, \quad (2.2)$$

and $v = \frac{d\varphi_t}{dt} \Big|_{t=0}$ denotes the variation vector field of $\{\varphi_t\}_{t \in (-\epsilon, \epsilon)}$.

Proof. Let $\phi : M \times (-\epsilon, \epsilon) \rightarrow N$ be a smooth map defined by

$$\phi(x, t) = \varphi_t(x), \quad \forall (x, t) \in M \times (-\epsilon, \epsilon).$$

We have $\phi(x, 0) = \varphi(x)$ for all $x \in M$, and the variation vector field associated to the variation $\{\varphi_t\}_{t \in (-\epsilon, \epsilon)}$ is given by

$$v(x) = d_{(x,0)}\phi\left(\frac{\partial}{\partial t}\right)\Big|_{t=0}, \quad \forall x \in M.$$

Let $\{e_i\}_{i=1}^m$ be an orthonormal frame on (M, g) . We compute

$$\begin{aligned} \frac{d}{dt}E_{p(\cdot)}(\varphi_t; D)\Big|_{t=0} &= \frac{d}{dt} \int_D \frac{|d\varphi_t|^{p(x)}}{p(x)} v_g \Big|_{t=0} \\ &= \int_D \frac{1}{p(x)} \frac{\partial}{\partial t} |d\varphi_t|^{p(x)} \Big|_{t=0} v_g \\ &= \int_D \frac{1}{p(x)} \frac{\partial}{\partial t} (|d\varphi_t|^2)^{\frac{p(x)}{2}} \Big|_{t=0} v_g \\ &= \sum_{i=1}^m \int_D \frac{1}{p(x)} \frac{\partial}{\partial t} h(d\varphi_t(e_i), d\varphi_t(e_i))^{\frac{p(x)}{2}} \Big|_{t=0} v_g \\ &= \sum_{i=1}^m \int_D \frac{1}{p(x)} \frac{\partial}{\partial t} h(d\phi(e_i, 0), d\phi(e_i, 0))^{\frac{p(x)}{2}} \Big|_{t=0} v_g \\ &= \sum_{i=1}^m \int_D h(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_i, 0), d\phi(e_i, 0)) (|d\varphi_t|^2)^{\frac{p(x)}{2}-1} \Big|_{t=0} v_g. \end{aligned} \quad (2.3)$$

By using the property

$$\nabla_X^\phi d\phi(Y) = \nabla_Y^\phi d\phi(X) + d\phi([X, Y]),$$

with $X = \frac{\partial}{\partial t}$, $Y = (e_i, 0)$, and $[\frac{\partial}{\partial t}, (e_i, 0)] = 0$, the equation (2.3) becomes

$$\begin{aligned} \frac{d}{dt}E_{p(\cdot)}(\varphi_t; D)\Big|_{t=0} &= \sum_{i=1}^m \int_D h(\nabla_{(e_i,0)}^\phi d\phi(\frac{\partial}{\partial t}), d\phi(e_i, 0)) |d\varphi_t|^{p(x)-2} \Big|_{t=0} v_g \\ &= \sum_{i=1}^m \int_D h(\nabla_{e_i}^\varphi v, |d\varphi|^{p(x)-2} d\varphi(e_i)) v_g \\ &= \sum_{i=1}^m \int_D [e_i h(v, |d\varphi|^{p(x)-2} d\varphi(e_i)) \\ &\quad - h(v, \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} d\varphi(e_i))] v_g. \end{aligned} \quad (2.4)$$

Let $\omega \in \Gamma(T^*M)$ defined by

$$\omega(X) = h(v, |d\varphi|^{p(x)-2} d\varphi(X)), \quad \forall X \in \Gamma(TM)$$

The divergence of ω is given by

$$\operatorname{div}^M \omega = \sum_{i=1}^m [e_i h(v, |d\varphi|^{p(x)-2} d\varphi(e_i)) - h(v, |d\varphi|^{p(x)-2} d\varphi(\nabla_{e_i}^M e_i))]. \quad (2.5)$$

