

***g*-NATURAL METRICS ON THE COTANGENT BUNDLE**

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ABSTRACT. The main aim of this paper is to investigate curvature properties and geodesics of the *g*-natural metric on the cotangent bundle of Riemannian manifold.

1. INTRODUCTION

Let (M^n, g) be an *n*-dimensional Riemannian manifold, T^*M^n its cotangent bundle and π the natural projection $T^*M^n \rightarrow M^n$. A system of local coordinates $(U, x^i), i = 1, \dots, n$ on M^n induces on T^*M^n a system of local coordinates $(\pi^{-1}(U), x^i, x^{\bar{i}} = p_i), \bar{i} := n + i (i = 1, \dots, n)$, where $x^{\bar{i}} = p_i$ are the components of covectors p in each cotangent space $T_x^*M^n, x \in U$ with respect to the natural coframe $\{dx^i\}, i = 1, \dots, n$.

We denote by $\mathfrak{S}_s^r(M^n)(\mathfrak{S}_s^r(T^*M^n))$ the module over $F(M^n)(F(T^*M^n))$ of C^∞ tensor fields of type (r, s) , where $F(M^n)(F(T^*M^n))$ is the ring of real-valued C^∞ functions on $M^n(T^*M^n)$.

Let $X = X^i \frac{\partial}{\partial x^i}$ and $\omega = \omega_i dx^i$ be the local expressions in $U \subset M^n$ of a vector and a covector (1-form) field $X \in \mathfrak{S}_0^1(M^n)$ and $\omega \in \mathfrak{S}_1^0(M^n)$, respectively. Then the complete and horizontal lifts ${}^C X, {}^H X \in \mathfrak{S}_0^1(T^*M^n)$ of $X \in \mathfrak{S}_0^1(M^n)$ and the vertical lift ${}^V \omega \in \mathfrak{S}_0^1(T^*M^n)$ of $\omega \in \mathfrak{S}_1^0(M^n)$ are given, respectively, by

$$(1.1) \quad {}^C X = X^i \frac{\partial}{\partial x^i} - \sum_i p_h \partial_i X^h \frac{\partial}{\partial x^{\bar{i}}},$$

$$(1.2) \quad {}^H X = X^i \frac{\partial}{\partial x^i} + \sum_i p_h \Gamma_{ij}^h X^j \frac{\partial}{\partial x^{\bar{i}}},$$

$$(1.3) \quad {}^V \omega = \sum_i \omega_i \frac{\partial}{\partial x^{\bar{i}}},$$

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with respect to the natural frame $\{\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^i}\}$, where Γ_{ij}^h are the components of the Levi-Civita connection ∇_g on M^n (see [19] for more details).

Theorem 1.1. *Let M^n be a Riemannian manifold with metric g , ∇ be the Levi-Civita connection and R be the Riemannian curvature tensor. Then the Lie bracket of the cotangent bundle T^*M^n of M^n satisfies the following*

$$(1.4) \quad \begin{aligned} i) \quad & [{}^V\omega, {}^V\theta] = 0, \\ ii) \quad & [{}^H X, {}^V\omega] = {}^V(\nabla_X\omega), \\ iii) \quad & [{}^H X, {}^H Y] = {}^H[X, Y] + \gamma R(X, Y) = {}^H[X, Y] + {}^V(pR(X, Y)) \end{aligned}$$

for all $X, Y \in \mathfrak{S}_0^1(M^n)$ and $\omega, \theta \in \mathfrak{S}_1^0(M^n)$. (See [19, p.238, p.277] for more details)

Definition 1.1. Let M^n be a Riemannian manifold with metric g . A Riemannian metric \bar{g} on cotangent bundle T^*M^n is said to be natural with respect to g on M^n if

$$(1.5) \quad \begin{aligned} i) \quad & \bar{g}({}^H X, {}^H Y) = g(X, Y), \\ ii) \quad & \bar{g}({}^H X, {}^V\omega) = 0 \end{aligned}$$

for all $X, Y \in \mathfrak{S}_0^1(M^n)$ and $\omega, \theta \in \mathfrak{S}_1^0(M^n)$.

Theorem 1.2. *Let M^n be a Riemannian manifold with metric g and T^*M^n be the cotangent bundle of M^n . If the Riemannian metric \bar{g} on T^*M^n is natural with respect to g on M^n then the corresponding Levi-Civita connection $\bar{\nabla}$ satisfies*

$$(1.6) \quad \begin{aligned} i) \quad & \bar{g}(\bar{\nabla}_{{}^H X} {}^H Y, {}^H Z) = g(\nabla_X Y, Z), \\ ii) \quad & \bar{g}(\bar{\nabla}_{{}^H X} {}^H Y, {}^V\omega) = \frac{1}{2}\bar{g}({}^V\omega, {}^V(pR(X, Y))), \\ iii) \quad & \bar{g}(\bar{\nabla}_{{}^H X} {}^V\omega, {}^H Z) = \frac{1}{2}\bar{g}({}^V(pR(Z, X)), {}^V\omega, \cdot), \\ iv) \quad & \bar{g}(\bar{\nabla}_{{}^H X} {}^V\omega, {}^V\theta) = \frac{1}{2}({}^H X(\bar{g}({}^V\omega, {}^V\theta)) - \bar{g}({}^V\omega, {}^V(\nabla_X\theta)) \\ & \quad + \bar{g}({}^V\theta, {}^V(\nabla_X\omega))), \\ v) \quad & \bar{g}(\bar{\nabla}_{{}^V\omega} {}^H Y, {}^H Z) = -\frac{1}{2}\bar{g}({}^V\omega, {}^V(pR(Y, Z))), \\ vi) \quad & \bar{g}(\bar{\nabla}_{{}^V\omega} {}^H Y, {}^V\theta) = \frac{1}{2}({}^H Y(\bar{g}({}^V\omega, {}^V\theta)) - \bar{g}({}^V\omega, {}^V(\nabla_Y\theta)) \\ & \quad - \bar{g}({}^V\theta, {}^V(\nabla_Y\omega))), \\ vii) \quad & \bar{g}(\bar{\nabla}_{{}^V\omega} {}^V\theta, {}^H Z) = \frac{1}{2}(-{}^H Z(\bar{g}({}^V\omega, {}^V\theta)) + \bar{g}({}^V\omega, {}^V(\nabla_Z\theta)) \\ & \quad + \bar{g}({}^V\theta, {}^V(\nabla_Z\omega))), \\ viii) \quad & \bar{g}(\bar{\nabla}_{{}^V\omega} {}^V\theta, {}^V\xi) = \frac{1}{2}({}^V\omega(\bar{g}({}^V\theta, {}^V\xi)) + {}^V\theta(\bar{g}({}^V\xi, {}^V\omega)) - {}^V\xi(\bar{g}({}^V\omega, {}^V\theta))) \end{aligned}$$

for all $X, Y \in \mathfrak{S}_0^1(M^n)$ and $\omega, \theta \in \mathfrak{S}_1^0(M^n)$ [4].

Corollary 1.1. *Let M^n be a Riemannian manifold with metric g and \bar{g} be a natural metric on the cotangent bundle T^*M^n of M^n . Then the Levi-Civita connection $\bar{\nabla}$ satisfies*

$$(1.7) \quad \bar{\nabla}_{{}^H X} {}^H Y = {}^H(\nabla_X Y) + \frac{1}{2}{}^V(pR(X, Y))$$

for all $X, Y \in \mathfrak{S}_0^1(M^n)$ [4].

For each $x \in M^n$ the scalar product $g^{-1} = (g^{ij})$ is defined on the cotangent space $\pi^{-1}(x) = T_x^*M^n$ by

$$g^{-1}(\omega, \theta) = g^{ij}\omega_i\theta_j$$

for all $\omega, \theta \in \mathfrak{S}_1^0(M^n)$.

Definition 1.2. A g -natural metric \tilde{g} is defined on T^*M^n by the following three equations

$$(1.8) \quad \tilde{g}({}^H X, {}^H Y) = V(g(X, Y)) = g(X, Y) \circ \pi,$$

$$(1.9) \quad \tilde{g}({}^V \omega, {}^H Y) = 0,$$

$$(1.10) \quad \tilde{g}({}^V \omega, {}^V \theta) = \varphi(z)g^{-1}(\omega, \theta) + \psi(z)g^{-1}(\omega, p)g^{-1}(\theta, p)$$

for any $X, Y \in \mathfrak{S}_0^1(M^n)$ and $\omega, \theta \in \mathfrak{S}_1^0(M^n)$. Here φ and ψ are some functions of argument $z = \frac{1}{2}|p| = \frac{1}{2}g^{-1}(p, p)$ such that $\varphi > 0$ and $\varphi + 2z\psi > 0$.

Since any tensor field of type (0,2) on T^*M^n is completely determined by its action on vector fields of type ${}^H X$ and ${}^V \omega$, it follows that \tilde{g} is completely determined by its equations (1.8), (1.9) and (1.10).

