



## Basis properties of root functions of a regular fourth order boundary value problem

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### Abstract

In this paper, we consider the following boundary value problem

$$\begin{aligned} y^{(4)} + q(x)y &= \lambda y, & 0 < x < 1, \\ y'''(1) - (-1)^\sigma y'''(0) + \alpha y(0) &= 0, \\ y^{(s)}(1) - (-1)^\sigma y^{(s)}(0) &= 0, & s = \overline{0, 2}, \end{aligned}$$

where  $\lambda$  is a spectral parameter,  $q(x) \in L_1(0, 1)$  is complex-valued function and  $\sigma = 0, 1$ . The boundary conditions of this problem are regular but not strongly regular. Asymptotic formulae for eigenvalues and eigenfunctions of the considered boundary value problem are established. When  $\alpha \neq 0$ , we proved that all the eigenvalues, except for finite number, are simple and the system of root functions of this spectral problem forms a Riesz basis in the space  $L_2(0, 1)$ . Furthermore, we show that the system of root functions forms a basis in the space  $L_p(0, 1)$ ,  $1 < p < \infty$  ( $p \neq 2$ ), under the conditions  $\alpha \neq 0$  and  $q(x) \in W_1^1(0, 1)$ .

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### 1. Introduction

Henceforth,  $L$  denotes the differential operator generated by the differential expression

$$l(y) = y^{(4)} + q(x)y, \quad x \in (0, 1), \tag{1.1}$$

and boundary conditions

$$\begin{aligned} U_3(y) &\equiv y'''(1) - (-1)^\sigma y'''(0) + \alpha y(0) = 0, \\ U_s(y) &\equiv y^{(s)}(1) - (-1)^\sigma y^{(s)}(0) = 0, \end{aligned} \tag{1.2}$$

where  $q(x) \in L_1(0, 1)$  is complex-valued function,  $s = \overline{0, 2}$  and  $\sigma = 0, 1$ . It is easy to verify that boundary conditions (1.2) are regular, but not strongly regular.

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In [11, 14–16], Kerimov, Kaya and Gunes investigated the following problem

$$\begin{aligned} y^{(4)} + p_2(x)y'' + p_1(x)y' + p_0(x)y &= \lambda y, \quad 0 < x < 1, \\ y'''(1) - (-1)^\sigma y'''(0) + \alpha_{3,2}y''(0) + \alpha_{3,1}y'(0) + \alpha_{3,0}y(0) &= 0, \\ y''(1) - (-1)^\sigma y''(0) + \alpha_{2,1}y'(0) + \alpha_{2,0}y(0) &= 0, \\ y'(1) - (-1)^\sigma y'(0) + \alpha_{1,0}y(0) &= 0, \\ y(1) - (-1)^\sigma y(0) &= 0 \end{aligned}$$

in various cases. However, the problems in [11, 14–16] cannot be reduced to eigenvalue problem for the operator (1.1)-(1.2).

In [8, 19, 27], it was proven that the system of root functions of a differential operator with strongly regular boundary conditions forms a basis. Besides, the basicity of root functions of a differential operator with non-strongly regular boundary conditions was investigated in [3–7, 9, 12, 17, 20–26, 29–33]. For more information about these papers, see [11, 14–16].

We define  $c_0$  and  $\varepsilon_n$  as follows:

$$c_0 = \int_0^1 q(\xi) d\xi, \tag{1.3}$$

$$\varepsilon_n = \left| \int_0^1 q(\xi) \cdot e^{2(2n-\sigma)\pi i \xi} d\xi \right| + \left| \int_0^1 q(\xi) \cdot e^{-2(2n-\sigma)\pi i \xi} d\xi \right| + n^{-1}. \tag{1.4}$$

Now, we give two theorems and their corollary and we will prove them.

**Theorem 1.1.** *If  $q(x) \in L_1(0, 1)$  is a complex-valued function and  $\alpha \neq 0$ , all eigenvalues of differential operator (1.1)–(1.2), excluding a finite number, are simple and form two sequences  $\{\lambda_{n,1}\}$  and  $\{\lambda_{n,2}\}$  and these eigenvalues have the following asymptotic formulae for sufficiently large numbers  $n$ :*

$$\begin{aligned} \lambda_{n+n_1,1} &= ((2n - \sigma)\pi)^4 \cdot \left\{ 1 + \frac{c_0}{((2n - \sigma)\pi)^4} + O(n^{-4}\varepsilon_n) \right\}, \\ \lambda_{n+n_2,2} &= ((2n - \sigma)\pi)^4 \cdot \left\{ 1 + \frac{c_0 - 2(-1)^\sigma \alpha}{((2n - \sigma)\pi)^4} + O(n^{-4}\varepsilon_n) \right\}, \end{aligned} \tag{1.5}$$

where  $n_1, n_2$  are certain integers. Moreover, for sufficiently large numbers  $n$ , the corresponding eigenfunctions  $u_{n,1}(x)$  and  $u_{n,2}(x)$  have the asymptotic formulae:

$$\begin{aligned} u_{n+n_1,1}(x) &= \sqrt{2} \sin(2n - \sigma)\pi x + O(\varepsilon_n), \\ u_{n+n_2,2}(x) &= \sqrt{2} \cos(2n - \sigma)\pi x + O(\varepsilon_n). \end{aligned} \tag{1.6}$$

**Theorem 1.2.** *If  $q(x) \in L_1(0, 1)$  is a complex-valued function and  $\alpha \neq 0$ , the root functions of differential operator (1.1)–(1.2) form a Riesz basis in the space  $L_2(0, 1)$ . In addition, if  $q(x) \in W_1^1(0, 1)$ , then the root functions form a basis in  $L_p(0, 1)$ ,  $1 < p < \infty$ , where*

$$\begin{aligned} L_p(0, 1) &= \left\{ f|f : (0, 1) \rightarrow \mathbb{C}, \int_0^1 |f(\xi)|^p d\xi < +\infty \right\}, \\ W_p^n(0, 1) &= \left\{ f|f : (0, 1) \rightarrow \mathbb{C}, f^{(n)} \in L_p(0, 1) \right\}. \end{aligned}$$

**Corollary 1.3.** *If  $q(x) \in L_2(0, 1)$  is a complex-valued function and  $\alpha \neq 0$ , then  $n_1 + n_2 = 1 - \sigma$ . Hence, we can choose  $n_1 = 0, n_2 = 1 - \sigma$ .*