By equations (2.4), (2.5), and the divergence Theorem [1], we get

$$\begin{aligned} \frac{d}{dt}E_{p(\cdot)}(\varphi_t; D)\Big|_{t=0} &= \sum_{i=1}^m \int_D h(v, |d\varphi|^{p(x)-2} d\varphi(\nabla_{e_i}^M e_i) - \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} d\varphi(e_i)) v_g \\ &= - \sum_{i=1}^m \int_D h(v, [\nabla_{e_i} |d\varphi|^{p(x)-2} d\varphi](e_i)) v_g. \end{aligned} \quad (2.6)$$

□

Corollary 2.1. A smooth map $\varphi : (M, g) \rightarrow (N, h)$ between two Riemannian manifolds is $p(\cdot)$ -harmonic if and only if

$$\tau_{p(\cdot)}(\varphi) = |d\varphi|^{p(x)-2} \tau(\varphi) + d\varphi(\text{grad}^M |d\varphi|^{p(x)-2}) = 0.$$

Example 2.1. The restriction of inversion

$$\varphi : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n \setminus \{0\}, \quad x \mapsto \frac{x}{\|x\|^2},$$

to $M = \{x \in \mathbb{R}^n \setminus \{0\}, \|x\|^2 > \sqrt{n}\}$ is $p(\cdot)$ -harmonic map, where the function p is given by

$$p(x) = n + \frac{c}{2 \ln(\|x\|^2) - \ln(n)}, \quad \forall x \in M,$$

for some constant $c \geq 0$. Here, $|d\varphi|(x) = \frac{\sqrt{n}}{\|x\|^2}$ for all $x \in \mathbb{R}^n \setminus \{0\}$.

Example 2.2. Let $F : \mathbb{R} \rightarrow [2, \infty)$ be a smooth function. The map

$$\varphi : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{S}^{n-1}, \quad x \mapsto \frac{x}{\|x\|},$$

is $p(\cdot)$ -harmonic, where $p(x) = F(\|x\|^2)$ for all $x \in \mathbb{R}^n \setminus \{0\}$. The Hilbert-Schmidt norm of $d\varphi$ is given by $|d\varphi|(x) = \frac{\sqrt{n-1}}{\|x\|}$ for all $x \in \mathbb{R}^n \setminus \{0\}$.

Remark 2.1. A smooth harmonic map, i.e., $\tau(\varphi) = 0$, with constant energy density $\frac{|d\varphi|^2}{2}$ is not always $p(\cdot)$ -harmonic. The previous examples prove the following results; There is no equivalence between the $p(\cdot)$ -harmonicity and the harmonicity of a smooth map $\varphi : (M, g) \rightarrow (N, h)$. There are $p(\cdot)$ -harmonic maps which have non-constant Hilbert-Schmidt norm and they are not harmonic.

3. Stable $p(\cdot)$ -Harmonic Maps

Theorem 3.1 (The second variation of the $p(\cdot)$ -energy). Let φ be a smooth $p(\cdot)$ -harmonic map between two Riemannian manifolds (M, g) and (N, h) . Then we have

$$\frac{\partial^2}{\partial t \partial s} E_{p(\cdot)}(\varphi_{t,s}; D) \Big|_{t=s=0} = \int_D h(J_{p(\cdot)}^\varphi(v), w) v_g, \tag{3.1}$$

where $\{\varphi_{t,s}\}_{(t,s) \in (-\epsilon, \epsilon) \times (-\epsilon, \epsilon)}$ is a smooth variation supported in compact domain $D \subset M$ of φ ,

$$v = \frac{\partial \varphi_{t,s}}{\partial t} \Big|_{t=s=0}, \quad w = \frac{\partial \varphi_{t,s}}{\partial s} \Big|_{t=s=0}, \tag{3.2}$$

and $J_{p(\cdot)}^\varphi$ the generalized Jacobi operator of φ given by

$$\begin{aligned} J_{p(\cdot)}^\varphi(v) = & -|d\varphi|^{p(x)-2} \text{trace}_g R^N(v, d\varphi)d\varphi - \text{trace}_g \nabla^\varphi |d\varphi|^{p(x)-2} \nabla^\varphi v \\ & - \text{trace}_g \nabla(p(x) - 2)|d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi. \end{aligned} \tag{3.3}$$

Here \langle , \rangle denote the inner product on $T^*M \otimes \varphi^{-1}TN$.

