

Some Prešić Type Results in b -Dislocated Metric Spaces

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ABSTRACT. In this paper, we obtain a Prešić type common fixed point theorem for four maps in b -dislocated metric spaces. We also present one example to illustrate our main theorem. Further, we obtain two more corollaries.

Keywords: b -Dislocated metric spaces, Jointly $2k$ -weakly compatible pairs, Prešić type theorem.

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1. INTRODUCTION AND PRELIMINARIES

There are several generalizations of the Banach contraction principle in literature on fixed point theory. Recently, very interesting results regarding fixed point are presented in the papers ([3, 4, 5, 7]). One of the generalization is a famous Prešić type fixed point theorem. There are a lot of generalizations of mentioned theorem (more on this topic see [1]-[2], [7]-[15]). Hitzler and Seda [6] introduced the concept of dislocated metric spaces (metric like spaces in [5], [15]) and established a fixed point theorem in complete dislocated metric spaces to generalize the celebrated Banach contraction principle. Recently Hussain et al. [7] introduced the definition of b -dislocated metric spaces to generalize the dislocated metric spaces introduced by [6] and proved two common fixed point theorems for four self mappings.

In this paper we have proved Prešić type common fixed point theorem for four mappings in b -dislocated metric spaces. One numerical example is also presented to illustrate our main theorem. We also obtained two corollaries for three and two maps in b -dislocated metric spaces.

Now we give some known definitions, lemmas and theorems which are needful for further discussion. Throughout this paper, N denotes the set of all positive integers.

Prešić [10] generalized the Banach contraction principle as follows.

Theorem 1.1. [10] *Let (X, d) be a complete metric space, k be a positive integer and $T : X^k \rightarrow X$ be a mapping satisfying*

$$(1.1) \quad d(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1})) \leq \sum_{i=1}^k q_i d(x_i, x_{i+1}),$$

for all $x_1, x_2, \dots, x_{k+1} \in X$, where $q_i \geq 0$ and $\sum_{i=1}^k q_i < 1$. Then there exists a unique point $x \in X$ such that $T(x, x, \dots, x) = x$. Moreover, if x_1, x_2, \dots, x_k are arbitrary points in X and for

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$n \in \mathbb{N}$, $x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1})$, then the sequence $\{x_n\}$ is convergent and $\lim_{n \rightarrow \infty} x_n = T(\lim_{n \rightarrow \infty} x_n, \lim_{n \rightarrow \infty} x_n, \dots, \lim_{n \rightarrow \infty} x_n)$.

Inspired by the Theorem 1.1, Ćirić and Prešić [8] proved the following theorem.

Theorem 1.2. [8] Let (X, d) be a complete metric space, k a positive integer and $T : X^k \rightarrow X$ be a mapping satisfying

$$(1.2) \quad d(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1})) \leq \lambda \max\{d(x_i, x_{i+1}) : 1 \leq i \leq k\}$$

for all $x_1, x_2, \dots, x_k, x_{k+1}$ in X , and $\lambda \in (0, 1)$. Then there exists a point $x \in X$ such that $x = T(x, x, \dots, x)$.

Moreover, if x_1, x_2, \dots, x_k are arbitrary points in X and for $n \in \mathbb{N}$, $x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1})$, then the sequence $\{x_n\}$ is convergent and $\lim_{n \rightarrow \infty} x_n = T(\lim_{n \rightarrow \infty} x_n, \lim_{n \rightarrow \infty} x_n, \dots, \lim_{n \rightarrow \infty} x_n)$. If in addition, we suppose that on diagonal $\Delta \subset X^k$, $d(T(u, u, \dots, u), T(v, v, \dots, v)) < d(u, v)$ holds for $u, v \in X$ with $u \neq v$, then x is the unique fixed point satisfying $x = T(x, x, \dots, x)$.

Later Rao et al. [11, 12] obtained some Prešić fixed point theorems for two and three maps in metric spaces.