## 2. Some auxiliary formulae

We denote the set

$$\left\{ \rho \in \mathbb{C} : 0 \leq \arg \rho \leq \frac{\pi}{4} \right\} \quad (2.1)$$

by  $S_0$  and the different four roots of the algebraic equation  $\omega^4 + 1 = 0$  by  $\omega_k$ ,  $k = \overline{1, 4}$ . The numbers  $\omega_k$ ,  $k = \overline{1, 4}$ , can be ordered so that the inequalities

$$\Re(\rho\omega_1) \leq \Re(\rho\omega_2) \leq \Re(\rho\omega_3) \leq \Re(\rho\omega_4) \quad (2.2)$$

hold for all  $\rho \in S_0$ , where  $\Re(z)$  denotes the real parts of a complex number  $z$  (see [28, Chapter II, §4.2]). From now on, the numbers  $\omega_k$ ,  $k = \overline{1, 4}$ , will be chosen by satisfying the inequalities (2.2) for all  $\rho \in S_0$ . Then, we get by [28, Chapter II, §4.8] that the numbers  $\omega_1, \omega_2, \omega_3, \omega_4$  are determined as

$$\omega_1 = e^{\frac{3\pi i}{4}}, \quad \omega_2 = e^{-\frac{3\pi i}{4}}, \quad \omega_3 = e^{\frac{\pi i}{4}}, \quad \omega_4 = e^{-\frac{\pi i}{4}}. \quad (2.3)$$

One can easily see that

$$\omega_1 = -\omega_4, \quad \omega_2 = -\omega_3. \quad (2.4)$$

**Lemma 2.1** ([16]). *For all  $\rho \in S_0$ , the inequalities*

$$\Re(\rho\omega_1) \leq -\frac{\sqrt{2}}{2} |\rho|, \quad \Re(\rho\omega_4) \geq \frac{\sqrt{2}}{2} |\rho|. \quad (2.5)$$

are valid.

Let

$$T_0 = \{\rho - c : \rho \in S_0\},$$

where  $c$  is a complex number. The inequalities (2.2) and (2.5) will be rewritten in the forms

$$\Re((\rho + c)\omega_1) \leq \Re((\rho + c)\omega_2) \leq \Re((\rho + c)\omega_3) \leq \Re((\rho + c)\omega_4), \quad (2.6)$$

$$\Re((\rho + c)\omega_1) \leq -\frac{\sqrt{2}}{2} |\rho + c|, \quad \Re((\rho + c)\omega_4) \geq \frac{\sqrt{2}}{2} |\rho + c| \quad (2.7)$$

for all  $\rho \in T_0$ .

For each  $\rho \in T_0$ , the equation

$$l(y) + \rho^4 y = 0 \quad (2.8)$$

has four solutions  $y_1(x, \rho)$ ,  $y_2(x, \rho)$ ,  $y_3(x, \rho)$ ,  $y_4(x, \rho)$ . These solutions are linearly independent and analytic when  $|\rho| \geq M_0$ , where  $M_0$  is a positive constant [28, Chapter II, §4.5-4.6]. Besides, the derivatives of these functions satisfy the following integro-differential equations

$$\begin{aligned} \frac{d^s y_k(x, \rho)}{dx^s} &= \rho^s \omega_k^s e^{\rho \omega_k x} + \frac{1}{4\rho^3} \int_0^x \frac{\partial^s K_1(x, \xi, \rho)}{\partial x^s} q(\xi) y_k(\xi, \rho) d\xi - \\ &- \frac{1}{4\rho^3} \int_x^1 \frac{\partial^s K_2(x, \xi, \rho)}{\partial x^s} q(\xi) y_k(\xi, \rho) d\xi, \quad s = \overline{0, 3}, \end{aligned} \quad (2.9)$$

where

$$K_1(x, \xi, \rho) = \sum_{\alpha=1}^k \omega_\alpha e^{\rho \omega_\alpha (x-\xi)}, \quad K_2(x, \xi, \rho) = \sum_{\alpha=k+1}^4 \omega_\alpha e^{\rho \omega_\alpha (x-\xi)}. \quad (2.10)$$

Let  $z_{k,s}(x, \rho)$ ,  $k = \overline{1, 4}$ ,  $s = \overline{0, 3}$ , be functions that satisfy the equations

$$\frac{d^s y_k(x, \rho)}{dx^s} = \rho^s e^{\rho \omega_k x} z_{k,s}(x, \rho). \quad (2.11)$$

By [28, Chapter II, §4.5], the functions  $z_{k,s}(x, \rho)$  are analytic with respect to  $\rho$  and satisfy

$$z_{k,s}(x, \rho) = \omega_k^s + O(\rho^{-1}), \quad s = \overline{0, 3}, \quad k = \overline{1, 4}. \tag{2.12}$$

By (2.9)-(2.11), we have

$$\begin{aligned} z_{k,s}(x, \rho) &= \omega_k^s + \frac{\omega_k^{s+1}}{4\rho^3} \int_0^x q(\xi) z_{k,0}(\xi, \rho) d\xi + \\ &+ \frac{1}{4\rho^3} \sum_{\alpha=1}^{k-1} \omega_\alpha^{s+1} \int_0^x e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} q(\xi) z_{k,0}(\xi, \rho) d\xi - \\ &- \frac{1}{4\rho^3} \sum_{\alpha=k+1}^4 \omega_\alpha^{s+1} \int_x^1 e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} q(\xi) z_{k,0}(\xi, \rho) d\xi. \end{aligned} \tag{2.13}$$

Note that, by (2.6), we get

$$\Re(\rho(\omega_\alpha - \omega_\beta)) = \Re((\rho + c)(\omega_\alpha - \omega_\beta)) - \Re(c(\omega_\alpha - \omega_\beta)) \leq 2|c|,$$

where  $1 \leq \alpha \leq \beta \leq 4$ . By using the above inequality and (2.12), we obtain for  $k = \overline{1, 4}$

$$\begin{aligned} \int_0^x q(\xi) z_{k,0}(\xi, \rho) e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} d\xi &= O(1), \quad \alpha \leq k, \\ \int_x^1 q(\xi) z_{k,0}(\xi, \rho) e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} d\xi &= O(1), \quad \alpha > k. \end{aligned}$$

By using the last relations and the formulae (2.12)-(2.13), we get

$$z_{k,s}(x, \rho) = \omega_k^s + O(\rho^{-3}), \quad s = \overline{0, 3}, \quad k = \overline{1, 4}. \tag{2.14}$$

