

## Weierstrass Representation, Degree and Classes of the Surfaces in the Four Dimensional Euclidean Space

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### Abstract

We study two parameters families of Bour-type and Enneper-type minimal surfaces using the Weierstrass representation in the four dimensional Euclidean space. We obtain implicit algebraic equations, degree and classes of the surfaces.

**Keywords** — 4-space, surface, Weierstrass representation, degree, class.

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### 1 Surfaces in $\mathbb{R}^4$

In Moore [4], we find a general definition of rotation surfaces in  $\mathbb{R}^4$ :

$$\begin{aligned} X(u, t) &= (x_1(u) \cos(at) - x_2(u) \sin(at), \\ &\quad x_1(u) \cos(at) + x_2(u) \sin(at), \\ &\quad x_3(u) \cos(bt) - x_4(u) \sin(bt), \\ &\quad x_3(u) \cos(bt) + x_4(u) \sin(bt)). \end{aligned}$$

We propose that we look at a restricted case of this, found in Ganchev-Milousheva [2] :

$$W(u, t) = (x_1(u), x_2(u), r(u) \cos(t), r(u) \sin(t)).$$

The first we think is a bit too general since the curve is not located in any subspace before rotation.

At any rate this has:

$$g(\partial u, \partial u) = r'^2 + (x_1)^2 + (x_2)^2 = 1$$

if we use arc length parametrization,  $g(\partial u, \partial t) = 0$  and  $g(\partial t, \partial t) = r^2$ .

Using the Weierstrass representation in Section 2, we give two parameters familes of Bour's-type (in Section 3) and Enneper's-type (in Section 4) minimal surfaces in the four dimensional Euclidean space. We also calculate implicit algebraic equations of the surfaces, degrees and classes of the surfaces.

### 2 Weierstrass equations for a minimal surface

in  $\mathbb{R}^4$

In Hoffman and Osserman [3], p.45, they give the Weierstrass equations for a minimal surface in  $\mathbb{R}^4$ :

$$\Phi(z) = \frac{\psi}{2}(1+fg, i(1-fg), f-g, -i(f+g)).$$

Here  $\psi$  is analytic and the order of the zeros of  $\psi$  must be greater than the order of the poles of  $f, g$  at each point. If  $\psi = 2z$  and  $f = f_1 + if_2$ ,  $g = g_1 + ig_2$  then

$$\begin{aligned} X_x - iX_y &= \Phi(z) \\ &= z(1+fg, i(1-fg), f-g, -i(f+g)) \\ &= ((1+f_1g_1 - f_2g_2)x - (f_2g_1 + f_1g_2)y, \\ &\quad (f_2g_1 + f_1g_2)x - y + f_1g_1y - f_2g_2y, \\ &\quad (f_1 - g_1)x + (-f_2 + g_2)y, (f_2 + g_2)x + (f_1 + g_1)y) \\ &\quad - i(-y - f_1(g_2x + g_1y) + f_2(-g_1x + g_2y)), \\ &\quad (-1 + f_1g_1 - f_2g_2)x - (f_2g_1 + f_1g_2)y, \\ &\quad + (-f_2 + g_2)x + (-f_1 + g_1)y, \\ &\quad (f_1 + g_1)x - (f_2 + g_2)y) \end{aligned}$$

We set

$$\begin{aligned} w_1 &= (-f_2g_1x + f_1g_2x - y + f_1g_1y - f_2g_2y), \\ &\quad (1 + f_1g_1 - f_2g_2)x - (f_2g_1 + f_1g_2)y, \\ &\quad - ((f_2 + g_2)x + (f_1 + g_1)y), \\ &\quad (f_1 - g_1)x + (-f_2 + g_2)y) \end{aligned}$$

which is perpendicular to  $X_x$ , and

$$\begin{aligned} w_2 &= (((-1 + f_1g_1 - f_2g_2)x - (f_2g_1 + f_1g_2)y), \\ &\quad - y - f_1(g_2x + g_1y) + f_2(-g_1x + g_2y), \\ &\quad - (f_1x + g_1x - (f_2 + g_2)y), \\ &\quad - f_2x + g_2x + (-f_1 + g_1)y) \end{aligned}$$

which is perpendicular to  $X_y$ .

