



The Existence of a Global Attractor for one Fourth Order Hyperbolic Equation with Memory Operator

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Article Info

Keywords: Bounded absorbing set, Memory operator, Minimal global attractor, Semilinear hyperbolic equation

2010 AMS: 35L30, 35L76

Received: 26 April 2018

Accepted: 29 November 2018

Available online: 20 March 2019

Abstract

In this work, the initial-boundary value problem for one fourth order semilinear hyperbolic equation with memory operator is considered (here the memory operator is under the operator of differentiation with respect to time variable). The asymptotic compactness of semigroup generated by this problem is proved. The existence of a minimal global attractor for this problem is also proved.

1. Introduction

Nonlinear equations with memory operator, especially the equations with hysteresis have great importance among the partial differential equations. Nonlinear relations of hysteresis type appear in ferromagnetism, ferroelectricity, superconductivity, plasticity, friction, etc. The research of solutions of partial differential equations with hysteresis nonlinearities is a nontrivial problem. Such equations, when hysteresis operator is under the operator of differentiation with respect to time variable, have special difficulties.

The research of asymptotic behaviour of a dynamic system, which is originated by the corresponding initial-boundary value problem, has a special significance. For the equations with hysteresis nonlinearities, these questions have not been almost investigated. In this field, only particular cases were considered. For instance, the asymptotic character of solutions of the initial-boundary value problem for one quasilinear parabolic equation, in which the hysteresis operator is under the operator of differentiation with respect to time variable, was investigated in [1]. The similar results were obtained in [2], [3]. In [4], [5], [6] the corresponding problems were researched by the application of the results of nonlinear semigroup theory.

In this work, the asymptotic result for solutions of the initial-boundary value problem for one semilinear hyperbolic equation with memory operator is obtained and the existence of a minimal global attractor for this problem is proved.

2. Problem statement and preliminaries

Here we use the concepts and notations which were introduced in [7].

Let $\Omega \subset \mathbb{R}^N$ ($N \geq 1$) be a bounded, connected set with a smooth boundary Γ . We consider the following problem:

$$\frac{\partial^2 u}{\partial t^2} + \frac{\partial}{\partial t} [u + F(u)] + \Delta^2 u + |u|^p u = h \text{ in } Q = \Omega \times (0, T), \quad (2.1)$$

$$u = 0, \Delta u = 0, (x, t) \in \Gamma \times [0, T], \quad (2.2)$$

$$[u + F(u)]|_{t=0} = u^{(0)} + w^{(0)}, \frac{\partial u}{\partial t} \Big|_{t=0} = u^{(1)} \text{ in } \Omega, \quad (2.3)$$

where $p > 0$ and F is a memory operator (at any instant t , $F(u)$ may depend not only on $u(t)$, but also on the previous evolution of u), which acts from $M(\Omega; C^0([0, T]))$ to $M(\Omega; C^0([0, T]))$. Here $M(\Omega; C^0([0, T]))$ is a space of strongly measurable functions $\Omega \rightarrow C^0([0, T])$. We assume that the operator F is applied at each point $x \in \Omega$ independently: the output $[F(u(x, \cdot))](t)$ depends on $u(x, \cdot)|_{[0, t]}$, but not on $u(y, \cdot)|_{[0, t]}$ for any $y \neq x$ (for more details see [7]).

We assume that

$$\begin{cases} \text{for } \forall v_1, v_2 \in M(\Omega; C^0([0, T])) \text{ and for } \forall t \in [0, T], \text{ if } v_1 = v_2 \\ \text{in } [0, t], \text{ a.e. in } \Omega, \text{ then } [F(v_1)](\cdot, t) = [F(v_2)](\cdot, t) \text{ a.e. in } \Omega; \end{cases} \tag{2.4}$$

$$\begin{cases} \forall \{v_n \in M(\Omega; C^0([0, T]))\}_{n \in \mathbb{N}}, \text{ if } v_n \rightarrow v \text{ uniformly in } [0, T] \\ \text{a.e. in } \Omega, \text{ then } F(v_n) \rightarrow F(v) \text{ uniformly in } [0, T] \text{ a.e. in } \Omega; \end{cases} \tag{2.5}$$