If we now put (2.14) in (2.13), then (2.13) takes the form

$$\begin{aligned} z_{k,s}(x, \rho) &= \omega_k^s + \frac{\omega_k^{s+1}}{4\rho^3} \int_0^x q(\xi) d\xi + \frac{1}{4\rho^3} \sum_{\alpha=1}^{k-1} \omega_\alpha^{s+1} \int_0^x q(\xi) e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} d\xi - \\ &- \frac{1}{4\rho^3} \sum_{\alpha=k+1}^4 \omega_\alpha^{s+1} \int_x^1 q(\xi) e^{\rho(\omega_\alpha - \omega_k)(x-\xi)} d\xi + O(\rho^{-6}). \end{aligned}$$

By the last relation, we have

$$\begin{aligned}
 z_{2,s}(0, \rho) &= \omega_2^s - \frac{\omega_3^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2\xi} d\xi \\
 &\quad - \frac{\omega_4^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_2-\omega_4)\xi} d\xi + O(\rho^{-6}), \\
 z_{3,s}(0, \rho) &= \omega_3^s - \frac{\omega_4^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_3-\omega_4)\xi} d\xi + O(\rho^{-6}), \\
 z_{2,s}(1, \rho) &= \omega_2^s + \frac{\omega_1^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_1-\omega_2)(1-\xi)} d\xi + O(\rho^{-6}), \\
 z_{3,s}(1, \rho) &= \omega_3^s + \frac{\omega_1^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_1-\omega_3)(1-\xi)} d\xi + \\
 &\quad + \frac{\omega_2^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2(1-\xi)} d\xi + O(\rho^{-6}),
 \end{aligned}
 \tag{2.15}$$

where we assume that  $c_0 = 0$ . The case  $c_0 \neq 0$  will be investigated later.

### 3. Proof of Theorem 1.1

Let

$$\Delta(\rho) = \begin{vmatrix} U_3(y_1) & U_3(y_2) & U_3(y_3) & U_3(y_4) \\ U_2(y_1) & U_2(y_2) & U_2(y_3) & U_2(y_4) \\ U_1(y_1) & U_1(y_2) & U_1(y_3) & U_1(y_4) \\ U_0(y_1) & U_0(y_2) & U_0(y_3) & U_0(y_4) \end{vmatrix}.
 \tag{3.1}$$

If the vertex  $-c$  in the domain  $T_0$  is properly chosen, then eigenvalues  $\lambda$  of the operator (1.1)-(1.2) whose absolute values are sufficiently large have the form  $\lambda = -\rho^4$ , where the numbers  $\rho$  are the zeros of the following equation

$$\Delta(\rho) = 0
 \tag{3.2}$$

and in  $T_0$ . Conversely, the set of such numbers  $\rho$  contains all the zeros of (3.2) in  $T_0$  excluding a finite number [28, Chapter II. § 4.9]. By (2.11), we have

$$\begin{aligned}
 U_s(y_k) &= \rho^s \{e^{\rho\omega_k} z_{k,s}(1, \rho) - (-1)^\sigma z_{k,s}(0, \rho)\}, \\
 U_3(y_k) &= \rho^3 \{e^{\rho\omega_k} z_{k,3}(1, \rho) - (-1)^\sigma z_{k,3}(0, \rho)\} + \alpha z_{k,0}(0, \rho)
 \end{aligned}
 \tag{3.3}$$

for  $s = \overline{0, 2}$  and  $k = \overline{1, 4}$ . By (2.7),  $e^{\rho\omega_1}$  exponentially tends to zero and  $e^{\rho\omega_4}$  exponentially tends to infinity. So, the relations

$$\begin{aligned}
 U_s(y_1) &= -(-1)^\sigma \rho^s \{z_{1,s}(0, \rho) + O(\rho^{-7})\}, \quad s = \overline{0, 2}, \\
 U_3(y_1) &= -(-1)^\sigma \rho^3 \left\{ z_{1,3}(0, \rho) - (-1)^\sigma \frac{\alpha}{\rho^3} z_{1,0}(0, \rho) + O(\rho^{-7}) \right\}, \\
 U_s(y_4) &= \rho^s e^{\rho\omega_4} \{z_{4,s}(1, \rho) + O(\rho^{-7})\}, \quad s = \overline{0, 3}
 \end{aligned}
 \tag{3.4}$$

are valid by (2.14) and (3.3).

Let

$$\begin{aligned}
 A_{s,k}(\rho) &= \begin{cases} z_{1,s}(0, \rho), & \text{if } k = 1, \\ e^{\rho\omega_k} z_{k,s}(1, \rho) - (-1)^\sigma z_{k,s}(0, \rho), & \text{if } k = 2, 3, \\ z_{4,s}(1, \rho), & \text{if } k = 4, \end{cases} \\
 A_{3,k}(\rho) &= \begin{cases} z_{1,3}(0, \rho) - (-1)^\sigma \frac{\alpha}{\rho^3} z_{1,0}(0, \rho), & \text{if } k = 1, \\ e^{\rho\omega_k} z_{k,3}(1, \rho) - (-1)^\sigma z_{k,3}(0, \rho) + \frac{\alpha}{\rho^3} z_{k,0}(0, \rho), & \text{if } k = 2, 3, \\ z_{4,3}(1, \rho), & \text{if } k = 4, \end{cases}
 \end{aligned} \tag{3.5}$$

where  $s = \overline{0, 2}$ . By the formulae (3.3)-(3.5), it is obvious that

$$\begin{aligned}
 U_s(y_1) &= -(-1)^\sigma \rho^s \{A_{s,1}(\rho) + O(\rho^{-7})\}, \\
 U_s(y_k) &= \rho^s A_{s,k}(\rho), \\
 U_s(y_4) &= \rho^s e^{\rho\omega_4} \{A_{s,4}(\rho) + O(\rho^{-7})\},
 \end{aligned} \tag{3.6}$$

where  $k = 2, 3$  and  $s = \overline{0, 3}$ . We put these formulae of boundary conditions in the equation (3.2). If we divide out the common multipliers  $\rho^3, \rho^2, \rho$  of the rows and also divide out the common multipliers  $-(-1)^\sigma$  and  $e^{\rho\omega_4}$  of the columns of the determinant  $\Delta(\rho)$ , then we get that the equation (3.2) is equivalent to

$$\Delta_1(\rho) + O(\rho^{-7}) = 0, \tag{3.7}$$

where

$$\Delta_1(\rho) = \begin{vmatrix} A_{3,1}(\rho) & A_{3,2}(\rho) & A_{3,3}(\rho) & A_{3,4}(\rho) \\ A_{2,1}(\rho) & A_{2,2}(\rho) & A_{2,3}(\rho) & A_{2,4}(\rho) \\ A_{1,1}(\rho) & A_{1,2}(\rho) & A_{1,3}(\rho) & A_{1,4}(\rho) \\ A_{0,1}(\rho) & A_{0,2}(\rho) & A_{0,3}(\rho) & A_{0,4}(\rho) \end{vmatrix}. \tag{3.8}$$

We now rewrite the formulae (35)-(36) in [14]. If  $\rho$  is a root of equation (3.7), we get that the equalities

$$e^{\rho\omega_2} - (-1)^\sigma = O(\rho^{-3}), \quad e^{\rho\omega_3} - (-1)^\sigma = O(\rho^{-3}) \tag{3.9}$$

are valid.