Proof. Let $\phi : M \times (-\epsilon, \epsilon) \times (-\epsilon, \epsilon) \rightarrow N$ be a smooth map defined by $\phi(x, t, s) = \varphi_{t,s}(x)$. We have $\phi(x, 0, 0) = \varphi(x)$, and the variation vectors fields associated to the variation $\{\varphi_{t,s}\}_{(t,s) \in (-\epsilon, \epsilon) \times (-\epsilon, \epsilon)}$ are given by

$$v(x) = d_{(x,0,0)}\phi\left(\frac{\partial}{\partial t}\right), \quad w(x) = d_{(x,0,0)}\phi\left(\frac{\partial}{\partial s}\right), \quad \forall x \in M. \tag{3.4}$$

Let $\{e_i\}_{i=1}^m$ be an orthonormal frame with respect to g on M such that $\nabla_{e_i}^M e_j = 0$ at $x \in M$ for all $i, j = 1, \dots, m$. We compute

$$\begin{aligned} \frac{\partial^2}{\partial t \partial s} E_{p(\cdot)}(\varphi_{t,s}; D) \Big|_{t=s=0} &= \frac{\partial^2}{\partial t \partial s} \int_D \frac{|d\varphi_{t,s}|^{p(x)}}{p(x)} v_g \Big|_{t=s=0} \\ &= \int_D \frac{1}{p(x)} \frac{\partial^2}{\partial t \partial s} |d\varphi_{t,s}|^{p(x)} \Big|_{t=s=0} v_g. \end{aligned} \tag{3.5}$$

First, note that

$$\begin{aligned} \frac{1}{p(x)} \frac{\partial^2}{\partial t \partial s} |d\varphi_{t,s}|^{p(x)} &= \frac{1}{p(x)} \frac{\partial}{\partial t} \left(\frac{\partial}{\partial s} (|d\varphi_{t,s}|^2)^{\frac{p(x)}{2}} \right) \\ &= \frac{1}{2} \frac{\partial}{\partial t} \left((|d\varphi_{t,s}|^2)^{\frac{p(x)}{2}-1} \frac{\partial}{\partial s} |d\varphi_{t,s}|^2 \right) \\ &= \sum_{i=1}^m \frac{\partial}{\partial t} \left((|d\varphi_{t,s}|^2)^{\frac{p(x)}{2}-1} h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), d\phi(e_i, 0, 0)) \right). \end{aligned}$$

Thus

$$\begin{aligned} \frac{1}{p(x)} \frac{\partial^2}{\partial t \partial s} |d\varphi_{t,s}|^{p(x)} &= \sum_{i=1}^m \frac{\partial}{\partial t} (|d\varphi_{t,s}|^2)^{\frac{p(x)}{2}-1} h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), d\phi(e_i, 0, 0)) \\ &\quad + \sum_{i=1}^m |d\varphi_{t,s}|^{p(x)-2} h(\nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), d\phi(e_i, 0, 0)) \\ &\quad + \sum_{i=1}^m |d\varphi_{t,s}|^{p(x)-2} h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), \nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_i, 0, 0)). \end{aligned}$$

So that

$$\begin{aligned} \frac{1}{p(x)} \frac{\partial^2}{\partial t \partial s} |d\varphi_{t,s}|^{p(x)} &= \sum_{i,j=1}^m (p(x) - 2) |d\varphi_{t,s}|^{p(x)-4} h(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_j, 0, 0), d\phi(e_j, 0, 0)) \\ &\quad h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), d\phi(e_i, 0, 0)) \\ &\quad + \sum_{i=1}^m |d\varphi_{t,s}|^{p(x)-2} h(\nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), d\phi(e_i, 0, 0)) \\ &\quad + \sum_{i=1}^m |d\varphi_{t,s}|^{p(x)-2} h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0), \nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_i, 0, 0)). \end{aligned}$$