$$\begin{cases} \exists L > 0, \exists g \in L^2(\Omega) : \forall v \in M(\Omega; C^0([0, T])) \\ \|[F(v)](x, \cdot)\|_{C^0([0, T])} \leq L \|v(x, \cdot)\|_{C^0([0, T])} + g(x), \text{ a.e. in } \Omega; \end{cases} \tag{2.6}$$

$$\begin{cases} \forall v \in M(\Omega; C^0([0, T])), \forall [t_1, t_2] \subset [0, T], \\ \text{if } v(x, \cdot) \text{ is affine in } [t_1, t_2] \text{ a.e. in } \Omega, \text{ then} \\ \{[F(v)](x, t_2) - [F(v)](x, t_1)\} [v(x, t_2) - v(x, t_1)] \geq 0, \text{ a.e. in } \Omega; \end{cases} \tag{2.7}$$

$$\begin{cases} \exists 0 < L_1 < 1, \forall v \in M(\Omega; C^0([0, T])), \forall [t_1, t_2] \subset [0, T], \\ \text{if } v(x, \cdot) \text{ is affine in } [t_1, t_2] \text{ a.e. in } \Omega, \text{ then} \\ |[F(v)](x, t_2) - [F(v)](x, t_1)| \leq L_1 |v(x, t_2) - v(x, t_1)| \text{ a.e. in } \Omega. \end{cases} \tag{2.8}$$

$$\begin{cases} \exists 0 < L_2 < 1, \forall v \in M(\Omega; C^0([0, T])), \forall [t_1, t_2] \subset [0, T], \\ \text{if } v(x, \cdot) \text{ is affine in } [t_1, t_2] \text{ a.e. in } \Omega, \text{ then} \\ |[F(u)](x, t_2) - [F(v)](x, t_2) - ([F(u)](x, t_1) - [F(v)](x, t_1))| \leq \\ \leq L_2 |u(x, t_2) - v(x, t_2) - (u(x, t_1) - v(x, t_1))|. \end{cases} \tag{2.9}$$

Let $V = H_0^2(\Omega) \cap L^{p+2}(\Omega)$ and

$$u^{(0)} \in V, w^{(0)} \in L^2(\Omega), u^{(1)} \in L^2(\Omega), h \in L^2(\Omega). \tag{2.10}$$

Definition 2.1. A function $u \in L^2(0, T; V) \cap H^1(0, T; L^2(\Omega))$ is said to be a solution of problem (2.1)-(2.3) if $F(u) \in L^2(Q)$, and

$$\begin{aligned} & \iint_Q \left\{ -\frac{\partial u}{\partial t} \cdot \frac{\partial v}{\partial t} - [u + F(u)] \frac{\partial v}{\partial t} + \Delta u \cdot \Delta v + |u|^p uv \right\} dxdt = \\ & = \iint_Q hv dxdt + \int_{\Omega} [u^{(0)}(x) + w^{(0)}(x) + u^{(1)}(x)] v(x, 0) dx, \end{aligned}$$

for every $v \in L^2(0, T; V) \cap H^1(0, T; L^2(\Omega))$ ($v(\cdot, T) = 0$ a.e. in Ω).

Well posedness of problem (2.1)-(2.3) without F , was studied by different authors (see, for example [8]). The initial boundary problem for the parabolic equation without the nonlinear term $|u|^p u$ and with Δu was studied in [7].

The following theorems about existence and uniqueness of solutions of problem (2.1)-(2.3) can be proved in the same way as the corresponding theorems from [9].

Theorem 2.2. Assume that (2.4)-(2.8), (2.10) hold. Then problem (2.1)-(2.3) has at least one solution such that

$$u \in W^{1, \infty}(0, T; L^2(\Omega)) \cap L^\infty(0, T; V), \quad F(u) \in H^1(0, T; L^2(\Omega)).$$

Theorem 2.3. Assume that the hypotheses of Theorem 2.2 hold,

$$p \leq \frac{2}{N-2}, N \geq 3 \text{ (} p \text{ is arbitrary and finite when } N=2\text{)} \tag{2.11}$$

and F fulfils the following condition

$$\begin{cases} \forall r > 0, \exists L(r) > 0 : \forall t \in (0, T], \forall v_1, v_2 \in \{u \in L^2(Q_t) : \|u\|_{L^2(Q_t)} \leq r\} : \\ \|F(v_1) - F(v_2)\|_{L^2(Q_t)} \leq L(r) \|v_1 - v_2\|_{L^2(Q_t)}. \end{cases} \tag{2.12}$$

Then problem (2.1)-(2.3) has only one solution.