The Sasaki metric is obtained for $\varphi(z) = 1$ and $\psi(z) = 0$, while the Cheeger-Gromoll metric for $\varphi(z) = \psi(z) = \frac{1}{1+r^2}$, $r^2 = g^{-1}(p, p)$. Sasaki, Cheeger-Gromoll and g -natural metrics are in the class of natural metric.

We now see, from (1.1) and (1.2), that the complete lift ${}^C X$ of $X \in \mathfrak{S}_0^1(M^n)$ is expressed by

$$(1.11) \quad {}^C X = {}^H X - V(p(\nabla X)),$$

where $p(\nabla X) = p_i(\nabla_h X^i)dx^h$.

Using (1.8), (1.9), (1.10) and (1.11), we have

$$(1.12) \quad \begin{aligned} \tilde{g}({}^C X, {}^C Y) &= V(g(X, Y)) + \varphi(z)(g^{-1}(p(\nabla X), p(\nabla Y))) \\ &+ \psi(z)g^{-1}(p(\nabla X), p)g^{-1}(p(\nabla Y), p), \end{aligned}$$

where $g^{-1}(p(\nabla X), p(\nabla Y)) = g^{ij}(p_l \nabla_i X^l)(p_k \nabla_j Y^k)$, $g^{-1}(p(\nabla X), p) = g^{ij}p_i(p(\nabla X))_j$.

Since the tensor field $\tilde{g} \in \mathfrak{S}_2^0(T^*M^n)$ is completely determined also by its action on vector fields type ${}^C X$ and ${}^C Y$ (see[19, p.237]), we have an alternative characterization of \tilde{g} on T^*M^n : \tilde{g} is completely determined by the condition (1.12).

The main purpose of this paper is to introduce Levi-Civita connection of g -natural type metric on the cotangent bundle T^*M^n of Riemannian manifold M^n and investigate curvature properties and geodesics on T^*M^n with respect to the Levi-Civita connection of \tilde{g} . Since the construction of lifts to the cotangent bundle is not similar to the definition of lifts to the tangent bundle, we have some differences for g -natural metrics on cotangent bundles. g -natural metric includes the Sasaki metric ([7], [12], [13]) and the Cheeger-Gromoll metric (see also [2], [4], [5], [6], [9], [11], [14], [15], [16], [18]) as a special cases. In [1]-[3] Abbasi and Sarih characterized the g -natural metric on the tangent bundle. In [17] Sukhova studied a class of Riemannian almost product metrics on the tangent bundle of a smooth manifold and investigated the scalar curvature of the tangent bundle. In [10] Munteanu computed the Levi-Civita connection, the curvature tensor, the

sectional curvature and the scalar curvature of the g -natural metric on the tangent bundle.

2. LEVI-CIVITA CONNECTION OF \tilde{g}

We put

$$X_{(i)} = \frac{\partial}{\partial x^i}, \theta^{(i)} = dx^i, i = 1, \dots, n.$$

Then from (1.2) and (1.3) we see that ${}^H X_{(i)}$ and ${}^V \theta^{(i)}$ have respectively local expressions of the form

$$(2.1) \quad \tilde{e}_{(i)} = {}^H X_{(i)} = \frac{\partial}{\partial x^i} + \sum_h p_a \Gamma_{hi}^a \frac{\partial}{\partial x^h},$$

$$(2.2) \quad \tilde{e}_{(\bar{i})} = {}^V \theta^{(i)} = \frac{\partial}{\partial x^{\bar{i}}}.$$

We call the set $\{\tilde{e}_{(\alpha)}\} = \{\tilde{e}_{(i)}, \tilde{e}_{(\bar{i})}\} = \{{}^H X_{(i)}, {}^V \theta^{(i)}\}$ the frame adapted to Levi-Civita connection ∇_g . The indices $\alpha, \beta, \dots = 1, \dots, 2n$ indicate the indices with respect to the adapted frame.

We now, from the equations (1.2), (1.3), (2.1) and (2.2) see that ${}^H X$ and ${}^V \omega$ have respectively components

$$(2.3) \quad {}^H X = X^i \tilde{e}_{(i)}, \quad {}^H X = ({}^H X^\alpha) = \begin{pmatrix} X^i \\ 0 \end{pmatrix},$$

$$(2.4) \quad {}^V \omega = \sum_i \omega_i \tilde{e}_{(\bar{i})}, \quad {}^V \omega = ({}^V \omega^\alpha) = \begin{pmatrix} 0 \\ \omega_i \end{pmatrix}$$

with respect to the adapted frame $\{\tilde{e}_{(\alpha)}\}$, where X^i and ω_i being local components of $X \in \mathfrak{X}_0^1(M^n)$ and $\omega \in \mathfrak{X}_1^0(M^n)$, respectively.

From (1.8), (1.9) and (1.10) we see that

$$\begin{aligned} \tilde{g}_{ij} &= \tilde{g}(\tilde{e}_{(i)}, \tilde{e}_{(j)}) = {}^V(g(\partial_i, \partial_j)) = g_{ij}, \\ \tilde{g}_{\bar{i}j} &= \tilde{g}(\tilde{e}_{(\bar{i})}, \tilde{e}_{(j)}) = 0, \\ \tilde{g}_{\bar{i}\bar{j}} &= \tilde{g}(\tilde{e}_{(\bar{i})}, \tilde{e}_{(\bar{j})}) = \varphi(z)g^{-1}(dx^i, dx^j) + \psi(z)g^{-1}(dx^i, p_k)g^{-1}(dx^j, p_l) \\ &= \varphi(z)g^{ij} + \psi(z)g^{ik}g^{lj}p_k p_l, \end{aligned}$$

i.e. \tilde{g} has components

$$(2.5) \quad \tilde{g} = \begin{pmatrix} g_{ij} & 0 \\ 0 & \varphi(z)g^{ij} + \psi(z)g^{ik}g^{lj}p_k p_l \end{pmatrix}$$

with respect to the adapted frame $\{\tilde{e}_{(\alpha)}\}$.

For the Levi-Civita connection of the g -natural metric we have the following.

Theorem 2.1. *Let M^n be a Riemannian manifold with metric g and $\tilde{\nabla}$ be the Levi-Civita connection of the cotangent bundle T^*M^n equipped with the g -natural*

metric \tilde{g} . Then $\tilde{\nabla}$ satisfies

$$\begin{aligned}
 (2.6) \quad & i) \quad \tilde{\nabla}_{HX}^H Y = {}^H(\nabla_X Y) + \frac{1}{2}{}^V(pR(X, Y)), \\
 & ii) \quad \tilde{\nabla}_{HX}^V \omega = {}^V(\nabla_X \omega) + \frac{\varphi(z)}{2}{}^H(p(g^{-1} \circ R(\cdot, X)\tilde{\omega})), \\
 & iii) \quad \tilde{\nabla}_{v\omega}^H Y = \frac{\varphi(z)}{2}{}^H(p(g^{-1} \circ R(\cdot, Y)\tilde{\omega})), \\
 & iv) \quad \tilde{\nabla}_{v\omega}^V \theta = -\frac{\varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}(\tilde{g}({}^V\omega, \gamma\delta){}^V\theta + \tilde{g}({}^V\theta, \gamma\delta){}^V\omega) \\
 & \quad + \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}\tilde{g}({}^V\omega, {}^V\theta)\gamma\delta \\
 & \quad + \frac{\psi'(z)\varphi(z) - \varphi'(z)\psi(z) - 2\psi^2(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))^3}\tilde{g}({}^V\omega, \gamma\delta)\tilde{g}({}^V\theta, \gamma\delta)\gamma\delta
 \end{aligned}$$

for all $X, Y \in \mathfrak{S}_0^1(M^n)$, $\omega, \theta \in \mathfrak{S}_1^0(M^n)$, where $\tilde{\omega} = g^{-1} \circ \omega \in \mathfrak{S}_0^1(M^n)$, $R(\cdot, X)\tilde{\omega} \in \mathfrak{S}_1^1(M^n)$, $g^{-1} \circ R(\cdot, X)\tilde{\omega} \in \mathfrak{S}_0^2(M^n)$, $z = \frac{1}{2}|p| = \frac{1}{2}g^{-1}(p, p)$, $\varphi > 0$, $\varphi + 2z\psi > 0$, R and $\gamma\delta$ denotes respectively the curvature tensor of ∇ and the canonical vertical vector field on T^*M^n with expression $\gamma\delta = p_i e_{(\bar{i})}$.