So far we see that:

$$\begin{aligned} b &= \langle X_x, w_2 \rangle \\ &= -(-1 + f_1^2 + f_2^2)(1 + g_1^2 + g_2^2)(x^2 + y^2) \\ &= -\langle X_y, w_1 \rangle, \end{aligned}$$

while

$$\begin{aligned} a &= \langle X_x, X_x \rangle \\ &= \langle X_y, X_y \rangle \\ &= (1 + f_1^2 + f_2^2)(1 + g_1^2 + g_2^2)(x^2 + y^2) \\ &= \langle w_j, w_j \rangle. \end{aligned}$$

Now we can use Gram-Schmidt to find an orthonormal basis for the normal space. We let  $e_1 = X_x / \sqrt{a}$  and  $e_2 = X_y / \sqrt{a}$ . Then we get

$$n_1 = \sqrt{\frac{a}{a^2 - b^2}} (w_1 + \frac{b}{a} X_y),$$

$$n_2 = \sqrt{\frac{a}{a^2 - b^2}} (w_2 - \frac{b}{a} X_x),$$

where

$$a^2 - b^2 = 4(f_1^2 + f_2^2)(x^2 + y^2)^2(g_1^2 + g_2^2 + 1)^2,$$

$$\begin{aligned} \sqrt{\frac{a}{a^2 - b^2}} &= \sqrt{\frac{1 + f_1^2 + f_2^2}{4(f_1^2 + f_2^2)(x^2 + y^2)(g_1^2 + g_2^2 + 1)}}, \\ \frac{b}{a} &= -\frac{-1 + f_1^2 + f_2^2}{1 + f_1^2 + f_2^2}. \end{aligned}$$

Then

$$n_1 = \sqrt{\frac{a}{a^2 - b^2}} \begin{bmatrix} -(f_1 g_2 + f_2 g_1)x - (-1 + f_1 g_1 - f_2 g_2)y \\ (1 + f_1 g_1 - f_2 g_2)x - (f_2 g_1 + f_1 g_2)y \\ -(f_2 + g_2)x - (f_1 + g_1)y \\ (f_1 - g_1)x + (-f_2 + g_2)y \\ -(f_1 g_2 + f_2 g_1)x + (-1 - f_1 g_1 - f_2 g_2)y \\ (-1 + f_1 g_1 - f_2 g_2)x - (f_2 g_1 + f_1 g_2)y \\ (-f_2 + g_2)x + (-f_1 + g_1)y \\ (f_1 + g_1)x - (f_2 + g_2)y \end{bmatrix}.$$

$$\int \Phi(z) dz = \begin{pmatrix} \frac{z^2}{2} + \frac{z^{m+n+2}}{m+n+2} \\ i\left(\frac{z^2}{2} - \frac{z^{m+n+2}}{m+n+2}\right) \\ \frac{z^{m+2}}{m+2} - \frac{z^{n+2}}{n+2} \\ -i\left(\frac{z^{m+2}}{m+2} + \frac{z^{n+2}}{n+2}\right) \end{pmatrix}.$$

We let  $z = re^{i\theta}$  and take the real part

With  $x = r \cos(\theta)$ ,  $y = r \sin(\theta)$ ,  
 $f_1 = r^m \cos(m\theta)$ ,  $f_2 = r^m \sin(m\theta)$ ,  
 $g_1 = r^n \cos(n\theta)$ ,  $g_2 = r^n \sin(n\theta)$  we have: normals  $n_1(r, \theta)$ :

$$\frac{1}{\sqrt{(r^{2m} + 1)(r^{2n} + 1)}} \begin{pmatrix} r^m \sin(\theta) - r^n \sin((m+n+1)\theta) \\ r^m \cos(\theta) + r^n \cos((m+n+1)\theta) \\ -r^{m+n} \sin((n+1)\theta) - \sin((m+1)\theta) \\ -r^{m+n} \cos((n+1)\theta) + \cos((m+1)\theta) \end{pmatrix}$$

and  $n_2(r, \theta)$ :

$$\frac{1}{\sqrt{(r^{2m} + 1)(r^{2n} + 1)}} \begin{pmatrix} r^m \cos(\theta) - r^n \cos((m+n+1)\theta) \\ -r^m \sin(\theta) - r^n \sin((m+n+1)\theta) \\ -r^{m+n} \cos((n+1)\theta) - \cos((m+1)\theta) \\ r^{m+n} \sin((n+1)\theta) - \sin((m+1)\theta) \end{pmatrix}$$

$$\mathbf{B}_{m,n}(r, \theta) = \begin{pmatrix} \frac{r^2 \cos(2\theta)}{2} + \frac{r^{m+n+2} \cos((m+n+2)\theta)}{m+n+2} \\ -\frac{r^2 \sin(2\theta)}{2} + \frac{r^{m+n+2} \sin((m+n+2)\theta)}{m+n+2} \\ \frac{r^{m+2} \cos((m+2)\theta)}{m+2} - \frac{r^{n+2} \cos((n+2)\theta)}{n+2} \\ \frac{r^{m+2} \sin((m+2)\theta)}{m+2} + \frac{r^{n+2} \sin((n+2)\theta)}{n+2} \end{pmatrix}$$