As an example of an operator which satisfies the mentioned conditions, we can present the Bouc operator (see, for example [10]):

$$[B(u)](t) = \alpha u(t) + \int_0^t f \left(\int_s^t |u'(\tau)| d\tau \right) \varphi(u(s)) u'(s) ds,$$

here α is a positive constant, f and φ are continuous real functions, with f positive and nondecreasing.

The following theorem is obtained from Theorem 2.2 and Theorem 2.3 by the common theory of solvability of linear hyperbolic equations.

Theorem 2.4. Assume that the conditions of Theorem 2.3 hold. Then for arbitrary $T > 0$ problem (2.1)-(2.3) has only one solution $u \in C^1([0, T]; L^2(\Omega)) \cap C([0, T]; H_0^2(\Omega))$.

By the condition (2.11): $V = H_0^2(\Omega) \cap L^{p+2}(\Omega) = H_0^2(\Omega)$. We set $E = H_0^2(\Omega) \times L^2(\Omega) \times L^2(\Omega)$. Then under the conditions of Theorem 2.4, Problems (2.1)-(2.3) generates the semigroup $\{S(t)\}_{t \geq 0}$ in E by the formula:

$$S(t) \left(u^{(0)}, u^{(1)}, w^{(0)} \right) = (u, u_t, w),$$

where u is a unique solution of this problem.

Definition 2.5. (see [11]) A bounded set $B_0 \subset E$ is said to be absorbing if for an arbitrary bounded set $B \subset E$ there exists $t_1(B)$ such that $S(t)B \subset B_0$ for all $t \geq t_1(B)$.

Definition 2.6. (see [11]) Let $\{S(t)\}_{t \geq 0}$ be a semigroup on a metric space (X, d) . A smallest, nonempty, bounded, closed set $A \subset X$ that satisfies

$$\limsup_{t \rightarrow \infty} \inf_{v \in B} \inf_{u \in A} d(S(t)v, u) = 0,$$

for each bounded set $B \subset X$, is called a minimal global attractor of $\{S(t)\}_{t \geq 0}$.

The following theorem about the existence of a bounded absorbing set for Problems (2.1)-(2.3) can be proved in the same way as the corresponding theorem in [12].

Theorem 2.7. Under the conditions (2.4)-(2.12), Problems (2.1)-(2.3) has a bounded absorbing set $B_0 \subset E$.

In this work, we first prove the asymptotic compactness of a semigroup, generated by problem (2.1)-(2.3), and then the basic theorem about the existence of a minimal global attractor for this problem.

Note that, a semigroup $\{S(t)\}_{t \geq 0}$, defined on a metric space (X, d) , is called asymptotically compact, if for arbitrary bounded set $B \subset X$ such, that $\bigcup_{t \geq 0} S(t)B$ is bounded in (X, d) , the sequence $\{S(t_k)v_k\}_{k=1}^\infty$, $t_k \rightarrow \infty$, $v_k \in B$ has a convergent subsequence.

3. Basic Results

Theorem 3.1. Assume that (2.4)-(2.12) hold. Then the semigroup $\{S(t)\}_{t \geq 0}$, generated by problem (2.1)-(2.3), is asymptotically compact in E .

The proof of Theorem 3.1. It suffices to prove that for any bounded set B from E and for arbitrary $\varepsilon > 0$ there exists $T = T(\varepsilon, B)$ such that

$$\limsup_{i \rightarrow \infty} \sup_{q \in \mathbb{N}} \|S(T)\theta_{i+q} - S(T)\theta_i\|_E \leq \varepsilon, \tag{3.1}$$

where $\{\theta_i\}$ is the sequence from B and $\{S(t)\theta_i\}$ converges $*$ -weakly in $L^\infty(0, \infty; E)$.

