



Advances in the Theory of Nonlinear Analysis and its Applications

ISSN: 2587-2648

Peer-Reviewed Scientific Journal

A modified Mann iterative scheme based on the generalized explicit methods for quasi-nonexpansive mappings in Banach spaces

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Abstract

In this paper, we introduce and study a new iterative algorithm which is a combination of a modified Mann iterative scheme and a generalized explicit methods (GEM) for finding a common fixed points of an infinite family of quasi-nonexpansive mappings in Banach spaces. Under suitable conditions, some strong convergence theorems for finding a common fixed points of an infinite family of quasi-nonexpansive mappings are obtained without imposing any compactness assumption. Presented results improve and generalize many known results in the current literature.

Keywords: Common fixed points; Quasi-nonexpansive mappings; Midpoint rule; Banach spaces.

2010 MSC: 47H09; 47H10; 47J25.

1. Introduction

Let X be a real normed space, K be a nonempty subset of X . A map $T : K \rightarrow X$ is said to be Lipschitz if there exists an $L \geq 0$ such that

$$\|Tx - Ty\| \leq L\|x - y\| \quad \text{for all } x, y \in K; \quad (1)$$

if $L < 1$, T is called *contraction* and if $L = 1$, T is called nonexpansive.

We denote by $F(T)$ the set of fixed points of the mapping T , that is $F(T) := \{x \in D(T) : x = Tx\}$. We

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assume that $F(T)$ is nonempty. If T is nonexpansive mappings, it is well know $F(T)$ is closed and convex. A map T is called quasi- nonexpansive if $\|Tx - p\| \leq \|x - p\|$ holds for all x in K and $p \in F(T)$. We note that the following inclusions hold for the classes of the mappings:

Firmly nonexpansive \subset nonexpansive \subset quasi-nonexpansive.

We illustrate these by the following example.

Example 1.1. Let $X = l_\infty$ and $C := \{x \in l_\infty : \|x\|_\infty \leq 1\}$. Define $T : C \rightarrow C$ by $Tx = (0, x^2_1, x^2_2, x^3_3, \dots)$ for $x = (x_1, x_2, x_3, \dots)$ in C . Then, it is clear that T is continuous and maps C into C . Moreover, $Tp = p$ if and only if $p = 0$. Futhermore,

$$\begin{aligned} \|Tx - p\|_\infty &= \|Tx\|_\infty = \|(0, x^2_1, x^2_2, x^3_3, \dots)\|_\infty \\ &\leq \|(x_1, x_2, x_3, \dots)\|_\infty \\ &= \|x - p\|_\infty. \end{aligned}$$

Therefore, T is quasi-nonexpansive. However, T is not nonexpansive.

Many problems arising in different areas of mathematics, such as optimization, variational analysis and differential equations, engineering and science problems can be modeled by the equation

$$x = Tx, \quad (2)$$

where T is a nonexpansive mapping. The solution set of this equation coincide to a fixed points set of T . Such operators have been studied extensively (see, e.g., Yao et al. [24], Chidume [4], Marino et al. [15] and the references therein).

Historically, one of the most investigated methods approximating fixed points of nonexpansive mappings dates back to 1953 and is known as Mann's method, in light of Mann [10]. Let C be a nonempty, closed and convex subset of a Banach space X , Mann's scheme is defined by

$$\begin{cases} x_0 \in C, \\ x_{n+1} = \alpha_n x_n + (1 - \alpha_n)Tx_n, \end{cases} \quad (3)$$

$\{\alpha_n\}$ is a sequence in $(0, 1)$. But Mann's iteration process has only weak convergence, even in Hilbert space setting. Therefore, many authors try to modify Mann's iteration to have strong convergence for nonlinear operators.

Over the last several years, the implicit midpoint rule (IMR) has become a powerful numerical method for numerically solving time-dependent differential equations (in particular, stiff equations) and differential algebraic equations (see, [18]). Consider the following initial value problem:

$$x'(t) = f(x(t)), \quad x_0 = x(t_0) \quad (4)$$

where $f : \mathbb{R}^M \rightarrow \mathbb{R}^M$ is a continuous function. The IMR is an implicit method given by the following finite difference scheme [6]:

$$\begin{cases} y_0 = x_0 \\ y_{n+1} = y_n + hf\left(\frac{y_{n+1} + y_n}{2}\right), \end{cases} \quad (5)$$

where $h > 0$ is a time step. It is known that if $f : \mathbb{R}^M \rightarrow \mathbb{R}^M$ is Lipschitz continuous and sufficiently smooth, then the sequence $\{y_n\}$ converges to the exact solution of (4) as $h \rightarrow 0$ uniformly over $t \in [t_0, t^*]$ for any fixed $t^* > 0$.