**Example:** For  $m = 2$ ,  $n = 0$ , we have  $\mathbf{B}_{2,0}(r, \theta)$ :

$$\begin{pmatrix} \frac{r^2 \cos(2\theta)}{2} + \frac{r^4 \cos(4\theta)}{4} \\ -\frac{r^2 \sin(2\theta)}{2} + \frac{r^4 \sin(4\theta)}{4} \\ \frac{r^2 \cos(2\theta)}{2} + \frac{r^4 \cos(4\theta)}{4} \\ \frac{r^2 \sin(2\theta)}{2} + \frac{r^4 \sin(4\theta)}{4} \end{pmatrix} = \begin{pmatrix} x(r, \theta) \\ y(r, \theta) \\ z(r, \theta) \\ w(r, \theta) \end{pmatrix},$$

and  $\mathbf{B}_{2,0}(u, v)$ :

$$\begin{pmatrix} \frac{1}{2}(u^2 - v^2) + \frac{1}{4}u^4 - \frac{3}{2}u^2v^2 + \frac{1}{4}v^4 \\ -uv + u^3v - uv^3 \\ -\frac{1}{2}(u^2 - v^2) + \frac{1}{4}u^4 - \frac{3}{2}u^2v^2 + \frac{1}{4}v^4 \\ uv + u^3v - uv^3 \end{pmatrix} = \begin{pmatrix} x(u, v) \\ y(u, v) \\ z(u, v) \\ w(u, v) \end{pmatrix}.$$

### 3 Bour's family of surfaces

We now choose, in analogy with the surface case,  $\psi = 2z$ ,  $f = z^m$  and  $g = z^n$ , with  $m \neq n$ . This gives:

$$\Phi(z) = z(1 + z^{m+n}, i(1 - z^{m+n}), z^m - z^n, -i(z^m + z^n)).$$

We integrate to get:

We want to find normals  $n_1$  and  $n_2$  of the Bour's minimal surface

$$\mathbf{B}_{2,0}(u, v) = (x(u, v), y(u, v), z(u, v), w(u, v)),$$

and degree of the algebraic Bour minimal surface.

Hence, we find the implicit equations  $Q(x, y, z, w) = 0$  of  $\mathbf{B}_{2,0}(u, v)$  using elimination

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techniques in the cartesian coordinates  $x, y, z, w$   
as follow:

$$y^2 + 4xy^2 + y^4 - 2yw - 8xyw - 4y^3w - 3w^2 + 4xw^2 + 6y^2w^2 - 4yw^3 + w^4,$$

and

$$-3y^2 + y^4 + 4y^2z - 2yw - 4y^3w - 8yzw + w^2 + 6y^2w^2 + 4zw^2 - 4yw^3 + w^4.$$

without  $z$  and  $x$ , respectively. But we should get with  $x, y, z, w$ . On the other hand, we use the Sylvester elimination technique and find the implicit eq. as follows:

$$\det \begin{pmatrix} 1 & 0 & A & 0 \\ 0 & 1 & 0 & A \\ 1 & 0 & B & 0 \\ 0 & 1 & 0 & B \end{pmatrix} = (B-A)^2$$

$$= (2x + 2z - 2wy + 2xz + w^2 - x^2 + y^2 - z^2)^2,$$

where

$$A = -2(x-z)^2 + 2(x+z),$$

$$B = -(x-z)^2 - (w-y)^2.$$

For short, taking  $r^4 = t^2 = k$ , then we get

$$\det \begin{pmatrix} 1 & A \\ 1 & B \end{pmatrix} = B - A$$

$$= 2x + 2z - 2wy + 2xz + w^2 - x^2 + y^2 - z^2.$$

Hence, the irreducible implicit equation is

$$Q(x, y, z, w) = 2x + 2z - 2wy + 2xz + w^2 - x^2 + y^2 - z^2$$

with  $\deg(\mathbf{B}_{2,0}) = 2$ . So,  $\mathbf{B}_{2,0}$  is an algebraic minimal surface in 4-space. Then find  $P_1$  using

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$$xX_1 + yY_1 + zZ_1 + wW_1 + P_1 = 0,$$

where

$$n_1 = (X_1(u, v), Y_1(u, v), Z_1(u, v), W_1(u, v)),$$

and  $P_1 = P_1(u, v)$ . Similarly, find  $P_2$  using

$$xX_2 + yY_2 + zZ_2 + wW_2 + P_2 = 0,$$

where

$$n_2 = (X_2(u, v), Y_2(u, v), Z_2(u, v), W_2(u, v)),$$

and  $P_2 = P_2(u, v)$ . Therefore, inhomogeneous tangential coordinates of the Bour surface, using  $n_1$  (resp. using  $n_2$ ), are  $a_1 = X_1/P_1$ ,  $b_1 = Y_1/P_1$ ,  $c_1 = Z_1/P_1$ ,  $d_1 = W_1/P_1$  (resp.  $a_2 = X_2/P_2$ ,  $b_2 = Y_2/P_2$ ,  $c_2 = Z_2/P_2$ ,  $d_2 = W_2/P_2$ ).