By the definition of the curvature tensor of (N, h) and the properties

$$\nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_i, 0, 0) = \nabla_{(e_i, 0, 0)}^\phi d\phi\left(\frac{\partial}{\partial t}\right), \quad \nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i, 0, 0) = \nabla_{(e_i, 0, 0)}^\phi d\phi\left(\frac{\partial}{\partial s}\right),$$

with $[\frac{\partial}{\partial t}, (e_i, 0, 0)] = 0$, we obtain the following equation

$$\begin{aligned} \frac{1}{p(x)} \frac{\partial^2}{\partial t \partial s} |d\varphi_{t,s}|^{p(x)} \Big|_{t=s=0} &= \sum_{i=1}^m h \left(\nabla_{e_i}^\varphi w, (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(e_i) \right) \\ &\quad - |d\varphi|^{p(x)-2} \sum_{i=1}^m h(R^N(v, d\varphi(e_i)) d\varphi(e_i), w) \\ &\quad + \sum_{i=1}^m h \left(\nabla_{e_i}^\varphi \nabla_{\frac{\partial}{\partial t}}^\phi d\phi\left(\frac{\partial}{\partial s}\right) \Big|_{t=s=0}, |d\varphi|^{p(x)-2} d\varphi(e_i) \right) \\ &\quad + \sum_{i=1}^m h \left(\nabla_{e_i}^\varphi w, |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi v \right). \end{aligned} \tag{3.6}$$

Let $\omega_1, \omega_2, \omega_3 \in \Gamma(T^*M)$ defined by

$$\begin{aligned} \omega_1(X) &= h \left(w, (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(X) \right); \\ \omega_2(X) &= h \left(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi\left(\frac{\partial}{\partial s}\right) \Big|_{t=s=0}, |d\varphi|^{p(x)-2} d\varphi(X) \right); \\ \omega_3(X) &= h \left(w, |d\varphi|^{p(x)-2} \nabla_X^\varphi v \right), \quad \forall X \in \Gamma(TM). \end{aligned}$$

The divergence of ω_1, ω_2 , and ω_3 are given by

$$\begin{aligned} \operatorname{div}^M \omega_1 &= \sum_{i=1}^m e_i h \left(w, (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(e_i) \right); \\ \operatorname{div}^M \omega_2 &= \sum_{i=1}^m e_i h \left(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi \left(\frac{\partial}{\partial s} \right) \Big|_{t=s=0}, |d\varphi|^{p(x)-2} d\varphi(e_i) \right); \\ \operatorname{div}^M \omega_3 &= \sum_{i=1}^m e_i h \left(w, |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi v \right), \quad \forall X \in \Gamma(TM). \end{aligned}$$

By equations (3.5), (3.6), the $p(\cdot)$ -harmonicity condition of φ , and the divergence Theorem, we obtain

$$\begin{aligned} \frac{\partial^2}{\partial t \partial s} E_{p(\cdot)}(\varphi_{t,s}; D) \Big|_{t=s=0} &= - \int_D \sum_{i=1}^m h \left(w, \nabla_{e_i}^\varphi (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(e_i) \right) v_g \\ &\quad - \int_D |d\varphi|^{p(x)-2} \sum_{i=1}^m h(w, R^N(v, d\varphi(e_i)) d\varphi(e_i)) v_g \\ &\quad - \int_D \sum_{i=1}^m h \left(w, \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi v \right) v_g. \end{aligned} \tag{3.7}$$