Based on IMR (5), Xu et al. [23] applied the viscosity approximation method introduced by Moudafi [13] to the IMR for a nonexpansive mapping T and proposed the following viscosity implicit midpoint rule (VIMR) in Hilbert spaces H as follows:

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)T\left(\frac{x_{n+1} + x_n}{2}\right), \quad n \geq 1 \quad (6)$$

where $\{\alpha_n\}$ is a real control condition in $(0, 1)$. They also proved that the sequence $\{x_n\}$ generated by (6) converges strongly to a point $x^* \in F(T)$, which solves the variational inequality

$$\langle x^* - f(x^*), x^* - p \rangle \leq 0, \quad \forall p \in F(T). \quad (7)$$

Recently, Ke and Ma [25] improved the VIMR by replacing the midpoint by any point of the interval $[x_n, x_{n+1}]$. They constructed the so-called method generalized viscosity implicit rules (GVIR) for a nonexpansive mapping as follows:

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)T(s_n x_n + (1 - s_n)x_{n+1}), \quad n \geq 1. \quad (8)$$

They showed that $\{x_n\}$ defined by (8) converges strongly to $x^* \in F(T)$, which solves the variational inequality problem (1).

In numerical analysis, it is clear that the computation by the IMR is not an easy work in practice. Because the IMR need to compute at every time steps, it can be much harder to implement. To overcome this difficulty, for solving (4), we consider the helpful method, the so-called explicit midpoint method (EMR), given by the following finite difference scheme

$$\begin{cases} y_0 = x_0 \\ \bar{y}_{n+1} = y_n + hf(y_n), \\ y_{n+1} = y_n + hf\left(\frac{\bar{y}_{n+1} + y_n}{2}\right). \end{cases} \quad (9)$$

It is easy to see that the explicit midpoint method calculates the state of a system at the next time from the state of the system at the current time [7].

In 2017, Marino et al. [15] applied the sequence (8) and the explicit midpoint method (9) to established the following so-called general viscosity explicit rule for quasi-nonexpansive mappings T in Hilbert spaces:

$$\begin{cases} \bar{x}_{n+1} = \beta_n x_n + (1 - \beta_n)T x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)T(s_n x_n + (1 - s_n)\bar{x}_{n+1}) \end{cases} \quad (10)$$

where f is a contraction and $\{\alpha_n\}$, $\{\beta_n\}$, and $\{s_n\}$ are the sequences in $(0, 1)$. They proved, under suitable conditions on the sequence parameters, that the generalized viscosity explicit rule (10) strongly converges to the set of $F(T)$, which is also the solution of the variational inequality problem (1).

Recently, Sow et al.[19] motivated by the fact that Mann algorithm method is remarkably useful for finding fixed points of nonexpansive mapping, proved the following theorem.

Theorem 1.2 (Sow et al. [19]). *Let E be a uniformly smooth real Banach space having a weakly continuous duality map and K a nonempty, closed and convex cone of E . Let $T : K \rightarrow K$ be a nonexpansive mapping with $F(T) \neq \emptyset$. Let $\{\lambda_n\}$ and $\{\alpha_n\}$ be two sequences in $(0, 1)$. Let $\{x_n\}$ be a sequence defined iteratively from arbitrary $x_0 \in K$ by:*

$$x_{n+1} = \alpha_n(\lambda_n x_n) + (1 - \alpha_n)Tx_n. \quad (11)$$

Suppose the following conditions hold:

$$(i) \lim_{n \rightarrow \infty} \alpha_n = 0; \quad (ii) \sum_{n=0}^{\infty} \alpha_n = \infty \text{ and } \sum_{n=0}^{\infty} |\alpha_n - \alpha_{n+1}| < \infty$$

$$(iii) \lim_{n \rightarrow \infty} \lambda_n = 1, \sum_{n=0}^{\infty} (1 - \lambda_n) \alpha_n = \infty, \text{ and } \sum_{n=0}^{\infty} |\lambda_n - \lambda_{n+1}| < \infty$$

Then, the sequence $\{x_n\}$ generated by (11) converges strongly to $x^* \in F(T)$.

Motivated and inspired by the above works, the purpose of the paper is to construct an iterative algorithm based on a modified Mann iterative scheme and prove strong convergence theorems for finding a common fixed points of an infinite family of quasi-nonexpansive mappings in real Banach spaces having a weakly continuous duality maps. No compactness assumption is made. The algorithm and results presented in this paper improve and extend some recent results. Finally, our method of proof is of independent interest.