Proof. *i)* The first statement is just Corollary 1.1.

ii) Following Definition 1.1 and Theorem 1.2 we see that

$$\begin{aligned}
 2\tilde{g}(\tilde{\nabla}_{HX}^V \omega, {}^H Y) &= \tilde{g}({}^V(pR(Y, X)), {}^V \omega) \\
 &= \varphi(z)g^{-1}(pR(Y, X), \omega) + \psi(z)g^{-1}(pR(Y, X), p)g^{-1}(\omega, p) \\
 &= \varphi(z)\tilde{g}({}^H(p(g^{-1} \circ R(\cdot, X)\tilde{\omega})), {}^H Y)
 \end{aligned}$$

and

$$\begin{aligned}
 2\tilde{g}(\tilde{\nabla}_{HX}^V \omega, {}^V \theta) &= ({}^H X(\tilde{g}({}^V \omega, {}^V \theta)) - \tilde{g}({}^V \omega, {}^V(\nabla_X \theta)) + \tilde{g}({}^V \theta, {}^V(\nabla_X \omega))) \\
 &= \tilde{g}({}^V \omega, {}^V(\nabla_X \theta)) + \tilde{g}({}^V \theta, {}^V(\nabla_X \omega)) - \tilde{g}({}^V \omega, {}^V(\nabla_X \theta)) + \tilde{g}({}^V \theta, {}^V(\nabla_X \omega)) \\
 &= 2\tilde{g}({}^V \theta, {}^V(\nabla_X \omega)) = 2\tilde{g}({}^V(\nabla_X \omega), {}^V \theta)
 \end{aligned}$$

Using

$$\begin{aligned}
 g^{-1}(pR(Y, X), \omega) &= (g^{kl}(pR(Y, X))_{kl}\omega_l) \\
 &= (g^{kl}p_s R_{ijk}{}^s Y^i X^j \omega_l) = (p_s R_{ijk}{}^s Y^i X^j g^{kl}\omega_l) \\
 &= (p_s R_{ijk}{}^s Y^i X^j \tilde{\omega}^k) = (g_{ai}p_s R_{.jk}{}^s Y^i X^j \tilde{\omega}^k) \\
 &= g(p(g^{-1} \circ R(\cdot, X)\tilde{\omega}), Y) \\
 &= \tilde{g}({}^H(p(g^{-1} \circ R(\cdot, X)\tilde{\omega})), {}^H Y),
 \end{aligned}$$

$$\begin{aligned}
 g^{-1}(pR(Y, X), p) &= (g^{ij}p_s R_{abi}{}^s Y^a X^b p_j) \\
 &= (p_s g^{ts} R_{abit} Y^a X^b \tilde{p}^i) = (R_{abit} Y^a X^b \tilde{p}^i \tilde{p}^t) \\
 &= (R_{itab} Y^a X^b \tilde{p}^i \tilde{p}^t) = (g_{fb} R_{ita}{}^f Y^a X^b \tilde{p}^i \tilde{p}^t) \\
 &= g(R(\tilde{p}, \tilde{p})Y, X) = 0,
 \end{aligned}$$

$${}^H X(\varphi(z)) = 0, \quad {}^H X(\psi(z)) = 0$$

and

$${}^H X(\tilde{g}({}^V \omega, {}^V \theta)) = \tilde{g}({}^V \omega, {}^V(\nabla_X \theta)) + \tilde{g}({}^V \theta, {}^V(\nabla_X \omega))$$

we have

$\tilde{\nabla}_{HX}^V \omega = V(\nabla_X \omega) + \frac{\varphi(z)}{2} H(p(g^{-1} \circ R(\cdot, X))\tilde{\omega})$
iii) Calculations similar to those in *ii)* give

$$\begin{aligned} 2\tilde{g}(\tilde{\nabla}_{v\omega}^H Y, V\theta) &= ({}^H Y(\tilde{g}(V\omega, V\theta)) - \tilde{g}(V\omega, V(\nabla_Y \theta)) - \tilde{g}(V\theta, V(\nabla_Y \omega))) \\ &= \tilde{g}(V\omega, V(\nabla_Y \theta)) + \tilde{g}(V\theta, V(\nabla_Y \omega)) - \tilde{g}(V\omega, V(\nabla_Y \theta)) - \tilde{g}(V\theta, V(\nabla_Y \omega)) \\ &= 0 \end{aligned}$$

and

$$\begin{aligned} 2\tilde{g}(\tilde{\nabla}_{v\omega}^H Y, {}^H Z) &= -\tilde{g}(V\omega, V(pR(Y, Z))) \\ &= -\varphi(z)g^{-1}(\omega, pR(Y, Z)) - \psi(z)g^{-1}(pR(Y, Z), p)g^{-1}(\omega, p) \\ &= \varphi(z)\tilde{g}({}^H(p(g^{-1} \circ R(\cdot, Y))\tilde{\omega}), {}^H Z). \end{aligned}$$

Thus we have

$$\tilde{\nabla}_{v\omega}^H Y = \frac{\varphi(z)}{2} H(p(g^{-1} \circ R(\cdot, Y))\tilde{\omega}).$$

iv) Applying Theorem 1.2 we yield

$$\begin{aligned} 2\tilde{g}(\tilde{\nabla}_{v\omega}^V \theta, {}^H Z) &= (-{}^H Z(\tilde{g}(V\omega, V\theta)) + \tilde{g}(V\omega, V(\nabla_Z \theta)) + \tilde{g}(V\theta, V(\nabla_Z \omega))) \\ &= -\tilde{g}(V\omega, V(\nabla_Z \theta)) - \tilde{g}(V\theta, V(\nabla_Z \omega)) + \tilde{g}(V\omega, V(\nabla_Z \theta)) + \tilde{g}(V\theta, V(\nabla_Z \omega)) \\ &= 0 \end{aligned}$$

Using ${}^V \omega(\varphi(z)) = \varphi'(z)g^{-1}(\omega, p)$, ${}^V \omega(\psi(z)) = \psi'(z)g^{-1}(\omega, p)$

$$\begin{aligned} {}^V \omega(\tilde{g}(V\theta, V\xi)) &= \varphi'(z)g^{-1}(\omega, p)g^{-1}(\theta, \xi) \\ &\quad + \psi'(z)g^{-1}(\omega, p)g^{-1}(\theta, p)g^{-1}(\xi, p) \\ &\quad + \psi(z)(g^{-1}(\omega, \theta)g^{-1}(\xi, p) + g^{-1}(\theta, p)g^{-1}(\omega, \xi)) \end{aligned}$$

and

$$\begin{aligned} \tilde{g}(V\omega, \gamma\delta) &= \varphi(z)g^{-1}(\omega, p) + \psi(z)g^{-1}(\omega, p)g^{-1}(p, p) \\ &= g^{-1}(\omega, p)(\varphi(z) + 2z\psi(z)), \end{aligned}$$

we have

$$\begin{aligned}
 \tilde{g}(\tilde{\nabla}_{V\omega}^V \theta, V\xi) &= V\omega(\tilde{g}(V\theta, V\xi)) + V\theta(\tilde{g}(V\xi, V\omega)) - V\xi(\tilde{g}(V\omega, V\theta)) \\
 &= \varphi'(z)g^{-1}(\omega, p)g^{-1}(\theta, \xi) + \varphi'(z)g^{-1}(\theta, p)g^{-1}(\xi, \omega) \\
 &\quad - \varphi'(z)g^{-1}(\omega, \theta)g^{-1}(\xi, p) + \psi'(z)g^{-1}(\theta, p)g^{-1}(\omega, p)g^{-1}(\xi, p) \\
 &\quad + \psi'(z)g^{-1}(\theta, p)g^{-1}(\xi, p)g^{-1}(\omega, p) - \psi'(z)g^{-1}(\theta, p)g^{-1}(\xi, p)g^{-1}(\omega, p) \\
 &\quad + 2\psi(z)g^{-1}(\xi, p)g^{-1}(\theta, \omega) \\
 &= \frac{\varphi'(z)}{\varphi(z)}g^{-1}(\omega, p)\tilde{g}(V\theta, V\xi) - \frac{\varphi'(z)}{\varphi(z)}g^{-1}(\xi, p)\tilde{g}(V\omega, V\theta) \\
 &\quad + \frac{\varphi'(z)}{\varphi(z)}g^{-1}(\theta, p)\tilde{g}(V\xi, V\omega) - \psi'(z)g^{-1}(\theta, p)g^{-1}(\omega, p)g^{-1}(\xi, p) \\
 &\quad + 2\psi(z)g^{-1}(\omega, \theta)g^{-1}(\xi, p) \\
 &= \tilde{g}\left(\frac{\varphi'(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))}\right)(\tilde{g}(V\omega, \gamma\delta)^V\theta + \tilde{g}(V\theta, \gamma\delta)^V\omega) \\
 &\quad + \frac{2\psi(z) - \varphi'(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))}\tilde{g}(V\omega, V\theta)\gamma\delta \\
 &\quad + \frac{\psi'(z)\varphi(z) - \varphi'(z)\psi(z) - 2\psi^2(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))^3}\tilde{g}(V\omega, \gamma\delta)\tilde{g}(V\theta, \gamma\delta)\gamma\delta, V\xi.
 \end{aligned}$$