Definition 1.1. Let X be a nonempty set, k a positive integer and $T : X^{2k} \rightarrow X$ and $f : X \rightarrow X$. The pair (f, T) is said to be $2k$ -weakly compatible if $f(T(x, x, \dots, x)) = T(fx, fx, \dots, fx)$ whenever there exists $x \in X$ such that $fx = T(x, x, \dots, x)$

Actually Rao et al. [11] obtained the following.

Theorem 1.3. Let (X, d) be a metric space and k be any positive integer. Let $S, T : X^{2k} \rightarrow X$ and $f : X \rightarrow X$ be mappings satisfying

$$(1) \quad d(S(x_1, x_2, \dots, x_{2k}), T(x_2, x_3, \dots, x_{2k+1})) \leq \lambda \max\{d(fx_i, fx_{i+1}) : 1 \leq i \leq 2k\}$$

for all $x_1, x_2, \dots, x_{2k}, x_{2k+1} \in X$, where $\lambda \in (0, 1)$.

$$(2) \quad d(S(u, u, \dots, u), T(v, v, \dots, v)) < d(fu, fv) \text{ for all } u, v \in X \text{ with } u \neq v$$

(3) Suppose that $f(X)$ is complete and either (f, S) or (f, T) is $2k$ -weakly compatible pair.

Then there exists a unique point $p \in X$ such that $p = fp = S(p, p, \dots, p, p) = T(p, p, \dots, p, p)$.

Hussain et al. [7] introduced b -dislocated metric spaces as follows.

Definition 1.2. Let X be a non empty set. A mapping $b_d : X \times X \rightarrow [0, \infty)$ is called a b -dislocated metric (or simply b_d -metric) if the following conditions hold for any $x, y, z \in X$ and $s \geq 1$:

$$(b_{d1}) : \text{If } b_d(x, y) = 0 \text{ then } x = y,$$

$$(b_{d2}) : b_d(x, y) = b_d(y, x),$$

$$(b_{d3}) : b_d(x, y) \leq s[b_d(x, z) + b_d(z, y)].$$

The pair (X, b_d) is called a b -dislocated metric space or b_d -metric space.

Definition 1.3. [7]

- (i) A sequence $\{x_n\}$ in b -dislocated metric space (X, b_d) converges with respect to b_d if there exists $x \in X$ such that $b_d(x_n, x)$ converges to 0 as $n \rightarrow \infty$. In this case, x is called the limit of $\{x_n\}$ and we write $x_n \rightarrow x$.

- (ii) A sequence $\{x_n\}$ in a b -dislocated metric space (X, b_d) is called a b_d -Cauchy sequence if given $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $b_d(x_m, x_n) < \varepsilon$ for all $n, m \geq n_0$ or $\lim_{n, m \rightarrow \infty} b_d(x_m, x_n) = 0$.
- (iii) A b -dislocated metric (X, b_d) is called b_d -complete if every b_d -Cauchy sequence in X is b_d -convergent.

Lemma 1.1. [7] Let (X, b_d) be a b -dislocated metric space with $s \geq 1$. Suppose that $\{x_n\}$ and $\{y_n\}$ are b_d -convergent to x, y respectively. Then we have

$$\frac{1}{s^2} b_d(x, y) \leq \liminf_{n \rightarrow \infty} b_d(x_n, y_n) \leq \limsup_{n \rightarrow \infty} b_d(x_n, y_n) \leq s^2 b_d(x, y),$$

and

$$\frac{1}{s} b_d(x, z) \leq \liminf_{n \rightarrow \infty} b_d(x_n, z) \leq \limsup_{n \rightarrow \infty} b_d(x_n, z) \leq s b_d(x, z)$$

for all $z \in X$.

2. MAIN RESULT

We introduce the definition of jointly $2k$ -weakly compatible pairs as follows.