The proof is completed. □

If (M, g) is a compact Riemannian manifold, φ be a $p(\cdot)$ -harmonic map from (M, g) to Riemannian manifold (N, h) , and for any vector field v along φ ,

$$I_{p(\cdot)}^\varphi(v, v) \equiv \int_M h(v, J_{p(\cdot)}^\varphi(v)) v_g \geq 0, \tag{3.8}$$

then φ is called a stable $p(\cdot)$ -harmonic map. Note that, the definition of stable $p(\cdot)$ -harmonic maps is a generalization of stable harmonic maps ([10]), is also a generalization of stable p -harmonic maps ([4, 9]). By using the Green Theorem [1] it is easy to prove that

$$\begin{aligned} I_{p(\cdot)}^\varphi(v, v) &= - \int_M |d\varphi|^{p(x)-2} \sum_{i=1}^m h(v, R^N(v, d\varphi(e_i)) d\varphi(e_i)) v_g \\ &\quad + \int_M |d\varphi|^{p(x)-2} |\nabla^\varphi v|^2 v_g + \int_M (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle^2 v_g. \end{aligned} \tag{3.9}$$

From equation (3.9), we deduce the following result.

Proposition 3.1. *Every $p(\cdot)$ -harmonic map from compact Riemannian manifold (M, g) to Riemannian manifold (N, h) has $\operatorname{Sect}^N \leq 0$ is stable.*

In the case where the codomain of the stable $p(\cdot)$ -harmonic map is the standard sphere \mathbb{S}^n , we have the following result.

Theorem 3.2. *Let (M, g) be a compact Riemannian manifold. When $n > 2$, any stable $p(\cdot)$ -harmonic map $\varphi : (M, g) \rightarrow \mathbb{S}^n$ must be constant, where p is a smooth positive function on M such that $2 \leq p(x) < n$ for all $x \in M$.*

Proof. Choose a normal orthonormal frame $\{e_i\}_{i=1}^m$ at point x in (M, g) . We set $\lambda(y) = \langle \alpha, y \rangle_{\mathbb{R}^{n+1}}$, for all $y \in \mathbb{S}^n$, where $\alpha \in \mathbb{R}^{n+1}$. Let $v = \operatorname{grad}^{\mathbb{S}^n} \lambda$. We have $\nabla_X^{\mathbb{S}^n} v = -\lambda X$ for all $X \in \Gamma(T\mathbb{S}^n)$, where $\nabla^{\mathbb{S}^n}$ is the Levi-Civita connection on \mathbb{S}^n with respect to the standard metric of the sphere (see [10]). We compute

$$\begin{aligned} \sum_{i=1}^m \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi (v \circ \varphi) &= \nabla_{\operatorname{grad}^M |d\varphi|^{p(x)-2}}^\varphi (v \circ \varphi) \\ &\quad + \sum_{i=1}^m |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi \nabla_{e_i}^\varphi (v \circ \varphi). \end{aligned} \tag{3.10}$$

By using the property $\nabla_X^{\mathbb{S}^n} v = -\lambda X$, the first term of (3.10) is given by

$$\nabla_{\text{grad}^M |d\varphi|^{p(x)-2}}^\varphi (v \circ \varphi) = -(\lambda \circ \varphi) d\varphi(\text{grad}^M |d\varphi|^{p(x)-2}), \quad (3.11)$$

and the seconde term of (3.10) is given by

$$\begin{aligned} \sum_{i=1}^m |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi \nabla_{e_i}^\varphi (v \circ \varphi) &= - \sum_{i=1}^m |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi (\lambda \circ \varphi) d\varphi(e_i) \\ &= - \sum_{i=1}^m |d\varphi|^{p(x)-2} \langle d\varphi(e_i), v \circ \varphi \rangle d\varphi(e_i) \\ &\quad - (\lambda \circ \varphi) |d\varphi|^{p(x)-2} \tau(\varphi). \end{aligned} \quad (3.12)$$

Substituting the formulas (3.11) and (3.12) in (3.10) gives

$$\begin{aligned} \sum_{i=1}^m \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi (v \circ \varphi) &= -(\lambda \circ \varphi) d\varphi(\text{grad}^M |d\varphi|^{p(x)-2}) \\ &\quad - \sum_{i=1}^m |d\varphi|^{p(x)-2} \langle d\varphi(e_i), v \circ \varphi \rangle d\varphi(e_i) \\ &\quad - (\lambda \circ \varphi) |d\varphi|^{p(x)-2} \tau(\varphi). \end{aligned} \quad (3.13)$$