Thus

$$\begin{aligned}
 \tilde{\nabla}_{V\omega}^V \theta &= \frac{\varphi'(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))}(\tilde{g}(V\omega, \gamma\delta)^V\theta + \tilde{g}(V\theta, \gamma\delta)^V\omega) \\
 &\quad + \frac{2\psi(z) - \varphi'(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))}\tilde{g}(V\omega, V\theta)\gamma\delta \\
 &\quad + \frac{\psi'(z)\varphi(z) - \varphi'(z)\psi(z) - 2\psi^2(z)}{\varphi(z)(\varphi(z) + 2z\psi(z))^3}\tilde{g}(V\omega, \gamma\delta)\tilde{g}(V\theta, \gamma\delta)\gamma\delta. \quad \square
 \end{aligned}$$

We write $\tilde{\nabla}_{e_\alpha} e_\beta = \tilde{\Gamma}_{\alpha\beta}^\delta e_\delta$ with respect to the adapted frame $\{e_\alpha\}$ of T^*M^n , where $\tilde{\Gamma}_{\alpha\beta}^\delta$ denote the Christoffel symbols constructed by \tilde{g} . From Theorem 2.1, we immediately have

Corollary 2.1. *Let M^n be a Riemannian manifold with metric g and $\tilde{\nabla}$ be the Levi-Civita connection of the cotangent bundle T^*M^n equipped with the g -natural metric \tilde{g} . The particular values of $\tilde{\Gamma}_{\alpha\beta}^\delta$ for different indices, on taking account of (2.6) are then found to be*

$$\begin{aligned}
 \tilde{\Gamma}_{ij}^k &= \Gamma_{ij}^k, & \tilde{\Gamma}_{\bar{i}\bar{j}}^k &= \tilde{\Gamma}_{\bar{i}\bar{j}}^{\bar{k}} = 0, \\
 \tilde{\Gamma}_{\bar{i}\bar{j}}^{\bar{k}} &= -\Gamma_{ik}^j, & \tilde{\Gamma}_{ij}^{\bar{k}} &= \frac{1}{2}p_a R_{ijk}^a, \\
 \tilde{\Gamma}_{\bar{i}\bar{j}}^k &= \frac{\varphi(z)}{2}p_a R_{.j.}^{k ia}, & \tilde{\Gamma}_{ij}^{\bar{k}} &= \frac{\varphi(z)}{2}p_a R_{.i.}^{k ja}, \\
 \tilde{\Gamma}_{\bar{i}\bar{j}}^{\bar{k}} &= \frac{\varphi'(z)}{2\varphi(z)}(p^i \delta_k^j + p^j \delta_k^i) + \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}g^{ij}p_k \\
 &\quad + \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}p^i p^j p_k \\
 &= L(p^i \delta_k^j + p^j \delta_k^i) + M g^{ij} p_k + N p^i p^j p_k.
 \end{aligned} \tag{2.7}$$

with respect to the adapted frame, where $p^i = g^{it}p_t$, $R_{.j}^{k ia} = g^{kt}g^{is}R_{tjs}{}^a$.

3. CURVATURE PROPERTIES OF \tilde{g}

We now consider local 1-forms $\tilde{\omega}^\alpha$ in $\pi^{-1}(U)$ defined by

$$\tilde{\omega}^\alpha = \bar{A}^\alpha_B dx^B,$$

where

$$(3.1) \quad A^{-1} = (\bar{A}^\alpha_B) = \begin{pmatrix} \bar{A}^i_j & \bar{A}^i_{\bar{j}} \\ \bar{A}^{\bar{i}}_j & \bar{A}^{\bar{i}}_{\bar{j}} \end{pmatrix} = \begin{pmatrix} \delta_j^i & 0 \\ -p_a \Gamma_{ij}^a & \delta_i^j \end{pmatrix}$$

The matrix (3.1) is the inverse of the matrix

$$(3.2) \quad A = (A_\beta^A) = \begin{pmatrix} A_j^i & A_{\bar{j}}^i \\ A_j^{\bar{i}} & A_{\bar{j}}^{\bar{i}} \end{pmatrix} = \begin{pmatrix} \delta_j^i & 0 \\ p_a \Gamma_{ij}^a & \delta_i^j \end{pmatrix}$$

of the transformation $\tilde{e}_\beta = A_\beta^A \partial_A$ (see (2.1) and (2.2)). We easily see that the set $\{\tilde{\omega}^\alpha\}$ is the coframe dual to the adapted frame $\{\tilde{e}_{(\beta)}\}$, i.e. $\tilde{\omega}^\alpha(\tilde{e}_{(\beta)}) = \bar{A}^\alpha_B A_\beta^B = \delta_\beta^\alpha$.

Since the adapted frame $\{\tilde{e}_{(\beta)}\}$ is non-holonomic, we put

$$[\tilde{e}_\gamma, \tilde{e}_\beta] = \Omega_{\gamma\beta}^\alpha \tilde{e}_\alpha$$

from which we have

$$\Omega_{\gamma\beta}^\alpha = (\tilde{e}_\gamma A_\beta^A - \tilde{e}_\beta A_\gamma^A) \bar{A}^\alpha_A.$$

According to (2.1), (2.2), (3.1) and (3.2), the components of non-holonomic object $\Omega_{\gamma\beta}^\alpha$ are given by

$$(3.3) \quad \begin{cases} \Omega_{l\bar{j}}^{\bar{i}} = -\Omega_{\bar{j}l}^{\bar{i}} = \Gamma_{li}^j, \\ \Omega_{lj}^{\bar{i}} = p_a R_{lji}{}^a, \end{cases}$$

all the others being zero, where $R_{lji}{}^a$ being local components of the curvature tensor R of ∇_g .

Let \tilde{R} be a curvature tensor of $\tilde{\nabla}$. Then we obtain $\tilde{R}(\tilde{e}_{(\alpha)}, \tilde{e}_{(\beta)})\tilde{e}_{(\gamma)} = \tilde{\nabla}_\alpha \tilde{\nabla}_\beta \tilde{e}_{(\gamma)} - \tilde{\nabla}_\beta \tilde{\nabla}_\alpha \tilde{e}_{(\gamma)} - \Omega_{\alpha\beta}^\varepsilon \tilde{\nabla}_\varepsilon \tilde{e}_{(\gamma)}$,

where $\tilde{\nabla}_\alpha = \tilde{\nabla}_{\tilde{e}_{(\alpha)}}$. The curvature tensor \tilde{R} has components

$$\tilde{R}_{\alpha\beta\gamma}{}^\sigma = \tilde{e}_\alpha \tilde{\Gamma}_{\beta\gamma}^\sigma - \tilde{e}_\beta \tilde{\Gamma}_{\alpha\gamma}^\sigma + \tilde{\Gamma}_{\alpha\varepsilon}^\sigma \tilde{\Gamma}_{\beta\gamma}^\varepsilon - \tilde{\Gamma}_{\beta\varepsilon}^\sigma \tilde{\Gamma}_{\alpha\gamma}^\varepsilon - \Omega_{\alpha\beta}^\varepsilon \tilde{\Gamma}_{\varepsilon\gamma}^\sigma$$

with respect to the adapted frame $\{\tilde{e}_{(\alpha)}\}$.