By using the relations (2.14), (2.15) and (3.9) for  $s = \overline{0, 3}$ , we have

$$\begin{aligned}
 A_{s,k}(\rho) &= A_{s,k}^{(k)}(\rho) + B_{s,k}^{(k)}(\rho) + O(\rho^{-6}), \quad k = 2, 3, \\
 A_{s,k}(\rho) &= \omega_k^s + O(\rho^{-3}), \quad k = 1, 4,
 \end{aligned} \tag{3.10}$$

where

$$\begin{aligned}
 A_{s,2}^{(2)}(\rho) &= \omega_2^s (e^{\rho\omega_2} - (-1)^\sigma) + \frac{(-1)^\sigma \omega_3^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2\xi} d\xi, \quad s = \overline{0, 2}, \\
 A_{s,3}^{(3)}(\rho) &= \omega_3^s (e^{\rho\omega_3} - (-1)^\sigma) + \frac{(-1)^\sigma \omega_2^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2(1-\xi)} d\xi, \quad s = \overline{0, 2}, \\
 A_{3,2}^{(2)}(\rho) &= \omega_2^3 (e^{\rho\omega_2} - (-1)^\sigma) + \frac{(-1)^\sigma \omega_3^4}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2\xi} d\xi + \frac{\alpha}{\rho^3}, \\
 A_{3,3}^{(3)}(\rho) &= \omega_3^3 (e^{\rho\omega_3} - (-1)^\sigma) + \frac{(-1)^\sigma \omega_2^4}{4\rho^3} \int_0^1 q(\xi) e^{2\rho\omega_2(1-\xi)} d\xi + \frac{\alpha}{\rho^3},
 \end{aligned} \tag{3.11}$$

and

$$\begin{aligned}
 B_{s,k}^{(k)}(\rho) &= \frac{(-1)^\sigma \omega_1^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_1 - \omega_k)(1-\xi)} d\xi \\
 &+ \frac{(-1)^\sigma \omega_4^{s+1}}{4\rho^3} \int_0^1 q(\xi) e^{\rho(\omega_k - \omega_4)\xi} d\xi, \quad s = \overline{0,3}, \quad k = 2,3.
 \end{aligned}
 \tag{3.12}$$

By the relations (3.9), (3.11) and (3.12), we have

$$A_{s,k}(\rho) = O(\rho^{-3}), \quad k = 2,3, \quad s = \overline{0,3}.
 \tag{3.13}$$

If we put the equalities (3.10) in the determinant (3.8), then, by using (3.13), we get that the equation (3.7) is equivalent to

$$\Delta_2(\rho) + O(\rho^{-7}) = 0,
 \tag{3.14}$$

where

$$\Delta_2(\rho) = \begin{vmatrix} \omega_1^3 & A_{3,2}^{(2)}(\rho) + B_{3,2}^{(2)}(\rho) & A_{3,3}^{(3)}(\rho) + B_{3,3}^{(3)}(\rho) & \omega_4^3 \\ \omega_1^2 & A_{2,2}^{(2)}(\rho) + B_{2,2}^{(2)}(\rho) & A_{2,3}^{(3)}(\rho) + B_{2,3}^{(3)}(\rho) & \omega_4^2 \\ \omega_1 & A_{1,2}^{(2)}(\rho) + B_{1,2}^{(2)}(\rho) & A_{1,3}^{(3)}(\rho) + B_{1,3}^{(3)}(\rho) & \omega_4 \\ 1 & A_{0,2}^{(2)}(\rho) + B_{0,2}^{(2)}(\rho) & A_{0,3}^{(3)}(\rho) + B_{0,3}^{(3)}(\rho) & 1 \end{vmatrix}.$$

By the definition of  $B_{s,k}^{(k)}(\rho)$  (see: (3.12)), it can be easily proven that the columns

$$\left( B_{3,2}^{(2)}(\rho), B_{2,2}^{(2)}(\rho), B_{1,2}^{(2)}(\rho), B_{0,2}^{(2)}(\rho) \right)^T$$

and

$$\left( B_{3,3}^{(3)}(\rho), B_{2,3}^{(3)}(\rho), B_{1,3}^{(3)}(\rho), B_{0,3}^{(3)}(\rho) \right)^T$$

are two linear combinations of the first and fourth columns of the determinant  $\Delta_2(\rho)$ . Consequently, the determinant  $\Delta_2(\rho)$  can be rewritten as follows:

$$\Delta_2(\rho) = \begin{vmatrix} \omega_1^3 & A_{3,2}^{(2)}(\rho) & A_{3,3}^{(3)}(\rho) & \omega_4^3 \\ \omega_1^2 & A_{2,2}^{(2)}(\rho) & A_{2,3}^{(3)}(\rho) & \omega_4^2 \\ \omega_1 & A_{1,2}^{(2)}(\rho) & A_{1,3}^{(3)}(\rho) & \omega_4 \\ 1 & A_{0,2}^{(2)}(\rho) & A_{0,3}^{(3)}(\rho) & 1 \end{vmatrix}.
 \tag{3.15}$$

If we put (3.11) in the determinant (3.15) and calculate it, then we get that the equation (3.14) is reduced to

$$\begin{aligned}
 &-16(e^{\rho\omega_2} - (-1)^\sigma)(e^{\rho\omega_3} - (-1)^\sigma) \\
 &- \frac{4\omega_2\alpha(e^{\rho\omega_2} - (-1)^\sigma)}{\rho^3} + \frac{4\omega_2\alpha(e^{\rho\omega_3} - (-1)^\sigma)}{\rho^3} + O(\rho^{-6}\varepsilon(\rho)) = 0,
 \end{aligned}
 \tag{3.16}$$

where

$$\varepsilon(\rho) = \left| \int_0^1 q(\xi) e^{2\rho\omega_2\xi} d\xi \right| + \left| \int_0^1 q(\xi) e^{2\rho\omega_2(1-\xi)} d\xi \right| + |\rho^{-1}|.
 \tag{3.17}$$

Note that the formula

$$\varepsilon(\rho) = o(1)$$

can be easily proved by using the proof of Riemann-Lebesgue Lemma.