2. Preliminaries

Let E be a Banach space with norm $\|\cdot\|$ and dual E^* . For any $x \in E$ and $x^* \in E^*$, $\langle x^*, x \rangle$ is used to refer to $x^*(x)$. Let $\varphi : [0, +\infty) \rightarrow [0, \infty)$ be a strictly increasing continuous function such that $\varphi(0) = 0$ and $\varphi(t) \rightarrow +\infty$ as $t \rightarrow \infty$. Such a function φ is called gauge. Associated to a gauge a duality map $J_\varphi : E \rightarrow 2^{E^*}$ defined by:

$$J_\varphi(x) := \{x^* \in E^* : \langle x, x^* \rangle = \|x\|\varphi(\|x\|), \|x^*\| = \varphi(\|x\|)\}, x \in E. \tag{12}$$

If the gauge is defined by $\varphi(t) = t$, then the corresponding duality map is called the *normalized duality map* and is denoted by J . Hence the normalized duality map is given by

$$J(x) := \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2 =\}, \forall x \in E.$$

Notice that

$$J_\varphi(x) = \frac{\varphi(\|x\|)}{\|x\|} J(x), x \neq 0.$$

Let E be a real normed space and let $S := \{x \in E : \|x\| = 1\}$. E is said to be *smooth* if the limit

$$\lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$$

exists for each $x, y \in S$. It is known that E is smooth if and only if each duality map J_φ is single-valued, that E is Frechet differentiable if and only if each duality map J_φ is norm-to-norm continuous in E , and that E is uniformly smooth if and only if each duality map J_φ is norm-to-norm uniformly continuous on bounded subsets of E .

Following Browder [2], we say that a Banach space has a weakly continuous duality map if there exists a gauge φ such that J_φ is single-valued and is weak-to-weak* sequentially continuous, i.e., if $(x_n) \subset E, x_n \xrightarrow{w} x$, then $J_\varphi(x_n) \xrightarrow{w^*} J_\varphi(x)$. It is known that l^p ($1 < p < \infty$) has a weakly continuous duality map with gauge $\varphi(t) = t^{p-1}$. (see [3] for more details on duality maps). Finally recall that a Banach space E satisfies Opial property (see, e.g., [15]) if $\limsup_{n \rightarrow +\infty} \|x_n - x\| < \limsup_{n \rightarrow +\infty} \|x_n - y\|$ whenever $x_n \xrightarrow{w} x, x \neq y$. A Banach space E that has a weakly continuous duality map satisfies Opial's property.

The following lemma can be found in [5].

Lemma 2.1 (Demiclosedness principle [5]). *Let E be a reflexive Banach space satisfying Opial's property, K be a closed convex subset of E , and $T : K \rightarrow K$ be a nonexpansive mapping. Then $I - T$ is demiclosed; that is,*

$$\{x_n\} \subset K, x_n \rightharpoonup x \in K \text{ and } (I - T)x_n \rightarrow y \text{ implies that } (I - T)x = y.$$

Lemma 2.2 ([9]). Assume that a Banach space E has a weakly continuous duality mapping J_φ with gauge φ .

$$\Phi(\|x + y\|) \leq \Phi(\|x\|) + \langle y, J_\varphi(x + y) \rangle$$

for all $x, y \in E$.

In particular, for all $x, y \in E$,

$$\|x + y\|^2 \leq \|x\|^2 + 2\langle y, J(x + y) \rangle.$$

Lemma 2.3. (Xu, [21], Zălinescu [25]) Let E be a uniformly convex real Banach space. For arbitrary $r > 0$, let $B_r := \{x \in E : \|x\| \leq r\}$ and $\beta_n \in [0, 1]$. Then there exists a continuous, strictly increasing and convex function

$$g : [0, 2r] \rightarrow \mathbb{R}^+, \quad g(0) = 0$$

such that for all $x, y \in B_r$

$$\|\beta_n x + (1 - \beta_n)y\|^2 \leq \beta_n \|x\|^2 + (1 - \beta_n)\|y\|^2 - (1 - \beta_n)\beta_n g(\|x - y\|).$$

Lemma 2.4 (Xu, [22]). Assume that $\{a_n\}$ is a sequence of nonnegative real numbers such that $a_{n+1} \leq (1 - \alpha_n)a_n + \alpha_n \sigma_n$ for all $n \geq 0$, where $\{\alpha_n\}$ is a sequence in $(0, 1)$ and $\{\sigma_n\}$ is a sequence in \mathbb{R} such that

$$(a) \sum_{n=0}^{\infty} \alpha_n = \infty, \quad (b) \limsup_{n \rightarrow \infty} \sigma_n \leq 0 \text{ or } \sum_{n=0}^{\infty} |\sigma_n \alpha_n| < \infty. \text{ Then } \lim_{n \rightarrow \infty} a_n = 0.$$

Lemma 2.5. [11] Let t_n be a sequence of real numbers that does not decrease at infinity in a sense that there exists a subsequence t_{n_i} of t_n such that $t_{n_i} \leq t_{n_{i+1}}$ for all $i \geq 0$. For sufficiently large numbers $n \in \mathbb{N}$, an integer sequence $\{\tau(n)\}$ is defined as follows:

$$\tau(n) = \max\{k \leq n : t_k \leq t_{k+1}\}.$$

Then, $\tau(n) \rightarrow \infty$ as $n \rightarrow \infty$ and

$$\max\{t_{\tau(n)}, t_n\} \leq t_{\tau(n)+1}.$$

Lemma 2.6 (Aoyama et. al [1], Nilsrakoo et al. [14]). Let K be a nonempty closed subset of a Banach space and let $\{T_n\}_{n \geq 0}$ be a sequence of mappings of K into itself. Suppose that $\sum_{n=0}^{\infty} \sup \left\{ \|T_{n+1}x - T_nx\| : x \in B \right\} < \infty$ for any bounded subset B of K . Then, for any $x \in K$ $\{T_nx\}$ converges strongly to some point of K . Moreover, let T be a mapping of K into itself defined by $Tx = \lim_{n \rightarrow \infty} T_nx$ for all $x \in K$. Then,

$$\lim_{n \rightarrow \infty} \sup_{x \in K} \|T_nx - Tx\| = 0.$$

Let C be a nonempty subsets of real Banach space E . A mapping $Q_C : E \rightarrow C$ is said to be sunny if

$$Q_C(Q_Cx + t(x - Q_Cx)) = Q_Cx$$

for each $x \in E$ and $t \geq 0$. A mapping $Q_C : E \rightarrow C$ is said to be a retraction if $Q_Cx = x$ for each $x \in C$.

Lemma 2.7. [17] Let C and D be nonempty subsets of a real Banach space E with $D \subset C$ and $Q_D : C \rightarrow D$ a retraction from C into D . Then Q_D is sunny and nonexpansive if and only if

$$\langle z - Q_Dz, j(y - Q_Dz) \rangle \leq 0$$

for all $z \in C$ and $y \in D$.

It is noted that Lemma 2.7 still holds if the normalized duality map is replaced by the general duality map J_φ , where φ is gauge function.

Remark 2.8. If K is a nonempty closed convex subset of a Hilbert space H , then the nearest point projection P_K from H to K is the sunny nonexpansive retraction.

3. Mains results

Throughout this section, we assume that E be a uniformly convex real Banach space having a weakly continuous duality map J_φ and K be a nonempty, closed and convex cone of E . For each $n = 0, 1, \dots$, let $T_n : K \rightarrow K$ be a quasi-nonexpansive mapping such that $F := \bigcap_{n=0}^\infty F(T_n) \neq \emptyset$.

Now, we present the following iterative algorithm.

Algorithm 3.1. Let $\{x_n\}$ be a sequence defined iteratively from arbitrary $x_0 \in K$ by:

$$\begin{cases} \bar{x}_{n+1} = \beta_n x_n + (1 - \beta_n) T_n x_n, \\ x_{n+1} = \alpha_n (\lambda_n x_n) + (1 - \alpha_n) T_n (s_n x_n + (1 - s_n) \bar{x}_{n+1}), \end{cases} \tag{13}$$

$\{\beta_n\}$, $\{\lambda_n\}$, $\{s_n\}$ and $\{\alpha_n\}$ be sequences in $(0, 1)$ satisfying:

(i) $\lim_{n \rightarrow \infty} \alpha_n = 0$; (ii) $\liminf_{n \rightarrow \infty} (1 - s_n) \beta_n (1 - \beta_n) > 0$.

(iii) $\lim_{n \rightarrow \infty} \lambda_n = 1$ and $\sum_{n=0}^\infty (1 - \lambda_n) \alpha_n = \infty$.

For strong convergence of our Algorithm, we assume the following assumptions.

Assumption 3.2. (a) $\sum_{n=0}^\infty \sup \{ \|T_{n+1}x - T_nx\| : x \in B \} < \infty$ for any bounded subset B of K and $F(T) =$

$\bigcap_{n=0}^\infty F(T_n)$ where T be a mapping of K into itself defined by $Tx = \lim_{n \rightarrow \infty} T_nx$ for all $x \in K$.

(b) $I - T$ is demiclosed at the origin.

We now prove the following results.

Theorem 3.3. Let Assumptions 3.2 hold. Then, the sequence $\{x_n\}$ generated by (13) converges strongly to $x^* \in F$ where $x^* = Q_F(0)$ with Q_F the sunny nonexpansive retraction of K onto F .

Proof. For each $n \geq 0$, we put $z_n := s_n x_n + (1 - s_n) \bar{x}_{n+1}$. Let $p \in F$, from (13) and T_n is quasi-nonexpansive, we have

$$\begin{aligned} \|z_n - p\| &= \|s_n x_n + (1 - s_n) \bar{x}_{n+1} - p\| \\ &\leq s_n \|x_n - p\| + (1 - s_n) \|\bar{x}_{n+1} - p\| \\ &\leq s_n \|x_n - p\| + (1 - s_n) \|\beta_n x_n + (1 - \beta_n) T_n x_n - p\| \\ &\leq s_n \|x_n - p\| + (1 - s_n) [\beta_n \|x_n - p\| + (1 - \beta_n) \|T_n x_n - p\|] \end{aligned}$$

Hence,

$$\|z_n - p\| \leq \|x_n - p\|. \tag{14}$$

Now, we prove that the sequence $\{x_n\}$ is bounded. Let $p \in F$.