Taking account of (2.7) and (3.3), we find

$$\begin{aligned}
 \tilde{R}_{kij}{}^l &= R_{kij}{}^l - \frac{\varphi(z)}{2} p_m p_a R_{kit}{}^a R_{.j}{}^{l\,tm} \\
 &\quad + \frac{\varphi(z)}{4} p_m p_a (R_{.k}{}^{l\,tm} R_{ijt}{}^a - R_{.i}{}^{l\,tm} R_{kjt}{}^a), \\
 \tilde{R}_{k\bar{i}j}{}^l &= \frac{\varphi(z)}{2} p_m \nabla_k R_{.j}{}^{l\,im}, \\
 \tilde{R}_{k\bar{i}j}{}^l &= \frac{\varphi(z)}{2} p_m (\nabla_k R_{.i}{}^{l\,jm} - \nabla_i R_{.k}{}^{l\,jm}), \\
 \tilde{R}_{kij}{}^{\bar{l}} &= \frac{1}{2} p_m (\nabla_k R_{ijl}{}^m - \nabla_i R_{kjl}{}^m), \\
 \tilde{R}_{k\bar{i}j}{}^{\bar{l}} &= R_{ikl}{}^j + \frac{\varphi(z)}{4} p_m p_a (R_{klt}{}^a R_{.i}{}^{t\,ja} - R_{itl}{}^m R_{.k}{}^{t\,ja}) \\
 &\quad - \frac{\varphi'(z)}{2\varphi(z)} p_a p^j R_{kil}{}^a - \frac{2\psi(z) - \varphi'(z)}{2(\psi(z) + 2z\varphi(z))} p_l p_a R_{ki}{}^{ja}, \\
 \tilde{R}_{\bar{k}ij}{}^{\bar{l}} &= \frac{1}{2} R_{ijl}{}^k - \frac{\varphi(z)}{4} p_m p_a R_{itl}{}^m R_{.j}{}^{t\,ka} \\
 &\quad + \frac{\varphi'(z)}{4\varphi(z)} p_a p^k R_{ijl}{}^a + \frac{2\psi(z) - \varphi'(z)}{4(\psi(z) + 2z\varphi(z))} p_l p_a R_{ij}{}^{ka}, \\
 \tilde{R}_{\bar{k}ij}{}^l &= \frac{\varphi'(z)}{2} p_a (p^k R_{.j}{}^{l\,ia} - p^i R_{.j}{}^{l\,ka}) + \frac{\varphi(z)}{2} (R_{.j}{}^{l\,ik} - R_{.j}{}^{l\,ki}) \\
 &\quad + \frac{\varphi^2(z)}{4} p_m p_a (R_{.t}{}^{l\,km} R_{.j}{}^{t\,ia} - R_{.t}{}^{l\,im} R_{.j}{}^{t\,ka}), \\
 \tilde{R}_{\bar{k}ij}{}^l &= \frac{\varphi(z)}{2} R_{.i}{}^{l\,jk} + \frac{\varphi'(z)}{4} p_a (p^k R_{.i}{}^{l\,ja} - p^j R_{.i}{}^{l\,ka}) \\
 &\quad + \frac{\varphi^2(z)}{4} p_m p_a R_{.t}{}^{l\,km} R_{.i}{}^{t\,ja}, \\
 \tilde{R}_{\bar{k}\bar{i}j}{}^{\bar{l}} &= [L - M(1 + 2zL)](g^{jk} \delta_i^{\bar{l}} - g^{ij} \delta_i^{\bar{k}}) \\
 &\quad + [N - (2M' + M^2 + 2zMN)](g^{kj} p^i p_l - g^{ij} p^k p_l) \\
 &\quad + [2L' - L^2 - N(1 + 2zL)](\delta_i^{\bar{l}} p^k p^j - \delta_i^{\bar{k}} p^i p^j), \\
 \tilde{R}_{k\bar{i}j}{}^{\bar{l}} &= \tilde{R}_{\bar{k}ij}{}^{\bar{l}} = \tilde{R}_{\bar{k}\bar{i}j}{}^l = \tilde{R}_{k\bar{i}j}{}^{\bar{l}} = 0,
 \end{aligned}
 \tag{3.4}$$

where $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$.

It is known (see [8, p.200]) that the sectional curvature on $(T^*M^n, {}^{CG}g)$ for $P(U, V)$ is given by

$$\tilde{K}(P) = -\frac{\tilde{R}_{kmi\bar{j}} U^k V^m U^i V^{\bar{j}}}{(\tilde{g}_{ki} \tilde{g}_{m\bar{j}} - \tilde{g}_{k\bar{j}} \tilde{g}_{mi}) U^k V^m U^i V^{\bar{j}}},
 \tag{3.5}$$

where $P(U, V) = (U, V)$ denotes the plane spanned by (U, V) . Let $\{X_i\}$ and $\{\omega^i\}$, $i = 1, \dots, n$ be a local orthonormal frame and coframe on M^n , respectively. Then from (8)-(10) we see that $\{{}^H X_1, \dots, {}^H X_n, {}^V \omega^1, \dots, {}^V \omega^n\}$ is a local orthonormal frame on T^*M^n . Let $\tilde{K}({}^H X, {}^H Y)$, $\tilde{K}({}^H X, {}^V \theta)$ and $\tilde{K}({}^V \omega, {}^V \theta)$ denote the sectional curvature of the plane spanned by $({}^H X, {}^H Y)$, $({}^H X, {}^V \theta)$ and $({}^V \omega, {}^V \theta)$ on (T^*M^n, \tilde{g}) ,

respectively. Then, using (2.3), (2.4), (2.5) and (3.4), we have from (3.5)

$$\begin{aligned}
i) \quad \tilde{K}({}^H X, {}^H Y) &= -\frac{\tilde{R}_{kij} {}^H \tilde{X}^k {}^H \tilde{Y}^i {}^H \tilde{X}^j {}^H \tilde{Y}^s}{(\tilde{g}_{kj} \tilde{g}_{is} - \tilde{g}_{ks} \tilde{g}_{ij}) {}^H \tilde{X}^k {}^H \tilde{Y}^i {}^H \tilde{X}^j {}^H \tilde{Y}^s} \\
&= -\frac{\tilde{R}_{kij} {}^l \tilde{g}_{sl} {}^H \tilde{X}^k {}^H \tilde{Y}^i {}^H \tilde{X}^j {}^H \tilde{Y}^s + \tilde{R}_{kij} {}^l \tilde{g}_{sl} {}^H \tilde{X}^k {}^H \tilde{Y}^i {}^H \tilde{X}^j {}^H \tilde{Y}^s}{(\tilde{g}_{kj} \tilde{g}_{is} - \tilde{g}_{ks} \tilde{g}_{ij}) {}^H \tilde{X}^k {}^H \tilde{Y}^i {}^H \tilde{X}^j {}^H \tilde{Y}^s} \\
&= K(X, Y) + \frac{\frac{\varphi(z)}{2} g^{tf} (pR(X, Y))_t (pR(X, Y))_f}{g(X, X)g(Y, Y) - g(X, Y)g(X, Y)} \\
&\quad - \frac{\frac{\varphi(z)}{4} g^{tf} (pR(X, Y))_t (pR(X, Y))_f}{g(X, X)g(Y, Y) - g(X, Y)g(X, Y)} + \frac{\frac{\varphi(z)}{4} g^{tf} (pR(Y, Y))_t (pR(X, X))_f}{g(X, X)g(Y, Y) - g(X, Y)g(X, Y)} \\
&= K(X, Y) - \frac{3\varphi(z)}{4} |(pR(X, Y))|^2.
\end{aligned}$$

$$\begin{aligned}
ii) \quad \tilde{K}({}^H X, {}^V \theta) &= -\frac{\tilde{R}_{kij} {}^H \tilde{X}^k {}^V \tilde{\omega}^i {}^H \tilde{X}^j {}^V \tilde{\omega}^s}{(\tilde{g}_{kj} \tilde{g}_{is} - \tilde{g}_{ks} \tilde{g}_{ij}) {}^H \tilde{X}^k {}^H \tilde{\omega}^i {}^H \tilde{X}^j {}^V \tilde{\omega}^s} \\
&= -\frac{\tilde{R}_{kij} {}^l \tilde{g}_{sl} X^k \omega_i X^j \omega_s + \tilde{R}_{kij} {}^l \tilde{g}_{sl} X^k \omega_i X^j \omega_s}{(g_{kj} (\varphi(z) g^{is} + \psi(z) g^{ia} g^{sb} p_a p_b)) X^k \omega_i X^j \omega_s} \\
&= \frac{\frac{\varphi^2(z)}{4} g^{tf} (pR(, X) \tilde{\omega})_t (pR(, X) \tilde{\omega})_f}{(\varphi(z) g(X, X) g^{-1}(\omega, \omega) + \psi(z) g(X, X) (g^{-1}(\omega, p))^2)} \\
&= \frac{\varphi^2(z)}{4(\varphi(z) + \psi(z) (g^{-1}(\omega, p))^2)} |(pR(, X) \tilde{\omega})|^2
\end{aligned}$$

$$\begin{aligned}
iii) \quad \tilde{K}({}^V \omega, {}^V \theta) &= -\frac{\tilde{R}_{kij} {}^V \tilde{\omega}^k {}^V \tilde{\theta}^i {}^V \tilde{\omega}^j {}^V \tilde{\theta}^s}{(\tilde{g}_{kj} \tilde{g}_{is} - \tilde{g}_{ks} \tilde{g}_{ij}) {}^V \tilde{\omega}^k {}^V \tilde{\theta}^i {}^V \tilde{\omega}^j {}^V \tilde{\theta}^s} \\
&= -\frac{\tilde{R}_{kij} {}^l \tilde{g}_{sl} \omega_k \theta_i \omega_j \theta_s + \tilde{R}_{kij} {}^l \tilde{g}_{sl} \omega_k \theta_i \omega_j \theta_s}{(\tilde{g}_{kj} \tilde{g}_{is} - \tilde{g}_{ks} \tilde{g}_{ij}) \omega_k \theta_i \omega_j \theta_s} \\
&= -\left[\frac{A(\delta_i^i p^k p^j - \delta_i^k p^i p^j) + B(g^{kj} p^i p_l - g^{ij} p^k p_l)}{P} \right. \\
&\quad \left. + \frac{C(g^{jk} \delta_l^i - g^{ij} \delta_l^k)}{P} \right] (\varphi(z) (g^{sl} + \psi(z) g^{sa} g^{lb} p_a p_b)) \omega_k \theta_i \omega_j \theta_s \\
&= -\frac{A(g^{-1}(\omega, p))^2}{\varphi(z) + \psi(z) [(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]} \\
&\quad - \frac{B(\varphi(z) + 2z\psi(z)) (g^{-1}(\theta, p))^2 + C(\varphi(z) + \psi(z) (g^{-1}(\theta, p))^2)}{\varphi^2(z) + \varphi(z)\psi(z) [(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]},
\end{aligned}$$