By the $p(\cdot)$ -harmonicity condition of φ

$$\tau_{p(\cdot)}(\varphi) = |d\varphi|^{p(x)-2} \tau(\varphi) + d\varphi(\text{grad}^M |d\varphi|^{p(x)-2}) = 0,$$

and equation (3.13), we get

$$\sum_{i=1}^m \langle \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi (v \circ \varphi), v \circ \varphi \rangle = - \sum_{i=1}^m |d\varphi|^{p(x)-2} \langle d\varphi(e_i), v \circ \varphi \rangle^2. \quad (3.14)$$

Since the sphere \mathbb{S}^n has constant curvature, we have

$$\begin{aligned} \sum_{i=1}^m \langle |d\varphi|^{p(x)-2} R^{\mathbb{S}^n} (v \circ \varphi, d\varphi(e_i)) d\varphi(e_i), v \circ \varphi \rangle &= |d\varphi|^{p(x)} \langle v \circ \varphi, v \circ \varphi \rangle \\ &\quad - \sum_{i=1}^m |d\varphi|^{p(x)-2} \langle d\varphi(e_i), v \circ \varphi \rangle^2. \end{aligned} \quad (3.15)$$

By the definition of generalized Jacobi operator, and (3.14), (3.15), we obtain

$$\begin{aligned} \langle J_f^\varphi (v \circ \varphi), v \circ \varphi \rangle &= 2|d\varphi|^{p(x)-2} \sum_{i=1}^m \langle d\varphi(e_i), v \circ \varphi \rangle^2 \\ &\quad - |d\varphi|^{p(x)} \langle v \circ \varphi, v \circ \varphi \rangle \\ &\quad - \sum_{i=1}^m \langle \nabla_{e_i}^\varphi (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v \circ \varphi, d\varphi \rangle d\varphi(e_i), v \circ \varphi \rangle, \end{aligned} \quad (3.16)$$

Using $\langle \nabla^\varphi v \circ \varphi, d\varphi \rangle = -(\lambda \circ \varphi) |d\varphi|^2$, and equation (3.16), we find that

$$\text{trace}_\alpha \langle J_f^\varphi (v \circ \varphi), v \circ \varphi \rangle = (p(x) - n) |d\varphi|^{p(x)}. \quad (3.17)$$

Hence Theorem 3.2 follows from (3.17), and the stable $p(\cdot)$ -harmonicity condition of φ , with $2 \leq p(x) < n$ for all $x \in M$. \square

4. $p(\cdot)$ -Biharmonic Maps

Let $\varphi : (M, g) \rightarrow (N, h)$ be a smooth map between two Riemannian manifolds, the $p(\cdot)$ -bienergy of φ is defined by

$$E_{2,p(\cdot)}(\varphi; D) = \frac{1}{2} \int_D |\tau_{p(\cdot)}(\varphi)|^2 v_g, \tag{4.1}$$

where $p \geq 2$ is a smooth function on M , and D a compact subset of M . A smooth map φ is called $p(\cdot)$ -biharmonic if it is a critical point of the $p(\cdot)$ -bienergy functional for any compact domain D .

Theorem 4.1 (The first variation of the $p(\cdot)$ -bienergy). *Let φ be a smooth map between two Riemannian manifolds (M, g) and (N, h) . Then we have*

$$\left. \frac{d}{dt} E_{2,p(\cdot)}(\varphi_t; D) \right|_{t=0} = - \int_D h(v, \tau_{2,p(\cdot)}(\varphi)) v_g, \tag{4.2}$$

where $\{\varphi_t\}_{t \in (-\epsilon, \epsilon)}$ is a smooth variation of φ supported in D , $v = \left. \frac{d\varphi_t}{dt} \right|_{t=0}$ denotes the variation vector field, and $\tau_{2,p(\cdot)}(\varphi)$ the $p(\cdot)$ -bitension field of φ given by

