

GENERAL DUAL BOOSTS IN LORENTZIAN DUAL PLANE D_1^2

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ABSTRACT. In this paper we obtained the equations of dual boosts (rotations in the Lorentzian dual plane D_1^2) about an arbitrary point (H, K) and showed that the set of all dual translations and dual boosts is a group and the set of all dual boosts is not a group.

1. INTRODUCTION

The set $D = \{a + \varepsilon b : \varepsilon \neq 0, \varepsilon^2 = 0, a, b \in \mathbb{R}\}$ is a commutative ring with a unit. Elements of D is called as dual numbers.

Clifford [5], introduced the Dual numbers in 1873. A. P. Koltelnikov [13] applied them to describe rigid body motions in three dimension. The notion of dual angle is defined by Study [18] and Yaglom [20] described geometrical objects in three dimensional space using these numbers.

There has been many applications of dual numbers in recent years, such as; in robotics, dynamics, and kinematics ([17], [7], [16]), in computer aided geometrical design and modelling of rigid bodies, mechanism design ([2], [4], [3], [14]), in field theory ([6],[19], [1]), and in group theory ([9], [10], [11]).

Gans' ([8]) work which is on - the equations of general rotations about an arbitrary point (h, k) and the theorems about resultant of translations and rotations in the Euclidean plane- is generalized to Lorentzian plane E_1^2 in [12].

The dual plane $D^2 = \{(A_1, A_2) : A_1, A_2 \in D\}$ is a 2-dimensiaonal modul on D . In this paper we obtain the equations of general dual boosts about an arbitrary point (H, K) in Lorentzian dual plane $D_1^2 = (D^2, (+, -))$ and show that the set of all dual translations and dual boosts is a group and the set of all dual boosts is not a group.

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2. EQUATIONS OF GENERAL DUAL BOOSTS

There are four kinds of isometries in two-dimensional Dual Lorentzian plane D_1^2 . They are the following :

$$\begin{pmatrix} \cosh \Phi & \sinh \Phi \\ \sinh \Phi & \cosh \Phi \end{pmatrix}, \quad \begin{pmatrix} \cosh \Phi & \sinh \Phi \\ -\sinh \Phi & -\cosh \Phi \end{pmatrix}$$

$$\begin{pmatrix} -\cosh \Phi & \sinh \Phi \\ -\sinh \Phi & \cosh \Phi \end{pmatrix}, \quad \begin{pmatrix} -\cosh \Phi & \sinh \Phi \\ \sinh \Phi & -\cosh \Phi \end{pmatrix}.$$

where $\Phi = \varphi + \varepsilon\varphi^*$ is the dual angle.

The ones whose determinants are +1 are dual boosts, the ones whose determinants are -1 are dual reflections (See [15]). Hence the dual boosts about the origin are given by the matrices

$$R_\Phi = \begin{pmatrix} \cosh \Phi & \sinh \Phi \\ \sinh \Phi & \cosh \Phi \end{pmatrix}, \quad \begin{pmatrix} -\cosh \Phi & \sinh \Phi \\ \sinh \Phi & -\cosh \Phi \end{pmatrix} = B_\Phi.$$

Let $O_1 = (H, K)$, $H = h + \varepsilon h^*$, $K = k + \varepsilon k^*$ be an arbitrary point, Φ be the angle of rotation, and let

$P_1 = (X_1, Y_1)$, denote the image of $P = (X, Y)$, where $X = x + \varepsilon x^*$, $Y = y + \varepsilon y^*$, $X_1 = x_1 + \varepsilon x_1^*$, $Y_1 = y_1 + \varepsilon y_1^*$.

We express the rotation in terms of an auxiliary \widehat{X}, \widehat{Y} -coordinate system, with origin O_1 , whose axis are parallel to X, Y axis and similarly directed.

If the coordinats of P and P_1 in the auxiliary system are $(\widehat{X}, \widehat{Y})$ and $(\widehat{X}_1, \widehat{Y}_1)$, then we have

$$(\widehat{X}_1, \widehat{Y}_1) = (\widehat{X} \cosh \Phi + \widehat{Y} \sinh \Phi, \widehat{X} \sinh \Phi + \widehat{Y} \cosh \Phi). \quad (1)$$

Denote this dual boost by

$$f: \begin{matrix} D_1^2 & \rightarrow & D_1^2 \\ (\widehat{X}, \widehat{Y}) & \rightarrow & f(\widehat{X}, \widehat{Y}) = (\widehat{X}_1, \widehat{Y}_1) \end{matrix}$$

and (respectively denote the second dual boosts by

$$g: \begin{matrix} D_1^2 & \rightarrow & D_1^2 \\ (\widehat{X}, \widehat{Y}) & \rightarrow & g(\widehat{X}, \widehat{Y}) = (\widehat{X}_1, \widehat{Y}_1) \end{matrix}$$

where in this case

$$(\widehat{X}_1, \widehat{Y}_1) = (-\widehat{X} \cosh \Phi + \widehat{Y} \sinh \Phi, \widehat{X} \sinh \Phi - \widehat{Y} \cosh \Phi). \quad (1')$$