where

$$\begin{aligned}
 P &= (\tilde{g}_{\bar{k}\bar{j}}\tilde{g}_{\bar{i}\bar{s}} - \tilde{g}_{\bar{k}\bar{s}}\tilde{g}_{\bar{i}\bar{j}})\omega_k\theta_i\omega_j\theta_s \\
 &= \left[(\varphi(z)g^{kj} + \psi(z)g^{ka}g^{jb}p_ap_b)(\varphi(z)g^{is} + \psi(z)g^{it}g^{sf}p_t p_f) \right. \\
 &\quad \left. - (\varphi(z)g^{ks} + \psi(z)g^{kc}g^{sd}p_cp_d)(\varphi(z)g^{ij} + \psi(z)g^{iu}g^{jv}p_u p_v) \right] \omega_k\theta_i\omega_j\theta_s \\
 &= \varphi^2(z)g^{-1}(\omega, \omega)g^{-1}(\theta, \theta) + \varphi(z)\psi(z)g^{-1}(\omega, \omega)(g^{-1}(\theta, p))^2 \\
 &\quad + \varphi(z)\psi(z)g^{-1}(\theta, \theta)(g^{-1}(\omega, p))^2 + \psi^2(z)(g^{-1}(\omega, p))^2(g^{-1}(\theta, p))^2 \\
 &\quad - \varphi^2(z)(g^{-1}(\omega, \theta))^2 - \varphi(z)\psi(z)g^{-1}(\omega, \theta)g^{-1}(\omega, p)g^{-1}(\theta, p) \\
 &\quad - \varphi(z)\psi(z)g^{-1}(\omega, \theta)g^{-1}(\omega, p)g^{-1}(\theta, p) - \psi^2(z)(g^{-1}(\omega, p))^2(g^{-1}(\theta, p))^2 \\
 &= \varphi^2(z) + \varphi(z)\psi(z)[(g^{-1}(\omega, p))^2 + (g^{-1}(\theta, p))^2].
 \end{aligned}$$

and $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $A = 2L' - L^2 - N(1 + 2zL)$, $B = N - (2M' + M^2 + 2zMN)$, $C = L - M(1 + 2zL)$

Thus we have

Theorem 3.1. *Let (M^n, g) be a Riemannian manifold and T^*M^n be its cotangent bundle equipped with the g -natural metric \tilde{g} . Then the sectional curvature \tilde{K} of (T^*M^n, \tilde{g}) satisfy the following:*

$$\begin{aligned}
 i) K(H\tilde{X}, HY) &= K(X, Y) - \frac{3\varphi(z)}{4} |(pR(X, Y))|^2, \\
 ii) \tilde{K}(^H X, ^V \omega) &= \frac{\varphi^2(z)}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p)))} |(pR(, X)\tilde{\omega})|^2, \\
 iii) \tilde{K}(^V \omega, ^V \theta) &= -\frac{A(g^{-1}(\omega, p))^2}{\varphi(z) + \psi(z)[(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]} \\
 &\quad - \frac{B(\varphi(z) + 2z\psi(z))(g^{-1}(\theta, p))^2 + C(\varphi(z) + \psi(z)(g^{-1}(\theta, p))^2)}{\varphi^2(z) + \varphi(z)\psi(z)[(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]},
 \end{aligned}$$

where K is a sectional curvature of (M^n, g) and $\tilde{\omega} = g^{-1} \circ \omega = (g^{ij}\omega_j) \in \mathfrak{S}_0^1(M^n)$, $R(, X)\tilde{\omega} \in \mathfrak{S}_1^1(M^n)$, $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $A = 2L' - L^2 - N(1 + 2zL)$, $B = N - (2M' + M^2 + 2zMN)$ and $C = L - M(1 + 2zL)$.

Theorem 3.2. *Let (M^n, g) be a Riemannian manifold of constant sectional curvature K . Let T^*M^n be its cotangent bundle equipped with the g -natural metric \tilde{g} .*

Then the sectional curvature \tilde{K} of (T^*M^n, \tilde{g}) satisfy the following:

$$\begin{aligned}
i) \tilde{K}({}^H X, {}^H Y) &= K - \frac{3\varphi^2(z)}{4} K^2 ((g^{-1}(p, \tilde{X}))^2 + (g^{-1}(p, \tilde{Y}))^2), \\
ii) \tilde{K}({}^H X, {}^V \omega) &= \begin{cases} \frac{\varphi^2(z) K^2 (2z - 2g^{-1}(\tilde{X}, p)g^{-1}(\omega, p) + (g^{-1}(\tilde{X}, p))^2)}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)}, & g(X, \tilde{\omega}) = 1, \\ \frac{\varphi^2(z) K^2 ((g^{-1}(\tilde{X}, p))^2)}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)}, & g(X, \tilde{\omega}) = 0, \end{cases} \\
iii) \tilde{K}({}^V \omega, {}^V \theta) &= -\frac{A(g^{-1}(\omega, p))^2}{\varphi(z) + \psi(z)[(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]} \\
&\quad - \frac{B(\varphi(z) + 2z\psi(z))(g^{-1}(\theta, p))^2 + C(\varphi(z) + \psi(z)(g^{-1}(\theta, p))^2)}{\varphi^2(z) + \varphi(z)\psi(z)[(g^{-1}(\theta, p))^2 + (g^{-1}(\omega, p))^2]},
\end{aligned}$$

where $\tilde{\omega} = g^{-1} \circ \omega = (g^{ij}\omega_j) \in \mathfrak{S}_0^1(M^n)$, $X^i = g^{ij}X_j = g^{-1} \circ \tilde{X} \in \mathfrak{S}_0^1(M^n)$, $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $A = 2L' - L^2 - N(1 + 2zL)$, $B = N - (2M' + M^2 + 2zMN)$ and $C = L - M(1 + 2zL)$.

Proof. Let $R_{kmj}{}^s = K(\delta_k^s g_{mj} - \delta_m^s g_{kj})$.

$$\begin{aligned}
i) \tilde{K}({}^H X, {}^H Y) &= K(X, Y) - \frac{3\varphi(z)}{4} |(pR(X, Y))|^2 \\
&= K - \frac{3\varphi(z)}{4} g^{ij} (pR(X, Y))_i (pR(X, Y))_j \\
&= K - \frac{3\varphi(z)}{4} g^{ij} p_a K(\delta_k^a g_{li} - \delta_l^a g_{ki}) p_b K(\delta_f^b g_{mj} - \delta_m^b g_{fj}) X^k Y^l X^f Y^m \\
&= K - \frac{3\varphi(z)}{4} K^2 [g^{-1}(\tilde{Y}, \tilde{Y})g^{-1}(\tilde{X}, p)g^{-1}(\tilde{X}, p) \\
&\quad - g^{-1}(X, Y)g^{-1}(X, p)g^{-1}(Y, p) - g^{-1}(X, Y)g^{-1}(\tilde{X}, p)g^{-1}(\tilde{Y}, p) \\
&\quad + g^{-1}(X, X)g^{-1}(\tilde{Y}, p)g^{-1}(\tilde{Y}, p)] \\
&= K - \frac{3\varphi(z)}{4} K^2 ((g^{-1}(p, \tilde{X}))^2 + (g^{-1}(p, \tilde{Y}))^2)
\end{aligned}$$

ii) Using Theorem 3.1, we have

$$\begin{aligned}
\tilde{K}({}^H X, {}^V \omega) &= \frac{\varphi^2(z)}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)} |(pR(\cdot, X)\tilde{\omega})|^2 \\
&= \frac{\varphi^2(z) g^{tf} (pR(\cdot, X)\tilde{\omega})_t (pR(\cdot, X)\tilde{\omega})_f}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)} \\
&= \frac{\varphi^2(z) g^{tf} p_a R_{tij}{}^a X^i \tilde{\omega}^j p_b R_{fkm}{}^b X^k \tilde{\omega}^m}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)}
\end{aligned}$$

$$\begin{aligned}
 &= \frac{\varphi^2(z)g^{tf}p_a(K(\delta_t^a g_{ij} - \delta_i^a g_{tj}))X^i \tilde{\omega}^j p_b(K(\delta_f^b g_{km} - \delta_k^b g_{fm}))X^k \tilde{\omega}^m}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)} \\
 &= \frac{\varphi^2(z)K^2(2z(g(X, \tilde{\omega}))^2 - 2g(X, \tilde{\omega})g^{-1}(\tilde{X}, p)g^{-1}(\omega, p) + g(\tilde{\omega}, \tilde{\omega})(g^{-1}(\tilde{X}, p))^2)}{4(\varphi(z) + \psi(z)(g^{-1}(\omega, p))^2)} \\
 &= \begin{cases} \frac{\varphi^2(z)K^2(2z-2g^{-1}(\tilde{X}, p)g^{-1}(\omega, p)+(g^{-1}(\tilde{X}, p))^2)}{4(\varphi(z)+\psi(z)(g^{-1}(\omega, p))^2)}, & g(X, \tilde{\omega}) = 1, \\ \frac{\varphi^2(z)K^2((g^{-1}(\tilde{X}, p))^2)}{4(\varphi(z)+\psi(z)(g^{-1}(\omega, p))^2)}, & g(X, \tilde{\omega}) = 0, \end{cases}
 \end{aligned}$$