Using (13) and inequality (14), we have

$$\begin{aligned} \|x_{n+1} - p\| &= \|\alpha_n (\lambda_n x_n) + (1 - \alpha_n) T_n z_n - p\| \\ &\leq \alpha_n \lambda_n \|x_n - p\| + (1 - \alpha_n) \|T_n z_n - p\| + (1 - \lambda_n) \alpha_n \|p\| \\ &\leq \alpha_n \lambda_n \|x_n - p\| + (1 - \alpha_n) \|x_n - p\| + (1 - \lambda_n) \alpha_n \|p\| \\ &\leq [1 - (1 - \lambda_n) \alpha_n] \|x_n - p\| + (1 - \lambda_n) \alpha_n \|p\| \\ &\leq \max \{ \|x_n - p\|, \|p\| \}. \end{aligned}$$

By induction, it is easy to see that

$$\|x_n - p\| \leq \max \{\|x_0 - p\|, \|p\|\}, \quad n \geq 1.$$

Hence $\{x_n\}$ is bounded also are $\{\bar{x}_n\}$, and $\{T_n x_n\}$.

Using Lemma 2.3, convexity of $\|\cdot\|^2$ and (13), we have

$$\begin{aligned} \|T_n z_n - p\|^2 &\leq \|z_n - p\|^2 \\ &= \|s_n x_n + (1 - s_n)\bar{x}_{n+1} - p\|^2 \\ &\leq s_n \|x_n - p\|^2 + (1 - s_n) \|\bar{x}_{n+1} - p\|^2 \\ &\leq s_n \|x_n - p\|^2 + (1 - s_n) \|\beta_n x_n + (1 - \beta_n)T_n x_n - p\|^2 \\ &\leq s_n \|x_n - p\|^2 + (1 - s_n) \left[\beta_n \|x_n - p\|^2 + (1 - \beta_n) \|T_n x_n - p\|^2 \right. \\ &\quad \left. - \beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \right] \\ &\leq \|x_n - p\|^2 - (1 - s_n)\beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \end{aligned}$$

Hence,

$$\|T_n z_n - p\|^2 \leq \|x_n - p\|^2 - \beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|). \quad (15)$$

Therefore, by Lemma 2.2 and inequality (15), we have

$$\begin{aligned} \|x_{n+1} - p\|^2 &= \|\alpha_n(\lambda_n x_n) + (1 - \alpha_n)T_n z_n - p\|^2 \\ &= \|\alpha_n \lambda_n (x_n - p) + (1 - \alpha_n)(T_n z_n - p) - (1 - \lambda_n)\alpha_n p\|^2 \\ &\leq \|\alpha_n(\lambda_n x_n - \lambda_n p) + (1 - \alpha_n)(T_n z_n - p)\|^2 + 2(1 - \lambda_n)\alpha_n \langle p, J(p - x_{n+1}) \rangle \\ &\leq \alpha_n \lambda_n^2 \|x_n - p\|^2 + (1 - \alpha_n) \|T_n z_n - p\|^2 + 2(1 - \lambda_n)\alpha_n \langle p, J(p - x_{n+1}) \rangle \\ &\leq \alpha_n \lambda_n \|x_n - p\|^2 + (1 - \alpha_n) \left[\|x_n - p\|^2 - \beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \right] \\ &\quad + 2(1 - \lambda_n)\alpha_n \langle p, J(p - x_{n+1}) \rangle \\ &\leq [1 - (1 - \lambda_n)\alpha_n] \|x_n - p\|^2 - (1 - \alpha_n)\beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \\ &\quad + 2(1 - \lambda_n)\alpha_n \langle p, J(p - x_{n+1}) \rangle. \end{aligned}$$

Therefore,

$$(1 - \alpha_n)\beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \leq \|x_n - p\|^2 - \|x_{n+1} - p\|^2 + 2(1 - \lambda_n)\alpha_n \langle p, J(p - x_{n+1}) \rangle. \quad (16)$$

Since $\{x_n\}$ is bounded, then there exists a constant $B > 0$ such that

$$(1 - \lambda_n)\langle p, J(p - x_{n+1}) \rangle \leq B, \quad \text{for all, } n \geq 0.$$

Hence,

$$(1 - \alpha_n)\beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) \leq \|x_n - p\|^2 - \|x_{n+1} - p\|^2 + 2\alpha_n B. \quad (17)$$

Now we prove that $\{x_n\}$ converges strongly to x^* .

We divide the proof into two cases.