Definition 2.4. Let X be a nonempty set, k a positive integer and $S, T : X^{2k} \rightarrow X$ and $f, g : X \rightarrow X$. The pairs (f, S) and (g, T) are said to be jointly $2k$ -weakly compatible if

$$f(S(x, x, \dots, x)) = S(fx, fx, \dots, fx)$$

and

$$g(T(x, x, \dots, x)) = T(gx, gx, \dots, gx)$$

whenever there exists $x \in X$ such that $fx = S(x, x, \dots, x)$ and $gx = T(x, x, \dots, x)$.

Now we give our main result. The contractive condition in the next theorem is similar with conditions in [2, 7, 10, 13].

Theorem 2.4. Let (X, b_d) be a b_d -complete b -dislocated metric space with $s \geq 1$ and k be any positive integer. Let $S, T : X^{2k} \rightarrow X$ and $f, g : X \rightarrow X$ be mappings satisfying

$$(2.3) \quad S(X^{2k}) \subseteq g(X), T(X^{2k}) \subseteq f(X),$$

$$(2.4)$$

$$b_d(S(x_1, x_2, \dots, x_{2k}), T(y_1, y_2, \dots, y_{2k})) \leq \lambda \max \left\{ \begin{array}{l} b_d(gx_1, fy_1), b_d(fx_2, gy_2), \\ b_d(gx_3, fy_3), b_d(fx_4, gy_4), \\ \dots\dots\dots \\ b_d(gx_{2k-1}, fy_{2k-1}), b_d(fx_{2k}, gy_{2k}) \end{array} \right\}$$

for all $x_1, x_2, \dots, x_{2k}, y_1, y_2, \dots, y_{2k} \in X$, where $\lambda \in (0, \frac{1}{s^{2k}})$.

$$(2.5) \quad (f, S) \text{ and } (g, T) \text{ are jointly } 2k - \text{weakly compatible pairs,}$$

$$(2.6) \quad \text{Assume that there exists } u \in X \text{ such that } fu = gu \text{ whenever there is sequence } \{y_{2k+n}\}_{n=1}^\infty \in X \text{ with } \lim_{n \rightarrow \infty} \lim_{n \rightarrow \infty} y_{2k+n} = fu = gu = z \in X.$$

Then z is the unique point in X such that $z = fz = gz = S(z, z, \dots, z, z) = T(z, z, \dots, z, z)$.

Proof. Suppose x_1, x_2, \dots, x_{2k} are arbitrary points in X . From (2.3), we can define

$$y_{2k+2n-1} = S(x_{2n-1}, x_{2n}, \dots, x_{2k+2n-2}) = gx_{2k+2n-1},$$

and

$$y_{2k+2n} = T(x_{2n}, x_{2n+1}, \dots, x_{2k+2n-1}) = fx_{2k+2n}, \quad n = 1, 2, \dots$$

Let

$$\alpha_{2n} = b_d(fx_{2n}, gx_{2n+1}),$$

and

$$\alpha_{2n-1} = b_d(gx_{2n-1}, fx_{2n}) \quad n = 1, 2, \dots$$

Write $\theta = \lambda^{\frac{1}{2k}}$ and $\mu = \max\{\frac{\alpha_1}{\theta}, \frac{\alpha_2}{(\theta)^2}, \dots, \frac{\alpha_{2k}}{(\theta)^{2k}}\}$.

Then $0 < \theta < 1$ and by the selection of μ , we have

$$(2.7) \quad \alpha_n \leq \mu \cdot (\theta)^n, \quad n = 1, 2, \dots, 2k$$

Consider

$$(2.8) \quad \alpha_{2k+1} = b_d(gx_{2k+1}, fx_{2k+2}) = b_d(S(x_1, x_2, \dots, x_{2k-1}, x_{2k}), T(x_2, x_3, \dots, x_{2k}, x_{2k+1}))$$