where

$$\begin{aligned}
 g(X_a, \tilde{\omega}^b) &= g_{ij}X_a^i(\tilde{\omega}^b)^j = g_{ij}X_a^i g^{jk}\omega_k^b = \delta_i^k X_a^i \omega_k^b \\
 &= X_a^k \omega_k^b = \omega^b(X_a) = \delta_a^b = \begin{cases} 1, & a = b, \\ 0, & a \neq b, \end{cases} \\
 g(\tilde{\omega}, \tilde{\omega}) &= g_{ij}\tilde{\omega}^i \tilde{\omega}^j = g_{ij}g^{is}\omega_s g^{jk}\omega_k = \delta_j^s \omega_s g^{jk}\omega_k \\
 &= g^{sk}\omega_s \omega_k = g^{-1}(\omega, \omega) = 1.
 \end{aligned}$$

iii) The statement is obtained by iii) of Theorem 3.1. \square

Let (x, p) be a point on T^*M^n with $p \neq 0$ and $\{e_1, \dots, e_n\}$ be an orthonormal basis for the tangent space $T_x M^n$ of M^n at x . Also, let $\{\omega^1, \dots, \omega^n\}$ be a dual orthonormal basis for the cotangent spaces $T_x^* M^n$ of M^n at x such that $\omega^1 = \frac{p}{|p|}$, where $|p|$ is the norm of p with respect to the metric g on M^n . Then for $i \in \{1, \dots, n\}$ and $k \in \{2, \dots, n\}$ define the horizontal and vertical lifts by $f_i = {}^H e_i$, $f_{n+1} = \frac{V \omega^1}{\sqrt{\varphi(z)+2z\psi(z)}}$ and $f_{n+k} = \frac{1}{\sqrt{\varphi(z)}}(V \omega^k)$, $z = \frac{1}{2}|p| = g^{-1}(p, p)$. Then $\{f_1, \dots, f_{2n}\}$ is an orthonormal basis for the cotangent space $T_{(x,p)}^* M^n$ with respect to the g -natural metric \tilde{g} .

Using Theorem 3.1, we have

$$\begin{aligned}
 i) \tilde{K}(f_i, f_j) &= \tilde{K}({}^H e_i, {}^H e_j) = K(e_i, e_j) - \frac{3\varphi(z)}{4}|pR(e_i, e_j)|^2, \\
 ii) \tilde{K}(f_i, f_{n+1}) &= \tilde{K}({}^H e_i, \frac{V \omega^1}{\sqrt{\varphi(z)+2z\psi(z)}}) \\
 &= \frac{\varphi^2(z)}{4(\varphi(z) + \psi(z)(g^{-1}(\frac{V \omega^1}{\sqrt{\varphi(z)+2z\psi(z)}}, p))^2)} |(pR(, e_i) \frac{V \omega^1}{\sqrt{\varphi(z)+2z\psi(z)}})|^2 \\
 &= 0
 \end{aligned}$$

by virtue of

$$pR(, e_i)\tilde{\omega}^1 = (p_m R_{,ks}{}^m e_i^k (\frac{p}{|p|})^s) = (R_{,ksl} e_i^k (\frac{p}{|p|})^s p^l) = \frac{1}{|p|}(R_{,ksl} e_i^k p^s p^l) = 0.$$

$$\begin{aligned}
 iii) \tilde{K}(f_i, f_{n+k}) &= \tilde{K}({}^H e_i, \frac{V \omega^k}{\sqrt{\varphi(z)}}) = \frac{\varphi^2(z)|(pR(, e_i) \frac{\tilde{\omega}^k}{\sqrt{\varphi(z)}})|^2}{4(\varphi(z) + \psi(z)(g^{-1}(\frac{V \omega^k}{\sqrt{\varphi(z)}}), p))^2)} \\
 &= \frac{1}{4}|(pR(, e_i)\tilde{\omega}^k)|^2,
 \end{aligned}$$

$$\begin{aligned}
iv) \tilde{K}(f_{n+1}, f_{n+k}) &= \tilde{K}\left(\frac{V_{\omega^1}}{\sqrt{\varphi(z) + 2z\psi(z)}}, \frac{V_{\omega^k}}{\sqrt{\varphi(z)}}\right) \\
&= \frac{A\left(g^{-1}\left(\frac{V_{\omega^1}}{\sqrt{\varphi(z) + 2z\psi(z)}}, p\right)\right)^2}{\varphi(z) + \psi(z)\left[\left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + \left(g^{-1}\left(\frac{V_{\omega^1}}{\sqrt{\varphi(z) + 2z\psi(z)}}, p\right)\right)^2\right]} \\
&= \frac{B(\varphi(z) + 2z\psi(z))\left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + C(\varphi(z) + \psi(z)\left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2)}{\varphi^2(z) + \varphi(z)\psi(z)\left[\left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + \left(g^{-1}\left(\frac{V_{\omega^1}}{\sqrt{\varphi(z) + 2z\psi(z)}}, p\right)\right)^2\right]} \\
&= -\frac{2zA + (\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)}, \\
v) \tilde{K}(f_{n+k}, f_{n+l}) &= \tilde{K}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, \frac{V_{\omega^l}}{\sqrt{\varphi(z)}}\right) \\
&= \frac{A\left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2}{\varphi(z) + \psi(z)\left[\left(g^{-1}\left(\frac{V_{\omega^l}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + \left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2\right]} \\
&= \frac{B(\varphi(z) + 2z\psi(z))\left(g^{-1}\left(\frac{V_{\omega^l}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + C(\varphi(z) + \psi(z)\left(g^{-1}\left(\frac{V_{\omega^l}}{\sqrt{\varphi(z)}}, p\right)\right)^2)}{\varphi^2(z) + \varphi(z)\psi(z)\left[\left(g^{-1}\left(\frac{V_{\omega^l}}{\sqrt{\varphi(z)}}, p\right)\right)^2 + \left(g^{-1}\left(\frac{V_{\omega^k}}{\sqrt{\varphi(z)}}, p\right)\right)^2\right]} \\
&= -\frac{C}{\varphi(z)} = \frac{2\varphi(z)\psi(z) - 2\varphi(z)\varphi'(z) - z\varphi'^2(z)}{2\varphi^2(z)(\varphi(z) + 2z\psi(z))},
\end{aligned}$$

where $A = 2L' - L^2 - N(1 + 2zL)$, $B = N - (2M' + M + 2zMN)$ and $C = L - M(1 + 2zL)$.

Thus we have

Theorem 3.3. *Let (x, p) be a point on T^*M^n and $\{f_1, \dots, f_{2n}\}$ be an orthonormal basis for the cotangent spaces $T_x^*M^n$ as above. Then the sectional curvature \tilde{K} satisfy the following equation*

$$\begin{aligned}
i) \quad \tilde{K}(f_i, f_j) &= K(e_i, e_j) - \frac{3\varphi(z)}{4}|pR(e_i, e_j)|^2, \\
ii) \quad \tilde{K}(f_i, f_{n+1}) &= 0, \\
iii) \quad \tilde{K}(f_i, f_{n+k}) &= \frac{1}{4}|(pR(\cdot, e_i)\tilde{\omega}^k)|^2, \\
iv) \quad \tilde{K}(f_{n+1}, f_{n+k}) &= -\frac{2zA + (\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)}, \\
v) \quad \tilde{K}(f_{n+k}, f_{n+l}) &= -\frac{C}{\varphi(z)} = \frac{2\varphi(z)\psi(z) - 2\varphi(z)\varphi'(z) - z\varphi'^2(z)}{2\varphi^2(z)(\varphi(z) + 2z\psi(z))}
\end{aligned}$$

where K is a sectional curvature of (M^n, g) and $\tilde{\omega}^k = g^{-1} \circ \omega^k$, for $i \in \{1, \dots, n\}$ and $k, l \in \{2, \dots, n\}$.

Corollary 3.1. *Let (M^n, p) be a Riemannian manifold and the cotangent bundle T^*M^n be equipped with the g -natural metric \tilde{g} . If we have constant sectional curvature, then T^*M^n flat and $A = C = 0$ for any z . It follows $N = \frac{2L' - L^2}{1 + 2zL}$ and*

$M = \frac{L}{1+2zL}$. We use $C = \frac{2\varphi(z)\varphi'(z)+z\varphi'^2(z)-2\varphi(z)\psi(z)}{2\varphi(z)(\varphi(z)+2z\psi(z))} = 0$, then

$$2\varphi(z)\varphi'(z) + z\varphi'^2(z) - 2\varphi(z)\psi(z) = 0.$$

So,

$$\psi(z) = \varphi'(z)\left(1 + \frac{z\varphi'(z)}{2\varphi(z)}\right).$$

i) $\psi(z) = k\varphi'(z)$ where k is a real constant.