Hence, we can find the implicit eq.

$$\widetilde{Q}_1(a_1, b_1, c_1, d_1) = 0$$

$$(\text{resp. } \widetilde{Q}_2(a_2, b_2, c_2, d_2) = 0)$$

of

$$\mathfrak{B}_{2,0}(u, v)$$

using elimination techniques in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$  (resp.  $a_2, b_2, c_2, d_2$ ) and can find the classes of the algebraic Bour minimal surface (we have 2 normals and then have 2 classes).

$$(n_1)_{2,0}(r, \theta) = \frac{1}{\sqrt{2(r^4 + 1)}} \begin{pmatrix} r^2 \sin(\theta) - \sin(3\theta) \\ r^2 \cos(\theta) + \cos(3\theta) \\ -r^2 \sin(\theta) - \sin(3\theta) \\ -r^2 \cos(\theta) + \cos(3\theta) \end{pmatrix}$$

$$= \begin{pmatrix} X_1(r, \theta) \\ Y_1(r, \theta) \\ Z_1(r, \theta) \\ W_1(r, \theta) \end{pmatrix},$$

$$(n_1)_{2,0}(u,v) = \begin{pmatrix} \frac{v(u^4+2u^2v^2-3u^2+v^4+v^2)}{(u^2+v^2)^{\frac{3}{2}}\sqrt{2((u^2+v^2)^2+1)}} \\ \frac{u(u^4+2u^2v^2+u^2+v^4-3v^2)}{(u^2+v^2)^{\frac{3}{2}}\sqrt{2((u^2+v^2)^2+1)}} \\ -\frac{v(u^4+2u^2v^2+3u^2+v^4-v^2)}{(u^2+v^2)^{\frac{3}{2}}\sqrt{2((u^2+v^2)^2+1)}} \\ -\frac{u(u^4+2u^2v^2-u^2+v^4+3v^2)}{(u^2+v^2)^{\frac{3}{2}}\sqrt{2((u^2+v^2)^2+1)}} \end{pmatrix}$$

$$= \begin{pmatrix} X_1(u,v) \\ Y_1(u,v) \\ Z_1(u,v) \\ W_1(u,v) \end{pmatrix}.$$

Using  $xX_1 + yY_1 + zZ_1 + wW_1 + P_1 = 0$ , we get

$$P_1 = \frac{v\sqrt{2}\left(\sqrt{u^2+v^2}\right)^3}{4\sqrt{(u^2+v^2)^2+1}},$$

and then

$$a_1 = X_1/P_1 = \frac{2(u^4+2u^2v^2-3u^2+v^4+v^2)}{(u^2+v^2)^3},$$

$$b_1 = Y_1/P_1 = \frac{2u(u^4+2u^2v^2+u^2+v^4-3v^2)}{v(u^2+v^2)^3},$$

$$c_1 = Z_1/P_1 = \frac{-2(u^4+2u^2v^2+3u^2+v^4-v^2)}{(u^2+v^2)^3},$$

$$d_1 = W_1/P_1 = \frac{-2u(u^4+2u^2v^2-u^2+v^4+3v^2)}{v(u^2+v^2)^3}.$$

Hence, in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$ , parametric eq. of Bour surface is

$$\mathfrak{B}_{2,0}(u,v) = \frac{2}{v(u^2+v^2)^3} \begin{pmatrix} v(u^4+2u^2v^2-3u^2+v^4+v^2) \\ u(u^4+2u^2v^2+u^2+v^4-3v^2) \\ -v(u^4+2u^2v^2+3u^2+v^4-v^2) \\ -u(u^4+2u^2v^2-u^2+v^4+3v^2) \end{pmatrix}$$

$$= \begin{pmatrix} a_1(u,v) \\ b_1(u,v) \\ c_1(u,v) \\ d_1(u,v) \end{pmatrix}.$$

So, we have 6 implicit eqs.