Case 1. Assume that the sequence $\{\|x_n - p\|\}$ is monotonically decreasing sequence. Then $\{\|x_n - p\|\}$ is convergent. Clearly, we have

$$\|x_n - p\|^2 - \|x_{n+1} - p\|^2 \rightarrow 0.$$

It then implies from (17) that

$$\lim_{n \rightarrow \infty} (1 - \alpha_n)\beta_n(1 - \beta_n)g(\|x_n - T_n x_n\|) = 0. \quad (18)$$

Using the fact that $\liminf_{n \rightarrow \infty} (1 - s_n)\beta_n(1 - \beta_n) > 0$ and property of g , we have

$$\lim_{n \rightarrow \infty} \|x_n - T_n x_n\| = 0. \tag{19}$$

We observe that,

$$\|x_n - T x_n\| \leq \|x_n - T_n x_n\| + \|T_n x_n - T x_n\|. \tag{20}$$

By inequalities (19), (20) and Lemma 2.6, we have

$$\lim_{n \rightarrow \infty} \|x_n - T x_n\| = 0. \tag{21}$$

Next, we prove that $\limsup_{n \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_n) \rangle$. Since E is reflexive and $\{x_n\}$ is bounded, there exists a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that x_{n_k} converges weakly to a in K and

$$\limsup_{n \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_n) \rangle = \lim_{k \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_{n_k}) \rangle.$$

From (21) and $I - T$ is demiclosed, we obtain $a \in F$. On other hand, the assumption that the duality mapping J_φ is weakly continuous, the fact that $x^* = Q_F(0)$ and Lemma 2.7, we then have

$$\begin{aligned} \limsup_{n \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_n) \rangle &= \lim_{k \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_{n_k}) \rangle \\ &= \langle x^*, J_\varphi(x^* - a) \rangle \leq 0. \end{aligned}$$

Finally, we show that $x_n \rightarrow x^*$. In fact, since $\Phi(t) = \int_0^t \varphi(\sigma) d\sigma, \forall t \geq 0$, and φ is a gauge function, then for $1 \geq k \geq 0, \Phi(kt) \leq k\Phi(t)$. From (13) and Lemma 2.2, we get that

$$\begin{aligned} \Phi(\|x_{n+1} - x^*\|) &= \Phi(\|\alpha_n(\lambda_n x_n) + (1 - \alpha_n)T_n z_n - x^*\|) \\ &\leq \Phi(\|\alpha_n \lambda_n (x_n - x^*) + (1 - \alpha_n)(T_n z_n - x^*)\|) + (1 - \lambda_n)\alpha_n \langle x^*, J_\varphi(x^* - x_{n+1}) \rangle \\ &\leq \Phi(\alpha_n \lambda_n \|x_n - x^*\| + \|(1 - \alpha_n)(T_n z_n - x^*)\|) + (1 - \lambda_n)\alpha_n \langle x^*, J_\varphi(x^* - x_{n+1}) \rangle \\ &\leq \Phi(\alpha_n \lambda_n \|x_n - x^*\| + (1 - \alpha_n)\|x_n - x^*\|) + (1 - \lambda_n)\alpha_n \langle x^*, J_\varphi(x^* - x_{n+1}) \rangle \\ &\leq \Phi((1 - (1 - \lambda_n)\alpha_n)\|x_n - x^*\|) + (1 - \lambda_n)\alpha_n \langle x^*, J_\varphi(x^* - x_{n+1}) \rangle \\ &\leq [1 - (1 - \lambda_n)\alpha_n]\Phi(\|x_n - x^*\|) + (1 - \lambda_n)\alpha_n \langle x^*, J_\varphi(x^* - x_{n+1}) \rangle. \end{aligned}$$

From Lemma 2.4, it follows that $x_n \rightarrow x^*$.

Case 2. Assume that the sequence $\{\|x_n - x^*\|\}$ is not monotonically decreasing sequence. Set $B_n = \|x_n - x^*\|$ and $\tau : \mathbb{N} \rightarrow \mathbb{N}$ be a mapping for all $n \geq n_0$ (for some n_0 large enough) by $\tau(n) = \max\{k \in \mathbb{N} : k \leq n, B_k \leq B_{k+1}\}$.

We have τ is a non-decreasing sequence such that $\tau(n) \rightarrow \infty$ as $n \rightarrow \infty$ and $B_{\tau(n)} \leq B_{\tau(n)+1}$ for $n \geq n_0$. From (17), we have

$$(1 - \alpha_{\tau(n)})\beta_{\tau(n)}(1 - \beta_{\tau(n)})g(\|x_{\tau(n)} - T_{\tau(n)}x_{\tau(n)}\|) \leq 2\alpha_{\tau(n)}B \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Hence,

$$\lim_{n \rightarrow \infty} \|x_{\tau(n)} - T_{\tau(n)}x_{\tau(n)}\| = 0. \tag{22}$$

At the same time, we observe that

$$\|x_{\tau(n)} - T x_{\tau(n)}\| \leq \|x_{\tau(n)} - T_{\tau(n)}x_{\tau(n)}\| + \|T_{\tau(n)}x_{\tau(n)} - T x_{\tau(n)}\|. \tag{23}$$