After some calculations, the equation (3.16) splits into the following two equations:

$$e^{\rho\omega_2} = (-1)^\sigma + O(\rho^{-3}\varepsilon(\rho)),
 \tag{3.18}$$

$$e^{\rho\omega_2} = (-1)^\sigma + \frac{\omega_2\alpha}{2\rho^3} + O\left(\rho^{-3}\varepsilon(\rho)\right). \tag{3.19}$$

Consider the equation (3.18). By Rouché’s theorem, we can get that the roots of the equation (3.18) in  $T_0$  with sufficiently large absolute values lie in the sets  $G_n \subset T_0$ , where  $G_n$  is  $O(n^{-1})$ -neighborhood of  $-(2n - \sigma)\pi i/\omega_2$ ,  $n = n_0, n_0 + 1, \dots$  and  $n_0$  is sufficiently large positive integer [28, Chapter II, § 4.9]. Besides, the equation (3.18) has a unique root in  $G_n$ . Assume that  $\tilde{\rho}$  is the unique root of (3.18) in  $G_n$ . By the equalities (40) and (41) in [14], we obtain

$$\tilde{\rho} = -\frac{(2n - \sigma)\pi i}{\omega_2} + r, \quad r = O\left(n^{-3}\right). \tag{3.20}$$

If we use the formulae (3.20) in (3.17), we obtain

$$\varepsilon(\rho) = O(\varepsilon_n), \tag{3.21}$$

where  $\varepsilon_n$  is the sequence defined in (1.4).

Now, we find more accurate formula for the number  $r$ . The following formulae

$$\frac{1}{\tilde{\rho}^3} = \frac{\omega_2}{(2n - \sigma)^3 \pi^3} + O\left(n^{-7}\right), \tag{3.22}$$

$$e^{\tilde{\rho}\omega_2} = (-1)^\sigma \left\{ 1 + r\omega_2 + O\left(n^{-6}\right) \right\} \tag{3.23}$$

can be easily obtained by using (3.20). By putting  $\rho = \tilde{\rho}$  in (3.18) and using the relations (3.21) and (3.23), we have

$$r = O\left(n^{-3}\varepsilon_n\right). \tag{3.24}$$

Thus, the equation (3.18) has the unique root

$$\tilde{\rho}_{n,1} = -\frac{(2n - \sigma)\pi i}{\omega_2} + O\left(n^{-3}\varepsilon_n\right) \tag{3.25}$$

in  $O(n^{-1})$ -neighbourhood  $G_n$  of  $z_n = -(2n - \sigma)\pi i/\omega_2$ ,  $n = n_0, n_0 + 1, \dots$  by (3.20) and (3.24).

Similarly, we conclude that the equation (3.19) has the unique root

$$\tilde{\rho}_{n,2} = -\frac{1}{\omega_2} \left\{ (2n - \sigma)\pi i - \frac{(-1)^\sigma i\alpha}{2(2n - \sigma)^3 \pi^3} \right\} + O\left(n^{-3}\varepsilon_n\right) \tag{3.26}$$

in  $O(n^{-1})$ -neighbourhood  $G_n$  of the point  $z_n$ ,  $n = n_0, n_0 + 1, \dots$  by the formulae (3.20)-(3.23).

Now, we investigate the eigenfunction  $\tilde{u}_{n,1}(x)$  corresponding to the eigenvalue  $\lambda = -(\tilde{\rho}_{n,1})^4$ . We use the following determinant for this eigenfunction

$$\tilde{u}_{n,1}(x) = \frac{(-1)^\sigma e^{-\rho\omega_4} \sqrt{2}}{4\omega_2 i \alpha \rho^3} \begin{vmatrix} y_1(x, \rho) & y_2(x, \rho) & y_3(x, \rho) & y_4(x, \rho) \\ U_3(y_1) & U_3(y_2) & U_3(y_3) & U_3(y_4) \\ U_2(y_1) & U_2(y_2) & U_2(y_3) & U_2(y_4) \\ U_1(y_1) & U_1(y_2) & U_1(y_3) & U_1(y_4) \end{vmatrix},$$

where  $\rho = \tilde{\rho}_{n,1}$  and  $n$  is sufficiently large positive integer. Easily, we can rewrite

$$\begin{aligned} \tilde{u}_{n,1}(x) &= -\frac{\rho^3 \sqrt{2}}{4\omega_2 i \alpha} \\ &\times \begin{vmatrix} -(-1)^\sigma y_1(x, \rho) & y_2(x, \rho) & y_3(x, \rho) & e^{-\rho\omega_4} y_4(x, \rho) \\ -(-1)^\sigma \rho^{-3} U_3(y_1) & \rho^{-3} U_3(y_2) & \rho^{-3} U_3(y_3) & \rho^{-3} e^{-\rho\omega_4} U_3(y_4) \\ -(-1)^\sigma \rho^{-2} U_2(y_1) & \rho^{-2} U_2(y_2) & \rho^{-2} U_2(y_3) & \rho^{-2} e^{-\rho\omega_4} U_2(y_4) \\ -(-1)^\sigma \rho^{-1} U_1(y_1) & \rho^{-1} U_1(y_2) & \rho^{-1} U_1(y_3) & \rho^{-1} e^{-\rho\omega_4} U_1(y_4) \end{vmatrix}, \end{aligned} \tag{3.27}$$



By (2.11)-(2.12), we can obtain

$$y_k(x, \rho) = O(1), \quad k = 1, 2, 3, \quad e^{-\rho\omega_4}y_4(x, \rho) = O(1), \quad (3.28)$$

where  $\rho = \tilde{\rho}_{n,1}$ . Putting the formulae (3.6) in (3.27) and using (3.28), we get that the formulae (3.27) has the form

$$\tilde{u}_{n,1}(x) = -\frac{\rho^3\sqrt{2}}{4\omega_2i\alpha} \begin{vmatrix} -(-1)^\sigma y_1(x, \rho) & y_2(x, \rho) & y_3(x, \rho) & e^{-\rho\omega_4}y_4(x, \rho) \\ A_{3,1}(\rho) & A_{3,2}(\rho) & A_{3,3}(\rho) & A_{3,4}(\rho) \\ A_{2,1}(\rho) & A_{2,2}(\rho) & A_{2,3}(\rho) & A_{2,4}(\rho) \\ A_{1,1}(\rho) & A_{1,2}(\rho) & A_{1,3}(\rho) & A_{1,4}(\rho) \end{vmatrix}, \quad (3.29)$$

where  $\rho = \tilde{\rho}_{n,1}$ . If we calculate the determinant in (3.29) by using (3.10), (3.13) and (3.28), then we have

$$\tilde{u}_{n,1}(x) = -\frac{\rho^3\sqrt{2}}{4\omega_2i\alpha} \{y_3(x, \rho) E_2(\rho) - y_2(x, \rho) E_3(\rho)\} + O(\rho^{-3}), \quad (3.30)$$

where  $\rho = \tilde{\rho}_{n,1}$  and

$$E_k(\rho) = \begin{vmatrix} \omega_1^3 & A_{3,k}(\rho) & \omega_4^3 \\ \omega_1^2 & A_{2,k}(\rho) & \omega_4^2 \\ \omega_1 & A_{1,k}(\rho) & \omega_4 \end{vmatrix}, \quad k = 2, 3.$$