$$\tilde{Q}_1(a_1, b_1, c_1, d_1) = 0$$

of

$$\mathfrak{B}_{2,0}(u,v)$$

using elimination techniques in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$ , as follow:

$$\begin{aligned} \tilde{Q}_1(a_1, b_1, c_1, d_1) &= -a_1^2b_1 + a_1^2d_1 + 2a_1b_1c_1 \\ &\quad - 2a_1c_1d_1 - b_1c_1^2 + c_1^2d_1 \\ &\quad - 4a_1b_1 + 4c_1d_1, \end{aligned}$$

or

$$\begin{aligned} \tilde{Q}_1(a_1, b_1, c_1, d_1) &= -a_1^3 + 2a_1^2c_1 + 2a_1b_1^2 \\ &\quad - 2a_1b_1d_1 - a_1c_1^2 - b_1^2c_1 \\ &\quad + c_1d_1^2 + 4a_1^2 + 4a_1c_1 \\ &\quad + 4b_1d_1 + 4d_1^2, \end{aligned}$$

or

$$\begin{aligned} \tilde{Q}_1(a_1, b_1, c_1, d_1) &= -2a_1^3 + 5a_1^2c_1 + 3a_1b_1^2 - 4a_1b_1d_1 \\ &\quad - 4a_1c_1^2 + a_1d_1^2 - 2b_1^2c_1 + 2b_1c_1d_1 \\ &\quad + c_1^3 + 8a_1^2 + 4a_1c_1 - 4b_1^2 + 4b_1d_1 \\ &\quad - 4c_1^2 + 8d_1^2, \end{aligned}$$

or

$$\begin{aligned}\tilde{Q}_1(a_1, b_1, c_1, d_1) = & a_1^4 - 4a_1^3c_1 + 6a_1^2c_1^2 - 4a_1c_1^3 \\ & + c_1^4 - 2a_1^2c_1 - 2a_1b_1^2 + 4a_1b_1d_1 \\ & + 4a_1c_1^2 - 2a_1d_1^2 - 2c_1^3 - 16a_1^2 \\ & - 24a_1c_1 - 8b_1^2 - 24b_1d_1 - 8c_1^2 \\ & - 16d_1^2,\end{aligned}$$

or

$$\begin{aligned}\tilde{Q}_1(a_1, b_1, c_1, d_1) = & -2a_1^3b_1 + 6a_1^2b_1c_1 - a_1b_1^3 + 3a_1b_1^2d_1 \\ & - 6a_1b_1c_1^2 - 3a_1b_1d_1^2 + a_1d_1^3 + 2b_1c_1^3 \\ & - 16a_1^2b_1 + 16a_1^2d_1 + 16a_1b_1c_1 - 4a_1c_1d_1 \\ & - 4b_1^3 - 8b_1^2d_1 - 12b_1c_1^2 + 4b_1d_1^2 + 8d_1^3 \\ & - 32a_1b_1 + 32c_1d_1,\end{aligned}$$

or

$$\begin{aligned}\tilde{Q}_1(a_1, b_1, c_1, d_1) = & a_1b_1^4 - 4a_1b_1^3d_1 + 6a_1b_1^2d_1^2 - 4a_1b_1d_1^3 + a_1d_1^4 \\ & - 16a_1^4 + 38a_1^3c_1 + 14a_1^2b_1^2 - 44a_1^2b_1d_1 \\ & - 28a_1^2c_1^2 + 22a_1^2d_1^2 + 16a_1b_1^2c_1 + 6a_1c_1^3 \\ & + 4b_1^4 + 4b_1^3d_1 - 8b_1^2c_1^2 - 12b_1^2d_1^2 - 4b_1d_1^3 \\ & + 8d_1^4 + 144a_1^3 - 144a_1^2c_1 - 208a_1b_1^2 \\ & + 168a_1b_1d_1 + 104a_1c_1^2 + 40a_1d_1^2 + 80b_1^2c_1 \\ & - 24c_1^3 - 320a_1^2 - 224a_1c_1 + 96b_1^2 - 224b_1d_1 \\ & + 96c_1^2 - 320d_1^2.\end{aligned}$$

So,

$$\text{classes}(\tilde{\mathfrak{B}}_{2,0}) = 3, 4, 5.$$

We can use the same techniques for  $(n_2)_{2,0}$  :

$$\begin{aligned}(n_2)_{2,0}(r, \theta) &= \frac{1}{\sqrt{2(r^4 + 1)}} \begin{pmatrix} r^2 \cos(\theta) - \cos(3\theta) \\ -r^2 \sin(\theta) - \sin(3\theta) \\ -r^2 \cos(\theta) - \cos(3\theta) \\ r^2 \sin(\theta) - \sin(3\theta) \end{pmatrix} \\ &= \begin{pmatrix} X_2(r, \theta) \\ Y_2(r, \theta) \\ Z_2(r, \theta) \\ W_2(r, \theta) \end{pmatrix},\end{aligned}$$

$$(n_2)_{2,0}(u, v) = \begin{pmatrix} X_2(u, v) \\ Y_2(u, v) \\ Z_2(u, v) \\ W_2(u, v) \end{pmatrix}.$$