Thanks inequalities (22), (23) and Lemma 2.6, we have

$$\lim_{n \rightarrow \infty} \|x_{\tau(n)} - T x_{\tau(n)}\| = 0.$$

By same argument as in case 1, we can show that $x_{\tau(n)}$ converges weakly in E and $\limsup_{n \rightarrow +\infty} \langle x^*, J_\varphi(x^* - x_{\tau(n)}) \rangle \leq 0$. We have for all $n \geq n_0$,

$$0 \leq \Phi(\|x_{\tau(n)+1} - x^*\|) - \Phi(\|x_{\tau(n)} - x^*\|) \leq (1 - \lambda_{\tau(n)})\alpha_{\tau(n)}[-\Phi(\|x_{\tau(n)} - x^*\|) + \langle x^*, J_\varphi(x^* - x_{\tau(n)+1}) \rangle],$$

which implies that

$$\Phi(\|x_{\tau(n)} - x^*\|) \leq \langle x^*, J_\varphi(x^* - x_{\tau(n)+1}) \rangle.$$

Then, we have

$$\lim_{n \rightarrow \infty} \Phi(\|x_{\tau(n)} - x^*\|) = 0.$$

Therefore,

$$\lim_{n \rightarrow \infty} B_{\tau(n)} = \lim_{n \rightarrow \infty} B_{\tau(n)+1} = 0.$$

Thus, by Lemma 2.5, we conclude that

$$0 \leq B_n \leq \max\{B_{\tau(n)}, B_{\tau(n)+1}\} = B_{\tau(n)+1}.$$

Hence, $\lim_{n \rightarrow \infty} B_n = 0$, that is $\{x_n\}$ converges strongly to x^* . This completes the proof. □

Remark 3.4. let $\{T_n\}_{n \geq 0}$ be a sequence of nonexpansive mappings of K into K , let $\{\lambda_n\}_{n \geq 0}$ be a sequence of real number such that and $0 \leq \lambda_n \leq 1$. For each $n \geq 0$, we define a mapping W_n of K into K as follows:

$$\begin{aligned} U_{n,n+1} &= I, \\ U_{n,n} &= \lambda_n T_n U_{n,n+1} + (1 - \lambda_n)I, \\ U_{n,n-1} &= \lambda_{n-1} T_{n-1} U_{n,n} + (1 - \lambda_{n-1})I, \\ &\vdots \\ U_{n,k} &= \lambda_k T_k U_{n,k+1} + (1 - \lambda_k)I, \\ &\vdots \\ U_{n,2} &= \lambda_2 T_2 U_{n,3} + (1 - \lambda_2)I, \\ W_n &= U_{n,1} = \lambda_1 T_1 U_{n,2} + (1 - \lambda_1)I. \end{aligned} \tag{24}$$

Such that is called W_n is the so called W -mapping generated by an countable infinite family of nonexpansive mappings $T_1, T_2, \dots, T_n, \dots$ and scalars $\lambda_1, \lambda_2, \dots, \lambda_n, \dots$ such that the common fixed points set $F := \bigcap_{n=1}^\infty F(T_n) \neq \emptyset$, see for example [20]. Clearly, W_n is nonexpansive and from [20], we know that $\bigcap_{n=1}^\infty F(T_n) = F(W_n)$.

Furthermore, from [16], we have the sequence $\{W_n\}_{n \geq 1}$ satisfies the condition $\sum_{n=0}^\infty \sup \left\{ \|W_{n+1}x - W_nx\| : x \in B \right\} < \infty$ for any bounded subset B of K imposed in Theorem 3.3.

By above remark, Lemma 2.1 and the fact that nonexpansive mapping is quasi-nonexpansive. We obtain the following results.

Theorem 3.5. Let E be a uniformly convex real Banach space having a weakly continuous duality map J_φ and K be a nonempty, closed and convex cone of E . For each $n = 0, 1, \dots$, let $T_n : K \rightarrow K$ be a nonexpansive mapping such that $F := \bigcap_{n=0}^\infty F(T_n) \neq \emptyset$. Let $\{x_n\}$ be a sequence defined iteratively from arbitrary $x_0 \in K$ by:

$$\begin{cases} \bar{x}_{n+1} = \beta_n x_n + (1 - \beta_n)W_n x_n, \\ x_{n+1} = \alpha_n(\lambda_n x_n) + (1 - \alpha_n)W_n(s_n x_n + (1 - s_n)\bar{x}_{n+1}) \end{cases} \tag{25}$$

$\{\beta_n\}, \{\lambda_n\}, \{s_n\}$ and $\{\alpha_n\}$ be a sequences in $(0, 1)$ satisfying:

(i) $\lim_{n \rightarrow \infty} \alpha_n = 0$; (ii) $\liminf_{n \rightarrow \infty} (1 - s_n)\beta_n(1 - \beta_n) > 0$.

(iii) $\lim_{n \rightarrow \infty} \lambda_n = 1$ and $\sum_{n=0}^{\infty} (1 - \lambda_n)\alpha_n = \infty$.

Then, the sequence $\{x_n\}$ generated by (25) converges strongly to $x^* \in F$ where $x^* = Q_F(0)$ with Q_F the sunny nonexpansive retraction of K onto F .

We apply Theorem 3.3 to approximate fixed points of quasi-nonexpansive mappings.