We prove this by the method of time discretization (see [7]).

For any $m \in \mathbb{N}$, we set $k = \frac{T}{m}$ and:

$$\begin{aligned} u_m^0 &= u^{(0)}, w_m^0 = w^{(0)}, u_m^1 = u^{(0)} + ku^{(1)}, \\ u_m^{-1} &= u^{(0)} - ku^{(1)}, u_m^n(x) = u(x, nk), n = 2, \dots, m, \\ w_m^n(x) &= [F(u_m)](x, nk), n = 1, \dots, m, \text{ a.e. in } \Omega, \end{aligned}$$

$u_m(x, \cdot)$ = linear time interpolate of $u(x, nk)$ for $n = 0, 1, \dots, m$ a.e. in Ω , $w_m(x, \cdot)$ = linear time interpolate of $w(x, nk)$ for $n = 1, \dots, m$ a.e. in Ω .

We will use the techniques used in [13, 14, 15]. We set $\theta_i = \left\{ u_i^{(0)}, u_i^{(1)}, w_i^{(0)} \right\}$, $u_i = S(t)\theta_i$ ($i = 1, 2, \dots$).

We consider the following problems for $l = i, j$ ($i, j = 1, 2, \dots$):

$$\begin{aligned} \frac{u_{lm}^n - 2u_{lm}^{n-1} + u_{lm}^{n-2}}{k^2} + \frac{u_{lm}^n - u_{lm}^{n-1}}{k} + \frac{w_{lm}^n - w_{lm}^{n-1}}{k} + \\ + \Delta^2 u_{lm}^n + |u_{lm}^n|^p u_{lm}^n = h \text{ in } V', n = 1, 2, \dots, m, \end{aligned}$$

$$u_{lm}^0 = u_l^{(0)}, w_{lm}^0 = w_l^{(0)}, u_{lm}^1 = u_l^{(0)} + ku_l^{(1)}, u_{lm}^{-1} = u_l^{(0)} - ku_l^{(1)},$$

and obtain, that

$$\frac{u_{im}^n - u_{jm}^n - 2(u_{im}^{n-1} - u_{jm}^{n-1}) + u_{im}^{n-2} - u_{jm}^{n-2}}{k^2} + \frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} +$$

$$\begin{aligned}
 & + \frac{w_{im}^n - w_{jm}^n - (w_{im}^{n-1} - w_{jm}^{n-1})}{k} + \\
 & + \Delta^2 \left(u_{im}^n - u_{jm}^n \right) + |u_{im}^n|^p u_{im}^n - |u_{jm}^n|^p u_{jm}^n = 0, \text{ in } V', \quad n = 1, 2, \dots, m.
 \end{aligned} \tag{3.2}$$

$$\begin{aligned}
 & u_{im}^0 - u_{jm}^0 = u_i^{(0)} - u_j^{(0)}, \quad w_{im}^0 - w_{jm}^0 = w_i^{(0)} - w_j^{(0)}, \\
 & u_{im}^1 - u_{jm}^1 = u_i^{(0)} - u_j^{(0)} + k \left(u_i^{(1)} - u_j^{(1)} \right), \quad u_{im}^{-1} - u_{jm}^{-1} = u_i^{(0)} - u_j^{(0)} - k \left(u_i^{(1)} - u_j^{(1)} \right).
 \end{aligned} \tag{3.3}$$

By multiplying both sides of equality (3.2) by $u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})$, summing for $n = s, \dots, m$ for arbitrary $s \in \{1, 2, \dots, m\}$, integrating by Ω and using the condition (2.7), we can obtain the following relation:

$$\begin{aligned}
 & E \left(u_{im}^m - u_{jm}^m \right) + \frac{k}{2} (1 - L_1) \sum_{n=s}^m \int_{\Omega} \left(\frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} \right)^2 dx + \\
 & + \sum_{n=s}^m \int_{\Omega} \left(|u_{im}^n|^p u_{im}^n - |u_{jm}^n|^p u_{jm}^n \right) \left(u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1}) \right) dx \leq \\
 & \leq E \left(u_{im}^{s-1} - u_{jm}^{s-1} \right),
 \end{aligned} \tag{3.4}$$

where

$$\begin{aligned}
 E \left(u_{im}^n - u_{jm}^n \right) & = \\
 & = \frac{1}{2} \int_{\Omega} \left| \Delta \left(u_{im}^n - u_{jm}^n \right) \right|^2 dx + \frac{1}{2} \int_{\Omega} \left(\frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} \right)^2 dx.
 \end{aligned}$$