By the last formula and (3.10), we get that the determinant  $E_k(\rho)$  can be rewritten as follows

$$E_k(\rho) = \begin{vmatrix} \omega_1^3 & A_{3,k}^{(k)}(\rho) & \omega_4^3 \\ \omega_1^2 & A_{2,k}^{(k)}(\rho) & \omega_4^2 \\ \omega_1 & A_{1,k}^{(k)}(\rho) & \omega_4 \end{vmatrix} + \begin{vmatrix} \omega_1^3 & B_{3,k}^{(k)}(\rho) & \omega_4^3 \\ \omega_1^2 & B_{2,k}^{(k)}(\rho) & \omega_4^2 \\ \omega_1 & B_{1,k}^{(k)}(\rho) & \omega_4 \end{vmatrix} + O(\rho^{-6}), \quad k = 2, 3,$$

where  $\rho = \tilde{\rho}_{n,1}$ . By (3.12), the second determinant above is zero, i.e.,

$$E_k(\rho) = \begin{vmatrix} \omega_1^3 & A_{3,k}^{(k)}(\rho) & \omega_4^3 \\ \omega_1^2 & A_{2,k}^{(k)}(\rho) & \omega_4^2 \\ \omega_1 & A_{1,k}^{(k)}(\rho) & \omega_4 \end{vmatrix} + O(\rho^{-6}), \quad k = 2, 3, \quad (3.31)$$

where  $\rho = \tilde{\rho}_{n,1}$ . The following formulae

$$A_{1,k}^{(k)}(\rho) = A_{2,k}^{(k)}(\rho) = O(\rho^{-3}\varepsilon), \quad A_{3,k}^{(k)}(\rho) = \frac{\alpha}{\rho^3} + O(\rho^{-3}\varepsilon)$$

are directly obtained by using (3.11) and (3.18), where  $k = 2, 3$ ,  $\rho = \tilde{\rho}_{n,1}$  and  $\varepsilon = \varepsilon_n$ . If we calculate the determinant in (3.31) by using the last relations, we get

$$E_k(\rho) = -\frac{2\omega_2\alpha}{\rho^3} + O(\rho^{-3}\varepsilon),$$

where  $k = 2, 3$  and  $\rho = \tilde{\rho}_{n,1}$  and  $\varepsilon = \varepsilon_n$ . Consequently, we have

$$\tilde{u}_{n,1}(x) = \frac{\sqrt{2}}{2i} (y_3(x, \tilde{\rho}_{n,1}) - y_2(x, \tilde{\rho}_{n,1})) + O(\varepsilon_n)$$

by (3.30). On the other hand, we can write

$$y_2(x, \tilde{\rho}_{n,1}) = e^{-(2n-\sigma)\pi ix} + O(n^{-1}), \quad y_3(x, \tilde{\rho}_{n,1}) = e^{(2n-\sigma)\pi ix} + O(n^{-1}),$$

$$(\tilde{\rho}_{n,1})^{-1} = O(n^{-1}),$$

by (2.11), (2.12) and (3.25). Finally, we have the expression

$$\tilde{u}_{n,1}(x) = \sqrt{2} \sin(2n - \sigma)\pi x + O(\varepsilon_n). \quad (3.32)$$

Now, we also investigate the eigenfunction  $\tilde{u}_{n,2}(x)$  corresponding to the eigenvalue  $\lambda = -(\tilde{\rho}_{n,2})^4$  by using the following determinant

$$\tilde{u}_{n,2}(x) = \frac{(-1)^\sigma e^{-\rho\omega_4} \sqrt{2}}{4i\alpha} \begin{vmatrix} y_1(x, \rho) & y_2(x, \rho) & y_3(x, \rho) & y_4(x, \rho) \\ U_2(y_1) & U_2(y_2) & U_2(y_3) & U_2(y_4) \\ U_1(y_1) & U_1(y_2) & U_1(y_3) & U_1(y_4) \\ U_0(y_1) & U_0(y_2) & U_0(y_3) & U_0(y_4) \end{vmatrix}$$

where  $\rho = \tilde{\rho}_{n,2}$ . In a similar way, we get

$$\tilde{u}_{n,2}(x) = \sqrt{2} \cos(2n - \sigma)\pi x + O(\varepsilon_n). \tag{3.33}$$

We now prove the formulae (1.5) and (1.6). By the relation  $\lambda = -\rho^4$ , we have

$$\begin{aligned} \tilde{\lambda}_{n,1} &= -(\tilde{\rho}_{n,1})^4 = ((2n - \sigma)\pi)^4 \left\{ 1 + O(n^{-4}\varepsilon_n) \right\}, \\ \tilde{\lambda}_{n,2} &= -(\tilde{\rho}_{n,2})^4 = ((2n - \sigma)\pi)^4 \left\{ 1 - \frac{2(-1)^\sigma \alpha}{((2n - \sigma)\pi)^4} + O(n^{-4}\varepsilon_n) \right\}. \end{aligned}$$

The above formulae are valid in case of  $c_0 = 0$ . Now, assume that  $c_0 \neq 0$  (see (1.3)). Consider the eigenvalue problem with the differential expression

$$y^{(4)} + q(x)y = \lambda y$$

(see (1.1)). We can rewrite this problem as

$$y^{(4)} + (q(x) - c_0)y = (\lambda - c_0)y.$$

One can easily see that the integral of  $q(x) - c_0$  on the line  $[0, 1]$  is zero. Then, by the above proof, for the eigenvalues  $\lambda - c_0$ , the formulae

$$\begin{aligned} \tilde{\lambda}_{n,1} - c_0 &= ((2n - \sigma)\pi)^4 \left\{ 1 + O(n^{-4}\varepsilon_n) \right\}, \\ \tilde{\lambda}_{n,2} - c_0 &= ((2n - \sigma)\pi)^4 \left\{ 1 - \frac{2(-1)^\sigma \alpha}{((2n - \sigma)\pi)^4} + O(n^{-4}\varepsilon_n) \right\}. \end{aligned} \tag{3.34}$$

are valid and the eigenfunctions  $y$  do not change. On the other hand, the construction of the integers  $n_1$  and  $n_2$  is similar to the way in [11, 14–16]. Hence, the formulae (1.5) and (1.6) can be obtained by (3.32), (3.33) and (3.34).