#### 4 Enneper's family of surfaces

We now choose, in analogy with the surface case,  $\psi = 2$ ,  $f = z^m$  and  $g = z^n$ , with  $m \neq n$ . This gives:

We integrate to get:

$$\int \Phi(z) dz = \begin{pmatrix} z + \frac{z^{m+n+1}}{m+n+1} \\ i\left(z - \frac{z^{m+n+1}}{m+n+1}\right) \\ \frac{z^{m+1}}{m+1} - \frac{z^{n+1}}{n+1} \\ -i\left(\frac{z^{m+1}}{m+1} + \frac{z^{n+1}}{n+1}\right) \end{pmatrix}.$$

We let  $z = re^{i\theta}$  and take the real part

$$\mathbf{E}_{m,n}(r, \theta) = \begin{pmatrix} r \cos(\theta) + \frac{r^{m+n+1} \cos((m+n+1)\theta)}{m+n+1} \\ -r \sin(\theta) + \frac{r^{m+n+1} \sin((m+n+1)\theta)}{m+n+1} \\ \frac{r^{m+1} \cos((m+1)\theta)}{m+1} - \frac{r^{n+1} \cos((n+1)\theta)}{n+1} \\ \frac{r^{m+1} \sin((m+1)\theta)}{m+1} + \frac{r^{n+1} \sin((n+1)\theta)}{n+1} \end{pmatrix}.$$

**Example:** For  $m = 2$ ,  $n = 0$ , we have  $\mathbf{E}_{2,0}(r, \theta)$ :

$$\begin{pmatrix} \frac{r^3 \cos(3\theta)}{3} + r \cos(\theta) \\ \frac{r^3 \sin(3\theta)}{3} - r \sin(\theta) \\ \frac{r^3 \cos(3\theta)}{3} - r \cos(\theta) \\ \frac{r^3 \sin(3\theta)}{3} + r \sin(\theta) \end{pmatrix} = \begin{pmatrix} x(r, \theta) \\ y(r, \theta) \\ z(r, \theta) \\ w(r, \theta) \end{pmatrix},$$

and  $\mathbf{E}_{2,0}(u, v)$ :

$$\begin{pmatrix} \frac{1}{3}u^3 - uv^2 + u \\ u^2v - \frac{1}{3}v^3 - v \\ \frac{1}{3}u^3 - uv^2 - u \\ u^2v - \frac{1}{3}v^3 + v \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \\ w(u,v) \end{pmatrix},$$

where  $u = r \cos \theta$ ,  $v = r \sin \theta$ .

We want to find normals  $n_1$  and  $n_2$  of the Enneper's minimal surface

$$\mathbf{E}_{2,0}(u,v) = (x(u,v), y(u,v), z(u,v), w(u,v)),$$

and degree of the algebraic Enneper minimal surface.

We have  $r + A = 0$ ,  $r^3 + B = 0$  and

$$Syl(A, B, r) = \det \begin{pmatrix} 1 & A & 0 & 0 \\ 0 & 1 & A & 0 \\ 0 & 0 & 1 & A \\ 1 & 0 & 0 & B \end{pmatrix} = B - A^3,$$

where

$$\begin{aligned} A &= -\frac{1}{4}((x-z)^2 + (w-y)^2), \\ B &= -\frac{9}{4}((x+z)^2 + (w+y)^2). \end{aligned}$$

Hence, we find the irreducible implicit equation  $\mathcal{Q}(x, y, z, w) = 0$  of  $\mathbf{E}_{2,0}(u, v)$  using elimination techniques in the cartesian coordinates  $x, y, z, w$  as follows:

$$\begin{aligned} w^6 - 6w^5y + 3w^4x^2 - 6w^4xz + 15w^4y^2 + 3w^4z^2 \\ - 12w^3x^2y + 24w^3xyz - 20w^3y^3 - 12w^3yz^2 + 3w^2x^4 \\ - 12w^2x^3z + 18w^2x^2y^2 + 18w^2x^2z^2 - 36w^2xy^2z \\ - 12w^2xz^3 + 15w^2y^4 + 18w^2y^2z^2 + 3w^2z^4 - 144w^2 \\ - 6wx^4y + 24wx^3yz - 12wx^2y^3 - 36wx^2yz^2 + 24wxy^3z \\ + 24wxyz^3 - 6wy^5 - 12wy^3z^2 - 6wyz^4 - 288wy + x^6 \\ - 6x^5z + 3x^4y^2 + 15x^4z^2 - 12x^3y^2z - 20x^3z^3 + 3x^2y^4 \\ + 18x^2y^2z^2 + 15x^2z^4 - 144x^2 - 6xy^4z - 12xy^2z^3 - 6xz^5 \\ - 288xz + y^6 + 3y^4z^2 + 3y^2z^4 - 144y^2 + z^6 - 144z^2. \end{aligned}$$