Corollary 3.6. Let E be a uniformly convex real Banach space having a weakly continuous duality map J_φ and K be a nonempty, closed and convex cone of E . Let $T : K \rightarrow K$ be a quasi-nonexpansive mapping such that $F(T) \neq \emptyset$. Let $\{x_n\}$ be a sequence defined iteratively from arbitrary $x_0 \in K$ by:

$$\begin{cases} \bar{x}_{n+1} = \beta_n x_n + (1 - \beta_n) T x_n, \\ x_{n+1} = \alpha_n (\lambda_n x_n) + (1 - \alpha_n) T (s_n x_n + (1 - s_n) \bar{x}_{n+1}) \end{cases} \tag{26}$$

$\{\beta_n\}, \{\lambda_n\}, \{s_n\}$ and $\{\alpha_n\}$ be sequences in $(0, 1)$ satisfying:

(i) $\lim_{n \rightarrow \infty} \alpha_n = 0$; (ii) $\liminf_{n \rightarrow \infty} (1 - s_n)\beta_n(1 - \beta_n) > 0$.

(iii) $\lim_{n \rightarrow \infty} \lambda_n = 1$ and $\sum_{n=0}^{\infty} (1 - \lambda_n)\alpha_n = \infty$.

Assume that $I - T$ is demiclosed at the origin. Then, the sequence $\{x_n\}$ generated by (26) converges strongly to $x^* \in F(T)$ where $x^* = Q_{F(T)}(0)$ with $Q_{F(T)}$ the sunny nonexpansive retraction of K onto $F(T)$.

Remark 3.7. In our theorems, we assume that K is a cone. But, in some cases, for example, if K is the closed unit ball, we can weaken this assumption to the following: $\lambda x \in K$ for all $\lambda \in (0, 1)$ and $x \in K$. Therefore, in the case where E is a real Hilbert space or $E = l_p, 1 < p < \infty$, our results can be used to approximate fixed points of an infinite family of quasi-nonexpansive mappings from the closed unit ball to itself.

Corollary 3.8. Assume that $E = l_p, 1 < p < \infty$ or E is a real Hilbert space. Let B be the closed unit ball of E . For each $n = 0, 1, \dots$, let $T_n : B \rightarrow B$ be a quasi-nonexpansive mapping such that $F := \bigcap_{n=0}^{\infty} F(T_n) \neq \emptyset$.

Let $\{x_n\}$ be a sequence defined iteratively from arbitrary $x_0 \in B$ by:

$$\begin{cases} \bar{x}_{n+1} = \beta_n x_n + (1 - \beta_n) T_n x_n, \\ x_{n+1} = \alpha_n (\lambda_n x_n) + (1 - \alpha_n) T_n (s_n x_n + (1 - s_n) \bar{x}_{n+1}) \end{cases} \tag{27}$$

$\{\beta_n\}, \{\lambda_n\}, \{s_n\}$ and $\{\alpha_n\}$ be sequences in $(0, 1)$ satisfying:

(i) $\lim_{n \rightarrow \infty} \alpha_n = 0$; (ii) $\liminf_{n \rightarrow \infty} (1 - s_n)\beta_n(1 - \beta_n) > 0$.

(iii) $\lim_{n \rightarrow \infty} \lambda_n = 1$ and $\sum_{n=0}^{\infty} (1 - \lambda_n)\alpha_n = \infty$.

Let Assumptions 3.2 hold. Then, the sequence $\{x_n\}$ generated by (27) converges strongly to $x^* \in F$ where $x^* = Q_F(0)$ with Q_F the sunny nonexpansive retraction of K onto F .

Now, we give some remarks on our results as follows:

(1) The proof methods of our results are very different from the ones of Sow et al.[19] (see, Corollary 3.6) and we extend results of Sow et al. from nonexpansive mappings to quasi-nonexpansive mappings. Further, we

remove the following conditions: $\sum_{n=0}^{\infty} |\alpha_n - \alpha_{n+1}| < \infty$ and $\sum_{n=0}^{\infty} |\lambda_n - \lambda_{n+1}| < \infty$, $\sum_{n=0}^{\infty} \alpha_n = \infty$, in Theorem 1.2 of [19] (see, Corollary 3.6).

(2) Our results improve many recent results using Mann's method to approximate fixed points of nonexpansive mappings.

(3) Our results are applicable for finding minimum-norm fixed points of an infinite family of quasi-nonexpansive mappings in Hilbert spaces.

Remark 3.9. Let $\alpha_n = \frac{1}{10n+1}$, $\beta_n = \frac{1}{20n+1} + 0.4$, $s_n = \frac{1}{30n+1} + 0.3$ and $\lambda_n = 1 - \frac{1}{\sqrt{n}}$. It is easy to see that the sequences $\{\alpha_n\}$, $\{\beta_n\}$, $\{s_n\}$ and $\{\lambda_n\}$ satisfy the conditions (i), (ii) and (iii) of Theorem 3.3.

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