#### 4. Proofs of Theorem 1.2 and Corollary 1.3

First, we prove that the root functions of the operator  $L$  form a Riesz basis in  $L_2(0, 1)$  provided  $q(x) \in L_1(0, 1)$ .

Let

$$v_{1,1}(x), v_{1,2}(x), \dots, v_{n,1}(x), v_{n,2}(x), \dots \tag{4.1}$$

be the biorthogonal system of the following system

$$u_{1,1}(x), u_{1,2}(x), \dots, u_{n,1}(x), u_{n,2}(x), \dots, \tag{4.2}$$

i.e.  $(u_{n,j}, v_{m,s}) = \delta_{n,m} \cdot \delta_{j,s}$ ,  $n, m = 1, 2, \dots, j, s = 1, 2$ . By [19, p.84] or [28, p.99], (4.1) is the root functions of the adjoint differential operator  $L^*$ .  $L^*$  consists of the differential expression and boundary conditions

$$\begin{aligned} l^*(z) &= z^{iv} + \overline{q(x)}z, \\ U_0^*(z) &\equiv z(1) - (-1)^\sigma z(0) = 0, \\ U_1^*(z) &\equiv z'(1) - (-1)^\sigma z'(0) = 0, \\ U_2^*(z) &\equiv z''(1) - (-1)^\sigma z''(0) = 0, \\ U_3^*(z) &\equiv z'''(1) - (-1)^\sigma z'''(0) + \bar{\alpha}z(0) = 0. \end{aligned} \tag{4.3}$$

(4.3) shows that the differential operator  $L^*$  provides the conditions of Theorem 1.1. So, the formulae

$$\begin{aligned} \overline{v_{n+n_1,1}(x)} &= r_{n+n_1,1}(\sin(2n - \sigma)\pi x + O(\varepsilon_n)), \\ \overline{v_{n+n_2,2}(x)} &= r_{n+n_2,2}(\cos(2n - \sigma)\pi x + O(\varepsilon_n)) \end{aligned} \tag{4.4}$$

are valid for sufficiently large numbers  $n$ , where the numbers  $r_{n_j+n,j}$ ,  $j = 1, 2$  are determined by the inner product  $(u_{n_j+n,j}, v_{n_j+n,j}) = 1$ . By these equality and (1.6), (4.4), we have

$$r_{n+n_j,j} = \sqrt{2} + O(\varepsilon_n), \quad j = 1, 2,$$

for sufficiently large numbers  $n$ . Consequently, if we put the last equality in (4.4), we get

$$\begin{aligned} \overline{v_{n+n_1,1}(x)} &= \sqrt{2} \sin(2n - \sigma)\pi x + O(\varepsilon_n), \\ \overline{v_{n+n_2,2}(x)} &= \sqrt{2} \cos(2n - \sigma)\pi x + O(\varepsilon_n). \end{aligned} \tag{4.5}$$

Each of the systems (4.1) and (4.2) is complete in  $L_2(0, 1)$  [2]. Furthermore, by (1.6) and (4.5), we get that the sequence of the multiplication of the norms of the elements of the systems (4.1) and (4.2) is bounded i.e.  $\|u_n\| \|v_n\| \leq M$  for all  $n \in \mathbb{N}$ , where  $M$  is a constant. On the other hand, since all the eigenvalues, excluding a finite number, are simple, then there are at most finitely many associate functions in the root functions of  $L$ . Hence, the system (4.2) is a Riesz basis in  $L_2(0, 1)$  by the main theorem in [18].

Now, we prove Corollary 1.3 by the assumption  $q(x) \in L_2(0, 1)$ . Let

$$g_0(x) = 1, \quad g_{2n-1}(x) = \sqrt{2} \sin 2n\pi x, \quad g_{2n}(x) = \sqrt{2} \cos 2n\pi x, \tag{4.6}$$

$$\tilde{g}_{2n-1} = \sqrt{2} \sin(2n - 1)\pi x, \quad \tilde{g}_{2n} = \sqrt{2} \cos(2n - 1)\pi x, \tag{4.7}$$

where  $n = 1, 2, \dots$ . The systems (4.6) and (4.7) are separately orthonormal bases in  $L_2(0, 1)$ . Since  $q(x) \in L_2(0, 1)$ , then the sum of the squares of the absolute values of Fourier coefficients is convergent. Then, we can easily obtain the following

$$\sum_{n=1}^{\infty} \varepsilon_n^2 < +\infty. \tag{4.8}$$

Now, we assume  $\sigma = 0$ . In the case  $\sigma = 1$ , proof can be obtained in a similar method by using (4.7). Let  $n_1 \geq 0$  and  $n_2 \geq 0$ . By (1.6), (4.6) and (4.8), we obtain

$$\sum_{n=1}^{\infty} \left( \|u_{n+n_1,1} - g_{2n-1}\|^2 + \|u_{n+n_2,2} - g_{2n}\|^2 \right) \leq \text{const} \sum_{n=1}^{\infty} \varepsilon_n^2 < +\infty. \tag{4.9}$$

One can easily see that  $n_1 + n_2$  root functions of  $L$  and one function in the system (4.6) are absent in (4.9). Let  $n_1 + n_2 > 1$ . By (4.9), the system  $S$  generated by all functions excluding  $n_1 + n_2 - 1$  functions in the system (4.2) is quadratically close to the system (4.6). Since (4.6) is a Riesz basis in  $L_2(0, 1)$ , then  $S$  is also a Riesz basis in  $L_2(0, 1)$  [10]. This contradicts the basicity of the system (4.2). Similarly, let  $n_1 = n_2 = 0$ . Since (4.2) forms a Riesz basis in  $L_2(0, 1)$ , then again by (4.9), the system  $\{g_k(x)\}_{k=1}^{\infty}$  is a Riesz basis in  $L_2(0, 1)$ . Obviously, the latter contradicts the basicity of  $\{g_k(x)\}_{k=0}^{\infty}$  in  $L_2(0, 1)$ . All other cases can be checked in a similar method.