Its degree is  $\deg(\mathbf{E}_{2,0}) = 6$ . So,  $\mathcal{Q}(x, y, z, w) = 0$  is an implicit algebraic Enneper type minimal surface in 4-space. Then find  $P_1$  using

$$xX_1 + yY_1 + zZ_1 + wW_1 + P_1 = 0,$$

where

$$n_1 = (X_1(u,v), Y_1(u,v), Z_1(u,v), W_1(u,v)),$$

and  $P_1 = P_1(u,v)$ . Similarly, find  $P_2$  using

$$xX_2 + yY_2 + zZ_2 + wW_2 + P_2 = 0,$$

where

$$n_2 = (X_2(u,v), Y_2(u,v), Z_2(u,v), W_2(u,v)),$$

and  $P_2 = P_2(u,v)$ . Therefore, inhomogeneous tangential coordinates of the Enneper surface, using  $n_1$  (resp. using  $n_2$ ), are  $a_1 = X_1/P_1$ ,  $b_1 = Y_1/P_1$ ,  $c_1 = Z_1/P_1$ ,  $d_1 = W_1/P_1$  (resp.  $a_2 = X_2/P_2$ ,  $b_2 = Y_2/P_2$ ,  $c_2 = Z_2/P_2$ ,  $d_2 = W_2/P_2$ ).

Hence, we can find the implicit eq.

$$\widetilde{\mathcal{Q}}_1(a_1, b_1, c_1, d_1) = 0$$

$$(\text{resp. } \widetilde{\mathcal{Q}}_2(a_2, b_2, c_2, d_2) = 0)$$

of

$$\mathfrak{E}_{2,0}(u,v)$$

using elimination techniques in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$  (resp.  $a_2, b_2, c_2, d_2$ ) and can find the classes of the algebraic Enneper minimal surface (we have 2 normals and then have 2 classes).  $(n_1)_{2,0}(r, \theta)$  is as follows:

$$(n_1)_{2,0}(r, \theta) = \frac{1}{\sqrt{2(r^4 + 1)}} \begin{pmatrix} -\sin(2\theta) \\ r^2 + \cos(2\theta) \\ -\sin(2\theta) \\ -r^2 + \cos(2\theta) \end{pmatrix}$$

$$= \begin{pmatrix} X_1(r, \theta) \\ Y_1(r, \theta) \\ Z_1(r, \theta) \\ W_1(r, \theta) \end{pmatrix},$$

and  $(n_1)_{2,0}(u, v)$  is as follows:

$$\frac{1}{(u^2 + v^2) \sqrt{2((u^2 + v^2)^2 + 1)}} \begin{pmatrix} -2uv \\ (u^2 + v^2)^2 + (u^2 - v^2) \\ -2uv \\ (u^2 - v^2) - (u^2 + v^2)^2 \end{pmatrix}$$

$$= \begin{pmatrix} X_1(u, v) \\ Y_1(u, v) \\ Z_1(u, v) \\ W_1(u, v) \end{pmatrix}.$$

Using  $xX_1 + yY_1 + zZ_1 + wW_1 + P_1 = 0$ , we get

$$P_1 = \frac{2\sqrt{2}v(u^2 + v^2)}{3\sqrt{(u^2 + v^2)^2 + 1}},$$

and then

$$a_1 = X_1/P_1 = -\frac{3u}{2(u^2 + v^2)^2},$$

$$b_1 = Y_1/P_1 = \frac{3((u^2 + v^2)^2 + u^2 - v^2)}{4v(u^2 + v^2)^2},$$

$$c_1 = Z_1/P_1 = -\frac{3u}{2(u^2 + v^2)^2},$$

$$d_1 = W_1/P_1 = -\frac{3((u^2 + v^2)^2 + v^2 - u^2)}{4v(u^2 + v^2)^2}.$$

Hence, using  $E_{2,0}(u, v)$  and  $(n_1)_{2,0}(u, v)$ , we get the first parametric eq. of Enneper type surface

$$\tilde{\mathfrak{E}}_{2,0}(u, v)$$

in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$  as follows:

$$\tilde{\mathfrak{E}}_{2,0}(u, v) = \frac{3}{4v(u^2 + v^2)^2} \begin{pmatrix} -2uv \\ (u^2 + v^2)^2 + u^2 - v^2 \\ -2uv \\ (u^2 + v^2)^2 + v^2 - u^2 \end{pmatrix}$$

$$= \begin{pmatrix} a_1(u, v) \\ b_1(u, v) \\ c_1(u, v) \\ d_1(u, v) \end{pmatrix}.$$

Then we have implicit eq.