It is evident that for arbitrary $\delta > 0$ there exists $c_2(\delta) > 1$ such, that

$$|u - v|^2 \leq \delta + c_2(\delta) |u - v|^2, \quad \forall u, v \in R.$$

We can obtain the following inequality from (3.4), when $s = 1$:

$$\begin{aligned}
 & k \sum_{n=1}^m \int_{\Omega} \left(\frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} \right)^2 dx \leq \delta T m e s \Omega + C_1 \frac{C_2(\delta)}{1 - L_1} \|B\|_V^2 + \\
 & + \frac{C_2(\delta)}{1 - L_1} \sum_{n=1}^m \int_{\Omega} \left(|u_{im}^n|^p u_{im}^n - |u_{jm}^n|^p u_{jm}^n \right) \left(u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1}) \right) dx, \quad \forall \delta > 0.
 \end{aligned} \tag{3.5}$$

By multiplying both sides of the equality (3.2) by $u_{im}^n - u_{jm}^n$, summing for $n = 1, \dots, m$, integrating by Ω and using the condition (2.7), we have

$$\begin{aligned}
 & -k \left(1 + \frac{L_1^2}{2\nu} \right) \sum_{n=1}^m \int_{\Omega} \left(\frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} \right)^2 dx + \\
 & + \frac{k}{2} \int_{\Omega} \left(\frac{u_{im}^m - u_{jm}^m - (u_{im}^{m-1} - u_{jm}^{m-1})}{k} \right)^2 dx + \\
 & + \frac{k}{2} \int_{\Omega} \left(\frac{u_{im}^0 - u_{jm}^0 - (u_{im}^{-1} - u_{jm}^{-1})}{k} \right)^2 dx + \\
 & + \int_{\Omega} \frac{u_{im}^m - u_{jm}^m - (u_{im}^{m-1} - u_{jm}^{m-1})}{k} \left(u_{im}^m - u_{jm}^m \right) dx - \\
 & - \int_{\Omega} \frac{u_{im}^0 - u_{jm}^0 - (u_{im}^{-1} - u_{jm}^{-1})}{k} \left(u_{im}^0 - u_{jm}^0 \right) dx + \\
 & + \int_{\Omega} \left(\frac{1}{2} \left(u_{im}^m - u_{jm}^m \right)^2 - \frac{1}{2} \left(u_{im}^0 - u_{jm}^0 \right)^2 \right) dx + \\
 & + k \left(1 - \frac{\nu C_2^2}{2} \right) \sum_{n=1}^m \int_{\Omega} \left| \Delta \left(u_{im}^n - u_{jm}^n \right) \right|^2 dx \leq 0,
 \end{aligned} \tag{3.6}$$

By (3.3) and due to the existence of a bounded absorbing set, we have

$$E(u^n(T)) \leq c(\|B\|_E) \text{ for } \forall T \geq 0,$$

where $\|B\|_E = \sup_{v \in B} \|v\|_E$. Then from (3.6), we obtain the following

$$\begin{aligned} & k \left(1 - \frac{vc_\Omega^2}{2} \right) \sum_{n=1}^m \left\| \Delta(u_{im}^n - u_{jm}^n) \right\|^2 \leq \\ & \leq C_3(\|B\|_V) + k \left(1 + \frac{L_1^2}{2v} \right) \sum_{n=1}^m \left\| \frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} \right\|^2. \end{aligned} \tag{3.7}$$