$$\begin{aligned} &\leq \lambda \max \left\{ \begin{array}{l} b_d(gx_1, fx_2), b_d(fx_2, gx_3), \\ b_d(gx_3, fx_4), b_d(fx_4, gx_5), \\ \dots\dots\dots \\ b_d(gx_{2k-1}, fx_{2k}), b_d(fx_{2k}, gx_{2k+1}) \end{array} \right\} \\ &\leq \lambda \max\{\alpha_1, \alpha_2, \alpha_3, \alpha_4, \dots, \alpha_{2k-1}, \alpha_{2k}\} \\ &\leq \lambda \max\{\mu \cdot \theta, \mu \cdot (\theta)^2, \dots, \mu \cdot (\theta)^{2k}\}, \\ &= \lambda\mu \cdot \theta = \mu \cdot \theta \cdot (\theta)^{2k} = \mu \cdot (\theta)^{2k+1}. \end{aligned}$$

using (2.7),
and

$$(2.9) \quad \begin{aligned} \alpha_{2k+2} &= b_d(fx_{2k+2}, gx_{2k+3}) \\ &= b_d(T(x_2, x_3, \dots, x_{2k}, x_{2k+1}), S(x_3, x_4, \dots, x_{2k+1}, x_{2k+2})) \\ &= b_d(S(x_3, x_4, \dots, x_{2k+1}, x_{2k+2}), T(x_2, x_3, \dots, x_{2k}, x_{2k+1})) \end{aligned}$$

$$\begin{aligned} &\leq \lambda \max \left\{ \begin{array}{l} b_d(gx_3, fx_4), b_d(fx_4, gx_5), \\ b_d(gx_5, fx_6), b_d(fx_6, gx_7), \\ \dots\dots\dots \\ b_d(gx_{2k+1}, fx_{2k}), b_d(fx_{2k+2}, gx_{2k+1}) \end{array} \right\} \\ &\leq \lambda \max\{\alpha_2, \alpha_3, \alpha_4, \alpha_5, \dots, \alpha_{2k}, \alpha_{2k+1}\} \\ &\leq \lambda \max\{\mu \cdot (\theta)^2, \mu \cdot (\theta)^3, \dots, \mu \cdot (\theta)^{2k}, \mu \cdot (\theta)^{2k+1}\}, \\ &= \lambda\mu \cdot (\theta)^2 = \mu \cdot (\theta)^2(\theta)^{2k} = \mu \cdot (\theta)^{2k+2}, \end{aligned}$$

using (2.7) and (2.8).

Continuing in this way, we get

$$(2.10) \quad \alpha_n \leq \mu \cdot (\theta)^n,$$

Suppose there exists $z' \in X$ such that

$$z' = fz' = gz' = S(z', z', \dots, z', z') = T(z', z', \dots, z', z').$$

Then from (2.4), we have

$$\begin{aligned} b_d(z, z') &= b_d(S(z, z, \dots, z, z), T(z', z', \dots, z', z')) \\ &\leq \lambda \max \left\{ \begin{array}{l} b_d(gz, fz'), b_d(fz, gz'), \\ \dots\dots\dots \\ b_d(gz, fz'), b_d(fz, gz') \end{array} \right\} \\ &\leq \lambda b_d(z, z'). \end{aligned}$$

This implies that $z' = z$.

Thus z is the unique point in X satisfying (2.22). □

Now we give an example to illustrate our main Theorem 2.4.

Example 2.1. Let $X = [0, 1]$ and $b_d(x, y) = |x + y|^2$ and $k = 1$.

Define $S(x, y) = \frac{3x^2+2y}{\sqrt{4608}}$, $T(x, y) = \frac{2x+3y^2}{\sqrt{4608}}$, $fx = \frac{x}{6}$ and $gx = \frac{x^2}{4}$ for all $x, y \in X$. Then clearly $s = 2$. Then for all $x_1, x_2, y_1, y_2 \in X$, we have