$$\begin{aligned} \tau_{2,p(\cdot)}(\varphi) &= -|d\varphi|^{p(x)-2} \text{trace}_g R^N(\tau_{p(\cdot)}(\varphi), d\varphi)d\varphi - \text{trace}_g \nabla^\varphi |d\varphi|^{p(x)-2} \nabla^\varphi \tau_{p(\cdot)}(\varphi) \\ &\quad - \text{trace}_g \nabla(p(x) - 2)|d\varphi|^{p(x)-4} \langle \nabla^\varphi \tau_{p(\cdot)}(\varphi), d\varphi \rangle d\varphi. \end{aligned} \tag{4.3}$$

Proof. Define $\phi : M \times (-\epsilon, \epsilon) \rightarrow N$ by $\phi(x, t) = \varphi_t(x)$. First, note that

$$\frac{d}{dt} E_{2,p(\cdot)}(\varphi_t; D) = \int_D h(\nabla_{\frac{\partial}{\partial t}}^\phi \tau_{p(\cdot)}(\varphi_t), \tau_{p(\cdot)}(\varphi_t)) v_g. \tag{4.4}$$

Calculating in a normal frame at $x \in M$, we have

$$\nabla_{\frac{\partial}{\partial t}}^\phi \tau_{p(\cdot)}(\varphi_t) = \sum_{i=1}^m \nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{(e_i, 0)}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0). \tag{4.5}$$

From the definition of the curvature tensor of (N, h) , we obtain

$$\begin{aligned} &\sum_{i=1}^m \nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{(e_i, 0)}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0) \\ &= |d\varphi_t|^{p(x)-2} \sum_{i=1}^m R^N(d\phi(\frac{\partial}{\partial t}), d\phi(e_i, 0)) d\phi(e_i, 0) \\ &\quad + \sum_{i=1}^m \nabla_{(e_i, 0)}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0). \end{aligned} \tag{4.6}$$

By using the compatibility of ∇^ϕ with h , we find that

$$\begin{aligned} &\sum_{i=1}^m h(\nabla_{(e_i, 0)}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0), \tau_{p(\cdot)}(\varphi_t)) \\ &= \sum_{i=1}^m (e_i, 0) \left[h(\nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0), \tau_{p(\cdot)}(\varphi_t)) \right] \\ &\quad - \sum_{i=1}^m h(\nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0), \nabla_{(e_i, 0)}^\phi \tau_{p(\cdot)}(\varphi_t)). \end{aligned} \tag{4.7}$$

From the property $\nabla_X^\phi d\phi(Y) = \nabla_Y^\phi d\phi(X) + d\phi([X, Y])$, with $X = \frac{\partial}{\partial t}$ and $Y = |d\varphi_t|^{p(x)-2}(e_i, 0)$, we get

$$\begin{aligned} \nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0) \Big|_{t=0} &= |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi v \\ &+ \sum_{j=1}^m (p(x) - 2) |d\varphi|^{p(x)-4} h(\nabla_{e_j}^\varphi v, d\varphi(e_j)) d\varphi(e_i), \end{aligned} \tag{4.8}$$

for all $i = 1, \dots, m$. Substituting (4.8) in (4.7), we have

$$\begin{aligned} \sum_{i=1}^m h(\nabla_{(e_i, 0)}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi |d\varphi_t|^{p(x)-2} d\phi(e_i, 0), \tau_{p(\cdot)}(\varphi_t)) \Big|_{t=0} &= \sum_{i=1}^m e_i h(|d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi v, \tau_{p(\cdot)}(\varphi)) \\ &+ \sum_{i=1}^m e_i h((p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(e_i), \tau_{p(\cdot)}(\varphi)) \\ &- \sum_{i=1}^m e_i h(v, |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi \tau_{p(\cdot)}(\varphi)) \\ &+ \sum_{i=1}^m h(v, \nabla_{e_i}^\varphi |d\varphi|^{p(x)-2} \nabla_{e_i}^\varphi \tau_{p(\cdot)}(\varphi)) \\ &- \sum_{j=1}^m e_j h(v, (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi \tau_{p(\cdot)}(\varphi), d\varphi \rangle d\varphi(e_j)) \\ &+ \sum_{j=1}^m h(v, \nabla_{e_j}^\varphi (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi \tau_{p(\cdot)}(\varphi), d\varphi \rangle d\varphi(e_j)). \end{aligned} \tag{4.9}$$