Multiplying (3.5) by v_1 and summing it with (3.7), we have

$$\begin{aligned} & k \sum_{n=1}^m E(u_{im}^n - u_{jm}^n) \leq \frac{v_1 \delta T m e s \Omega}{2v_2} + \frac{\tilde{C}(\|B\|_V, \delta)}{2v_2} + \\ & + k \frac{v_1 C_2(\delta)}{2v_2(1-L_1)} \sum_{n=1}^m \int_{\Omega} \left(|u_{jm}^n|^p u_{jm}^n - |u_{im}^n|^p u_{im}^n \right) \frac{u_{im}^n - u_{jm}^n - (u_{im}^{n-1} - u_{jm}^{n-1})}{k} dx, \forall \delta > 0, \end{aligned} \tag{3.8}$$

where

$$v_2 = \min \left\{ v_1 - 1 - \frac{L_1^2}{2v}, 1 - \frac{vc_\Omega^2}{2} \right\},$$

and v, v_1 are chosen such that

$$1 - \frac{vc_\Omega^2}{2} > 0, v_1 - 1 - \frac{L_1^2}{2v} > 0.$$

Summing (3.4) for $s = 1, \dots, m$, using the condition $L_1 < 1$, (3.8) and lemma 2.2 from [15], we can obtain that

$$\limsup_{i \rightarrow \infty} \limsup_{j \rightarrow \infty} E(u_{im}^m - u_{jm}^m) \leq \frac{v_1 m e s \Omega}{2v_2} \delta + \frac{C(\|B\|_V, \delta)}{2v_2 T}, \forall \delta > 0$$

and consequently,

$$\limsup_{i \rightarrow \infty} \sup_{q \in \mathbb{N}} E(u_{(i+q)m}^m - u_{im}^m) \leq \frac{2v_1 m e s \Omega}{v_2} \delta + \frac{2C(\|B\|_V, \delta)}{v_2 T}, \forall \delta > 0, \forall T > 0.$$

From the last relation we obtain, that for arbitrary $\varepsilon > 0$ there exists $T = T(\varepsilon, B)$ and $\delta > 0$ such that

$$\limsup_{i \rightarrow \infty} \sup_{q \in \mathbb{N}} \left[\frac{1}{2} \left\| \Delta(u_{(i+q)m}^m - u_{im}^m) \right\|^2 + \frac{1}{2} \left\| \frac{u_{(i+q)m}^m - u_{im}^m - (u_{(i+q)m}^{m-1} - u_{im}^{m-1})}{k} \right\|^2 \right] \leq \varepsilon,$$

whence defining

$$\tilde{u}_m(x, t) = u_{im}^n(x), \text{ if } (n-1)k < t \leq nk, n = 1, 2, \dots, m; \text{ a.e. in } \Omega$$

and defining \tilde{w}_m, \tilde{f}_m similarly, we obtain that

$$\limsup_{i \rightarrow \infty} \sup_{q \in \mathbb{N}} \left[\frac{1}{2} \left\| \Delta(\tilde{u}_{(i+q)m} - \tilde{u}_{im}) \right\|^2 + \frac{1}{2} \left\| (u_{(i+q)m} - u_{im})_t \right\|^2 \right] \leq \varepsilon. \tag{3.9}$$

Since (see, [9])

$$u_m \rightarrow u \text{ weakly star in } H^1(0, T; L^2(\Omega)) \cap L^\infty(0, T; H_0^1(\Omega)),$$

$$\tilde{u}_m \rightarrow u \text{ weakly star in } L^\infty(0, T; H_0^1(\Omega)),$$

as $m \rightarrow \infty$, then passing to the limit as $m \rightarrow \infty$ in the inequality (3.9), we obtain (3.1).

Theorem 3.1 is proved.

Theorem 3.2. (the basic theorem) Assume that (2.4)-(2.12) hold. Then Problems (2.1)-(2.3) has a minimal global attractor which is invariant and compact.

The proof of Theorem 3.2. According to Theorem 2.7, under the conditions (2.4)-(2.12), problem (2.1)-(2.3) has a bounded absorbing set and by Theorem 3.1, the semigroup $\{S(t)\}_{t \geq 0}$, generated by this problem is asymptotically compact. Therefore according to Theorem 3.2 from [11], the problem (2.1)-(2.3) has a minimal global attractor, which is invariant and compact.

Theorem 3.2 is proved.

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