$$\begin{aligned} b_d(S(x_1, x_2), T(y_1, y_2)) &= \left| \frac{3x_1^2 + 2x_2}{\sqrt{4608}} + \frac{2y_1 + 3y_2^2}{\sqrt{4608}} \right|^2 \\ &= \left(\frac{x_1^2}{16\sqrt{2}} + \frac{x_2}{24\sqrt{2}} + \frac{y_1}{24\sqrt{2}} + \frac{y_2^2}{16\sqrt{2}} \right)^2 \\ &= \frac{1}{2} \left(\left(\frac{x_1^2}{16} + \frac{y_1}{24} \right) + \left(\frac{x_2}{24} + \frac{y_2^2}{16} \right) \right)^2 \\ &= \frac{1}{32} \left(\left(\frac{x_1^2}{4} + \frac{y_1}{6} \right) + \left(\frac{x_2}{6} + \frac{y_2^2}{4} \right) \right)^2 \\ &= \frac{1}{8} \left(\frac{\left(\frac{x_1^2}{4} + \frac{y_1}{6} \right) + \left(\frac{x_2}{6} + \frac{y_2^2}{4} \right)}{2} \right)^2 \\ &\leq \frac{1}{8} \left(\max \left\{ \frac{x_1^2}{4} + \frac{y_1}{6}, \frac{x_2}{6} + \frac{y_2^2}{4} \right\} \right)^2 \\ &= \frac{1}{8} \max \left\{ \left(\frac{x_1^2}{4} + \frac{y_1}{6} \right)^2, \left(\frac{x_2}{6} + \frac{y_2^2}{6} \right)^2 \right\} \end{aligned}$$

where used the following:

$$\frac{a + b}{2} \leq \max\{a, b\}, \quad (\max(a, b))^2 = \max\{a^2, b^2\},$$

for non-negative a and b . Here $\lambda = \frac{1}{8} \in (0, \frac{1}{4}) = (0, \frac{1}{2^2}) = (0, \frac{1}{s^{2k}})$.

One can easily verify the remaining conditions of Theorem 2.4. Clearly 0 is the unique point in X such that $f0 = 0 = g0 = S(0, 0) = T(0, 0)$.

Corollary 2.1. Let (X, b_d) be a b_d -complete b -dislocated metric space with $s \geq 1$ and k be any positive integer. Let $S, T : X^{2k} \rightarrow X$ and $f : X \rightarrow X$ be mappings satisfying

$$(2.23) \quad S(X^{2k}) \subseteq g(X), T(X^{2k}) \subseteq f(X),$$

$$(2.24) \quad b_d(S(x_1, x_2, \dots, x_{2k}), T(y_1, y_2, \dots, y_{2k})) \leq \lambda \max\{b_d(fx_i, fy_i) : 1 \leq i \leq 2k\}$$

for all $x_1, x_2, \dots, x_{2k}, y_1, y_2, \dots, y_{2k} \in X$, where $\lambda \in (0, \frac{1}{s^{2k}})$

$$(2.25) \quad f(X) \text{ is } ab_d\text{-complete subspace of } X$$

$$(2.26) \quad (f, S) \text{ or } (f, T) \text{ is } 2k\text{-dweakly compatible pair.}$$

Then there exists a unique point $u \in X$ such that $u = fu = S(u, u, \dots, u, u) = T(u, u, \dots, u, u)$.

Corollary 2.2. Let (X, b_d) be a b_d -complete b -dislocated metric space with $s \geq 1$ and k be any positive integer. Let $S, T : X^{2k} \rightarrow X$ be mappings satisfying

$$(2.27) \quad b_d(S(x_1, x_2, \dots, x_{2k}), T(y_1, y_2, \dots, y_{2k})) \leq \lambda \max\{b_d(x_i, y_i) : 1 \leq i \leq 2k\}$$

for all $x_1, x_2, \dots, x_{2k}, y_1, y_2, \dots, y_{2k} \in X$, where $\lambda \in (0, \frac{1}{s^{2k}})$

Then there exists a unique point $u \in X$ such that $u = S(u, u, \dots, u, u) = T(u, u, \dots, u, u)$.

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Competing interests

Authors declare that they have no any conflict of interest regarding the publication of this paper.

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