Let $\eta_1, \eta_2, \eta_3, \eta_4 \in \Gamma(T^*M)$ defined by

$$\begin{aligned} \eta_1(X) &= h(|d\varphi|^{p(x)-2} \nabla_X^\varphi v, \tau_{p(\cdot)}(\varphi)); \\ \eta_2(X) &= h((p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi v, d\varphi \rangle d\varphi(X), \tau_{p(\cdot)}(\varphi)); \\ \eta_3(X) &= h(v, |d\varphi|^{p(x)-2} \nabla_X^\varphi \tau_{p(\cdot)}(\varphi)); \\ \eta_4(X) &= h(v, (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi \tau_{p(\cdot)}(\varphi), d\varphi \rangle d\varphi(X)). \end{aligned}$$

Finally, we calculate the divergence of η_i ($i = 1, \dots, 4$) and substituting in (4.9). The proof of Theorem 4.1 follows by (4.4)-(4.6), (4.9), and the divergence Theorem. \square

From Theorem 4.1, we deduce:

Corollary 4.1. *Let $\varphi : (M, g) \rightarrow (N, h)$ be a smooth map between Riemannian manifolds. Then, φ is $p(\cdot)$ -biharmonic if and only if*

$$\begin{aligned} \tau_{2,p(\cdot)}(\varphi) &= -|d\varphi|^{p(x)-2} \text{trace}_g R^N(\tau_{p(\cdot)}(\varphi), d\varphi) d\varphi \\ &- \text{trace}_g \nabla^\varphi |d\varphi|^{p(x)-2} \nabla^\varphi \tau_{p(\cdot)}(\varphi) \\ &- \text{trace}_g \nabla (p(x) - 2) |d\varphi|^{p(x)-4} \langle \nabla^\varphi \tau_{p(\cdot)}(\varphi), d\varphi \rangle d\varphi = 0. \end{aligned}$$

Remark 4.1. For any smooth map $\varphi : (M, g) \rightarrow (N, h)$ between two Riemannian manifolds, we have

$$\tau_{2,p(\cdot)}(\varphi) = J_{p(\cdot)}^\varphi(\tau_{p(\cdot)}(\varphi)).$$

We can extract several examples of $p(\cdot)$ -biharmonic non $p(\cdot)$ -harmonic maps $\varphi : (M, g) \rightarrow \mathbb{R}^n$ where the $p(\cdot)$ -tension field is parallel along φ , i.e., the components of $\tau_{p(\cdot)}(\varphi)$ are constants.

Example 4.1. Let $M = \{(x, y, z) \in \mathbb{R}^3, \sqrt{x^2 + y^2} > 2\}$. The smooth map $\varphi : M \rightarrow \mathbb{R}^2$ defined by

$$\varphi(x, y, z) = (\sqrt{x^2 + y^2}, z), \quad \forall (x, y, z) \in M,$$

is $p(\cdot)$ -biharmonic non $p(\cdot)$ -harmonic, where

$$p(x, y, z) = \frac{\ln(x^2 + y^2)}{\ln(2)},$$

for all $(x, y, z) \in M$. Here, $\tau_{p(\cdot)}(\varphi) = (1, 0)$.

Acknowledgements

The authors are supported by National Agency Scientific Research of Algeria and Laboratory of Geometry, Analysis, Control and Applications, Algeria.

Funding

There is no funding for this work.

Availability of data and materials

Not applicable.

Competing interests

The authors declare that they have no competing interests.

Author's contributions

All authors contributed equally to the writing of this paper. All authors read and approved the final manuscript.

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