$$\tilde{Q}_1(a_1, b_1, c_1, d_1) = 0$$

of the first surface

$$\tilde{\mathfrak{E}}_{2,0}(u, v)$$

using elimination techniques in the inhomogeneous tangential coordinates  $a_1, b_1, c_1, d_1$ , as follows:

$$\begin{aligned} \tilde{Q}_1(a_1, b_1, c_1, d_1) = & 16a_1^2b_1^6 - 96a_1^2b_1^5d_1 + 240a_1^2b_1^4d_1^2 \\ & - 320a_1^2b_1^3c_1^3 + 240a_1^2b_1^2d_1^4 - 96a_1^2b_1d_1^5 + 16a_1^2d_1^6 \\ & - 144a_1^2b_1^4 + 288a_1^2b_1^3d_1 - 288a_1^2b_1d_1^3 + 144a_1^2d_1^4 - 36b_1^6 \\ & + 108b_1^4d_1^2 - 108b_1^2d_1^4 + 36d_1^6 - 1296a_1^4 - 648a_1^2b_1^2 \\ & - 1296a_1^2b_1d_1 - 648a_1^2d_1^2 - 81b_1^4 - 324b_1^3d_1 - 486b_1^2d_1^2 \\ & - 324b_1d_1^3 - 81d_1^4. \end{aligned}$$

So,

$$class(\tilde{\mathfrak{E}}_{2,0}) = 8.$$

$$(n_2)_{2,0}(r, \theta) = \frac{1}{\sqrt{2r^4(r^4 + 1)}} \begin{pmatrix} r^4 - r^2 \cos(2\theta) \\ -r^2 \sin(2\theta) \\ -r^4 - r^2 \cos(2\theta) \\ -r^2 \sin(2\theta) \end{pmatrix}$$

$$= \begin{pmatrix} X_2(r, \theta) \\ Y_2(r, \theta) \\ Z_2(r, \theta) \\ W_2(r, \theta) \end{pmatrix},$$

and  $(n_2)_{2,0}(u, v)$ :

$$\frac{1}{(u^2 + v^2) \sqrt{2((u^2 + v^2)^2 + 1)}} \begin{pmatrix} (u^2 + v^2)^2 + v^2 - u^2 \\ -2uv \\ -(u^2 + v^2)^2 + v^2 - u^2 \\ -2uv \end{pmatrix}$$

$$= \begin{pmatrix} X_2(u, v) \\ Y_2(u, v) \\ Z_2(u, v) \\ W_2(u, v) \end{pmatrix}.$$

Using  $E_{2,0}(u, v)$  and  $(n_2)_{2,0}(u, v)$ , we get

$$P_2 = -\frac{2\sqrt{2}u(u^2 + v^2)}{3\sqrt{(u^2 + v^2)^2 + 1}}.$$

Hence, we obtain the second surface:

$$\widetilde{\mathfrak{E}}_{2,0}(u, v) = \frac{3}{4v(u^2 + v^2)^2} \begin{pmatrix} -[(u^2 + v^2)^2 + v^2 - u^2] \\ 2uv \\ -[(u^2 + v^2)^2 + u^2 - v^2] \\ 2uv \end{pmatrix}$$

$$= \begin{pmatrix} a_2(u, v) \\ b_2(u, v) \\ c_2(u, v) \\ d_2(u, v) \end{pmatrix}.$$

$$\widetilde{Q}_2(a_2, b_2, c_2, d_2) = 0$$

of the second surface

$$\widetilde{\mathfrak{E}}_{2,0}(u, v)$$

using elimination techniques in the inhomogeneous tangential coordinates  $a_2, b_2, c_2, d_2$  as follows:

$$\begin{aligned} \widetilde{Q}_2(a_2, b_2, c_2, d_2) &= 16a_2^6b_2^2 - 96a_2^5b_2^2c_2 + 240a_2^4b_2^2c_2^2 \\ &- 320a_2^3b_2^2c_2^3 + 240a_2^2b_2^2c_2^4 - 96a_2b_2^2c_2^5 + 16b_2^2c_2^6 \\ &- 36a_2^6 - 144a_2^4b_2^2 + 108a_2^4c_2^2 + 288a_2^3b_2^2c_2 - 108a_2^2c_2^4 \\ &- 288a_2b_2^2c_2^3 + 144b_2^2c_2^4 + 36c_2^6 - 81a_2^4 - 324a_2^3c_2 \\ &- 648a_2^2b_2^2 - 486a_2^2c_2^2 - 1296a_2b_2^2c_2 - 324a_2c_2^3 \\ &- 1296b_2^4 - 648b_2^2c_2^2 - 81c_2^4. \end{aligned}$$

Then we have

$$\text{class}(\widetilde{\mathfrak{E}}_{2,0}) = 8.$$

## 5 References

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