If $\varphi'(z) = 0$ then $\varphi(z)$ is constant.

If $\varphi'(z) \neq 0$ then $\varphi(z) = az^{2(k-1)}$ ($k > 1$ or $k \leq 0$, $a > 0$).

ii) $\psi(z) = \varphi(z)$, then we obtain $\frac{\varphi(z)}{\varphi'(z)} = \frac{-1 \pm \sqrt{1+2z}}{z}$ which gives

$$\varphi(z) = a \frac{e^{2\sqrt{1+2z}}}{(1 + \sqrt{1+2z})^2}, \quad a > 0$$

or

$$\varphi(z) = a \frac{e^{-2\sqrt{1+2z}}}{(\sqrt{1+2z} - 1)^2}.$$

So we have to deal with non zero vector.

Let now $\{f_1, \dots, f_{2n}\}$ be an orthonormal basis for the cotangent space $T_x^*M^n$ as above, then the scalar curvature $\tilde{r} = \sum_{i \neq j} \tilde{K}(f_i, f_j)$ is given by

$$\begin{aligned} \tilde{r} &= \sum_{i \neq j} \tilde{K}(f_i, f_j) \\ &= 2 \sum_{\substack{i,j=1 \\ i < j}}^n \tilde{K}(f_i, f_j) + 2 \sum_{i,j=1}^n {}^{CG}K(f_i, f_{n+j}) + 2 \sum_{\substack{i,j=1 \\ i < j}}^n {}^{CG}K(f_{n+i}, f_{n+j}) \\ &= \sum_{i \neq j}^n K(e_i, e_j) - \frac{3\varphi(z)}{4} \sum_{i,j=1}^n |pR(e_i, e_j)|^2 + \frac{1}{2} \sum_{i,j=1}^n |(pR(, e_i)\tilde{\omega}^j)|^2 \\ &\quad - 2 \sum_{i=2}^n \frac{2zA + (\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)} + \sum_{\substack{i,j=2 \\ i \neq j}}^n \frac{C}{\varphi(z)} \\ &= r - \frac{3\varphi(z)}{4} \sum_{i,j=1}^n |pR(e_i, e_j)|^2 + \frac{1}{2} \sum_{i,j=1}^n |(pR(, e_i)\tilde{\omega}^j)|^2 \\ &\quad - 2(n-1) \frac{2zA + (\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)} - (n-1)(n-2) \frac{C}{\varphi(z)} \end{aligned}$$

from which we have

Theorem 3.4. Let (M^n, g) be a Riemannian manifold and T^*M^n be its cotangent bundle equipped with the g -natural metric \tilde{g} . Let r be the scalar curvature of g and

\tilde{r} be the scalar curvature of \tilde{g} . Then the following equation holds

$$\begin{aligned} \tilde{r} = r - \frac{3\varphi(z)}{4} \sum_{i,j=1}^n |pR(e_i, e_j)|^2 + \frac{1}{2} \sum_{i,j=1}^n |(pR(\cdot, e_i)\tilde{\omega}^j)|^2 \\ - 2(n-1) \frac{2zA + (\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)} - (n-1)(n-2) \frac{C}{\varphi(z)}. \end{aligned}$$

Theorem 3.5. Let (M^n, g) , $n > 2$ be a Riemannian manifold of constant scalar curvature κ . Then the scalar curvature \tilde{r} of (T^*M^n, g) is

$$\begin{aligned} \tilde{r} = (n-1)[n\kappa + z(2-3\varphi(z))\kappa^2 \\ - (\frac{4zA + 2(\varphi(z) + 2z\psi(z))C}{(\varphi(z) + 2z\psi(z))\varphi(z) + 2z\psi(z)} - \frac{(n-2)C}{\varphi(z)})], \end{aligned}$$

where $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$, $A = 2L' - L^2 - N(1 + 2zL)$ and $C = L - M(1 + 2zL)$.

Proof. Using the formulas $R_{kmj}^s = \kappa(\delta_k^s g_{mj} - \delta_m^s g_{kj})$, $r = n(n-1)\kappa$ and Theorem 8, we get the conclusion. \square

Example. Using the Theorem 3.5. If $\varphi(z) = \frac{2}{3}$ and $\psi(z) = 0$, then (T^*M^n, g) has constant scalar curvature $\tilde{r} = n(n-1)\kappa$.

4. GEODESICS OF \tilde{g}

Let C be a curve in M^n expressed locally by $x^h = x^h(t)$ and $\omega_h(t)$ be a covector field along C . Then, in the cotangent bundle T^*M^n , we defined a curve \tilde{C} by

$$(4.1) \quad x^h = x^h(t), \quad x^{\bar{h}} \stackrel{def}{=} p_h = \omega_h(t)$$

If the curve C satisfies at all the points the relation

$$\frac{\delta\omega_h}{dt} = \frac{d\omega_h}{dt} - \Gamma_{jh}^i \frac{dx^j}{dt} \omega_i = 0,$$

then the curve \tilde{C} is said to be a horizontal lift of the curve C in M^n . Thus, if the initial condition $\omega_h = \omega_h^0$ for $t = t_0$ is given, there exists a unique horizontal lift expressed by (4.1).

We now consider differential equations of the geodesic in the cotangent bundle T^*M^n with the metric \tilde{g} . If t is the arc length of a curve $x^A = x^A(t)$, $A = (i, \bar{i})$ in T^*M^n , then equations of geodesic in T^*M^n have the usual form

$$(4.2) \quad \frac{\delta^2 x^A}{dt^2} = \frac{d^2 x^A}{dt^2} + \tilde{\Gamma}_{CB}^A \frac{dx^C}{dt} \frac{dx^B}{dt} = 0$$

with respect to the induced coordinates $(x^i, x^{\bar{i}}) = (x^i, p_i)$ in T^*M^n , where $\tilde{\Gamma}_{CB}^A$ are components of $\tilde{\nabla}$ defined by (2.7).

We find it more convenient to refer equations (4.2) to the adapted frame $\{e_\alpha\}$. From (2.1) and (2.2) we see that the matrix of change of frames $e_\beta = A_\beta^H \partial_H$ has components of the form (3.2).

Using (3.1), now we write

$$\theta^\alpha = \bar{A}^\alpha_A dx^A,$$

i.e.

$$\theta^h = \bar{A}^h_A dx^A = \delta_i^h dx^i = dx^h$$

for $\alpha = h$ and

$$\theta^{\bar{h}} = \bar{A}^{\bar{h}}_A dx^A = -p_a \Gamma^a_{hj} dx^j + \delta^h_j dx^j = \delta p_h$$

for $\alpha = \bar{h}$. Also we put

$$\begin{aligned} \frac{\theta^h}{dt} &= \bar{A}^h_A \frac{dx^A}{dt} = \frac{dx^h}{dt}, \\ \frac{\theta^{\bar{h}}}{dt} &= \bar{A}^{\bar{h}}_A \frac{dx^A}{dt} = \frac{\delta p_h}{dt} \end{aligned}$$

along a curve $x^A = x^A(t)$ in T^*M^n .

If we therefore write down the form equivalent to (4.2), namely,

$$\frac{d}{dt} \left(\frac{\theta^\alpha}{dt} \right) + \tilde{\Gamma}^\alpha_{\gamma\beta} \frac{\theta^\gamma}{dt} \frac{\theta^\beta}{dt} = 0$$

with respect to adapted frame and taking account of (2.7), then we have

$$(4.3) \quad \begin{cases} (a) \quad \frac{\delta^2 x^h}{dt^2} + \varphi(z) p_a R^{k,ja}_{.i.} \frac{dx^i}{dt} \frac{\delta p_j}{dt} = 0, \\ (b) \quad \frac{\delta^2 p_h}{dt^2} + [L(p^i \delta^j_h + p^j \delta^i_h) + M g^{ij} p_h + N p^i p^j p_h] \frac{\delta p_i}{dt} \frac{\delta p_j}{dt} = 0. \end{cases}$$

where $L = \frac{\varphi'(z)}{2\varphi(z)}$, $M = \frac{2\psi(z) - \varphi'(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$ and $N = \frac{\psi'(z)\varphi(z) - 2\varphi'(z)\psi(z)}{2\varphi(z)(\varphi(z) + 2z\psi(z))}$.

Thus the equations (4.3) are the equations of the geodesic in T^*M^n with the metric \tilde{g} . Let now $\tilde{C} : x^h = x^h(t)$, $x^{\bar{h}} = p_h(t) = \omega_h(t)$ be a horizontal lift ($\frac{\delta p_h}{dt} = \frac{\delta \omega_h}{dt} = 0$) of the geodesic $C : x^h = x^h(t)$ ($\frac{\delta^2 x^h}{dt^2} = 0$) in M^n of ∇_g . Then by virtue of (4.3), we have

Theorem 4.1. *The horizontal lift of a geodesic in (M^n, g) is always geodesic in T^*M^n with the g -natural metric \tilde{g} .*

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