Hence, the equality  $n_1 + n_2 = 1$  is valid. So, we can assume that  $n_1 = 0$ ,  $n_2 = 1 - \sigma$  without loss of generality. Then, we obtain

$$\begin{aligned} u_{n,1}(x) &= \sqrt{2} \sin(2n - \sigma)\pi x + O(\varepsilon_n), \\ u_{n+1-\sigma,2}(x) &= \sqrt{2} \cos(2n - \sigma)\pi x + O(\varepsilon_n), \\ \overline{v_{n,1}(x)} &= \sqrt{2} \sin(2n - \sigma)\pi x + O(\varepsilon_n), \\ \overline{v_{n+1-\sigma,2}(x)} &= \sqrt{2} \cos(2n - \sigma)\pi x + O(\varepsilon_n). \end{aligned} \tag{4.10}$$

by (1.6) and (4.5).

Now, we show that the root functions of  $L$  form a basis in the Lebesgue space  $L_p(0, 1)$  when  $q(x) \in W_1^1(0, 1)$ , where  $1 < p < \infty$ ,  $p \neq 2$ . We prove the basicity in  $L_p(0, 1)$  in the

case  $\sigma = 0$ . In the case  $\sigma = 1$ , the proof is similar. Since the function  $q(x)$  is in the space  $W_1^1(0, 1)$ , then it is differentiable and its derivative is integrable. So, we get

$$\varepsilon_n = O(n^{-1})$$

by using (1.3). Thus, the formulae (4.10) turn into

$$\begin{aligned} u_{n,1}(x) &= \sqrt{2} \sin(2n - \sigma)\pi x + O(n^{-1}), \\ u_{n+1-\sigma,2}(x) &= \sqrt{2} \cos(2n - \sigma)\pi x + O(n^{-1}), \\ \frac{v_{n,1}(x)}{v_{n+1-\sigma,2}(x)} &= \sqrt{2} \sin(2n - \sigma)\pi x + O(n^{-1}), \\ &= \sqrt{2} \cos(2n - \sigma)\pi x + O(n^{-1}). \end{aligned} \tag{4.11}$$

For each  $p \in (1, \infty)$ , (4.6) is a basis in  $L_p(0, 1)$  [1, Chapter VIII, §20, Theorem 2]. Then, there exists  $M_p > 0$  such that the inequality

$$\left\| \sum_{n=0}^N (f, g_n) g_n \right\|_p \leq M_p \|f\|_p, \quad N = 1, 2, \dots, \tag{4.12}$$

holds for each function  $f(x) \in L_p(0, 1)$ , where  $\|\cdot\|_p$  is the norm of the normed space  $L_p(0, 1)$  [13, Chapter I, §4, Theorem 6]. Let  $p \in (1, 2)$ . Since (4.2) is a complete system in  $L_2(0, 1)$ , then it is also complete in  $L_p(0, 1)$ . Besides, one can easily see that the inequality

$$\|(f, v_{n,j}) u_{n,j}\|_p \leq \text{const} \|f\|_p,$$

where  $j = 1, 2$  and  $n = 1, 2, \dots$

By theorem 6 in [13, Chapter VIII, §4], for the basicity of this system in  $L_p(0, 1)$ , we must prove that there exists a constant  $M > 0$  such that the inequality

$$\left\| \sum_{n=1}^m \sum_{j=1}^2 (f, v_{n,j}) u_{n,j} \right\|_p \leq M \|f\|_p \quad m = 1, 2, \dots,$$

holds for  $f(x) \in L_p(0, 1)$ . Instead of the above inequality, it is enough to prove the following

$$J_m(f) = \left\| \sum_{n=1}^m \{(f, v_{n,1}) u_{n,1} + (f, v_{n+1,2}) u_{n+1,2}\} \right\|_p \leq M' \|f\|_p, \tag{4.13}$$

where  $M'$  is a positive constant and  $m = 1, 2, \dots$

By (4.6) and (4.11), we have

$$J_m(f) \leq J_{m,1}(f) + J_{m,2}(f) + J_{m,3}(f) + J_{m,4}(f), \tag{4.14}$$

where

$$J_{m,1}(f) = \left\| \sum_{n=1}^{2m} (f, g_n) g_n \right\|_p, \quad J_{m,2}(f) = \left\| \sum_{n=1}^{2m} (f, g_n) O(n^{-1}) \right\|_p,$$

$$J_{m,3}(f) = \left\| \sum_{n=1}^{2m} (f, O(n^{-1})) g_n \right\|_p, \quad J_{m,4}(f) = \left\| \sum_{n=1}^{2m} (f, O(n^{-1})) O(n^{-1}) \right\|_p.$$

By (4.12),

$$J_{m,1}(f) \leq \text{const} \|f\|_p. \tag{4.15}$$

By Theorem 2.8 (Riesz theorem) [34, Chapter XII, §2,], the relations

$$\begin{aligned} J_{m,2}(f) &\leq \text{const} \sum_{n=1}^{2m} |(f, g_n)| n^{-1} \\ &\leq \text{const} \left( \sum_{n=1}^{2m} |(f, g_n)|^q \right)^{1/q} \left( \sum_{n=1}^{2m} n^{-p} \right)^{1/p} \leq \text{const} \|f\|_p, \end{aligned} \quad (4.16)$$

holds, where  $1/p + 1/q = 1$ . Moreover,

$$\begin{aligned} J_{m,3}(f) &\leq \left\| \sum_{n=1}^{2m} (f, O(n^{-1})) g_n \right\|_2 = \left( \sum_{n=1}^{2m} |(f, O(n^{-1}))|^2 \right)^{1/2} \\ &\leq \text{const} \|f\|_1 \left( \sum_{n=1}^{2m} n^{-2} \right)^{1/2} \leq \text{const} \|f\|_p. \end{aligned} \quad (4.17)$$

Further,

$$J_{m,4} \leq \text{const} \|f\|_1 \sum_{n=1}^{2m} n^{-2} \leq \text{const} \|f\|_p. \quad (4.18)$$

The inequalities (4.14)-(4.18) prove the inequality (4.13). The basicity of (4.2) in  $L_p(0, 1)$  is obtained when  $1 < p < 2$ .

Assume that the relations  $2 < p < \infty$  and  $1/p + 1/q = 1$  hold. Then,  $1 < q < 2$  and the biorthogonal system (4.1) is the root functions of the adjoint operator  $L^*$ . Above, we show that the system of root functions of such operator is a basis of  $L_q(0, 1)$ . So, the system (4.2) being biorthogonal system of (4.1) is a basis in  $L_p(0, 1)$ .

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