The relations between the original and the auxiliary coordinates of P, P_1 are

$$(X, Y) = (\widehat{X} + H, \widehat{Y} + K) \quad \text{and} \quad (X_1, Y_1) = (\widehat{X}_1 + H, \widehat{Y}_1 + K) \quad (2)$$

substituting the values of $\widehat{X}, \widehat{Y}, \widehat{X}_1, \widehat{Y}_1$ into (1) (respectively into (1')) we obtain the equations we have been seeking. Thus the dual boosts through the angle Φ about the point (H, K) has the equations

$$(X_1 - H, Y_1 - K) = ((X - H) \cosh \Phi + (Y - K) \sinh \Phi, (X - H) \sinh \Phi + (Y - K) \cosh \Phi) \quad (3)$$

(respectively

$$(X_1 - H, Y_1 - K) = (-(X - H) \cosh \Phi + (Y - K) \sinh \Phi, (X - H) \sinh \Phi - (Y - K) \cosh \Phi). \quad (3')$$

Hence

$$\begin{cases} (X_1, Y_1) = (X \cosh \Phi + Y \sinh \Phi + A, X \sinh \Phi + Y \cosh \Phi + B) \\ \text{where } A = H(1 - \cosh \Phi) - K \sinh \Phi \\ \quad \quad B = K(1 - \cosh \Phi) - H \sinh \Phi \end{cases} \quad (4)$$

(respectively from (3'))

$$\begin{cases} (X_1, Y_1) = (-X \cosh \Phi + Y \sinh \Phi + C, X \sinh \Phi - Y \cosh \Phi + D) \\ \text{where } C = H(1 + \cosh \Phi) - K \sinh \Phi \\ \quad \quad D = K(1 + \cosh \Phi) - H \sinh \Phi \end{cases}. \quad (4')$$

Equation (4) (respectively equation (4')) are seen to be the resultant TR_Φ (respectively SB_Φ) of the following dual boost. R_Φ about O and dual translation T (respectively following dual boost B_Φ about O and dual translation S)

$$\begin{aligned} (X_1, Y_1) &= R_\Phi(X, Y) = \begin{pmatrix} \cosh \Phi & \sinh \Phi \\ \sinh \Phi & \cosh \Phi \end{pmatrix} \begin{pmatrix} X \\ Y \end{pmatrix} \\ &= (X \cosh \Phi + Y \sinh \Phi, X \sinh \Phi + Y \cosh \Phi) \\ (X_2, Y_2) &= T(X_1, Y_1) = (X_1 + A, Y_1 + B) \end{aligned}$$

(respectively

$$\begin{aligned} (X_1, Y_1) &= B_\Phi(X, Y) = \begin{pmatrix} -\cosh \Phi & \sinh \Phi \\ \sinh \Phi & -\cosh \Phi \end{pmatrix} \begin{pmatrix} X \\ Y \end{pmatrix} \\ &= (-X \cosh \Phi + Y \sinh \Phi, Y \sinh \Phi - Y \cosh \Phi) \\ (X_2, Y_2) &= S(X_1, Y_1) = (X_1 + C, Y_1 + D). \end{aligned}$$

Therefore the dual boost represented by (3) is equal to TR_Φ (respectively the dual boost represented by (3') is equal to SB_Φ).

Theorem 2.1. *The equations of the dual boost about an arbitrary point through a dual angle Φ is given by the equation in (4) (respectively in (4')).*

Proof.

$$\begin{aligned} f: D_1^2 &\rightarrow D_1^2 \\ (X, Y) &\rightarrow f(X, Y) = \begin{pmatrix} X \cosh \Phi + Y \sinh \Phi + H(1 - \cosh \Phi) - K \sinh \Phi, \\ X \sinh \Phi + Y \cosh \Phi + K(1 - \cosh \Phi) - H \sinh \Phi \end{pmatrix} \end{aligned}$$

$$g : D_1^2 \rightarrow D_1^2$$

$$(X, Y) \rightarrow g(X, Y) = \begin{pmatrix} -X \cosh \Phi + Y \sinh \Phi + H(1 + \cosh \Phi) - K \sinh \Phi, \\ X \sinh \Phi - Y \cosh \Phi + K(1 + \cosh \Phi) - H \sinh \Phi \end{pmatrix}$$

Note that for f and g we have

$$d(f(P), f(Q)) = d(P, Q), \quad d(g(P), g(Q)) = d(P, Q),$$

where

$$d(P, Q) = \left\| \vec{PQ} \right\| = \sqrt{\langle \vec{PQ}, \vec{PQ} \rangle}.$$

Hence f and g are isometries. Moreover

$$f(H, K) = (H, K) \text{ and } g(H, K) = (H, K).$$

Thus f and g are the dual boosts about the point (H, K) and through a dual angle Φ . \square

Using this same R (respectively B), we can also find a dual translation T' (respectively S') such that the dual boost (3) (respectively dual boost (3')) is equal to RT' (respectively BS'). To prove this we write

$$(X_1, Y_1) = T'(X, Y) = (X + A', Y + B')$$

and

$$(X_2, Y_2) = R(X_1, Y_1) = (X_1 \cosh \Phi + Y_1 \sinh \Phi, X_1 \sinh \Phi + Y_1 \cosh \Phi)$$

(respectively

$$(X_1, Y_1) = S'(X, Y) = (X + C', Y + D')$$

and

$$(X_2, Y_2) = B(X_1, Y_1) = (-X_1 \cosh \Phi + Y_1 \sinh \Phi, X_1 \sinh \Phi - Y_1 \cosh \Phi).$$

Hence we get

$$(X_2, Y_2) = RT'(X, Y)$$

$$= \left((X + A') \cosh \Phi + (Y + B') \sinh \Phi, (X + A') \sinh \Phi + (Y + B') \cosh \Phi \right)$$

(respectively

$$(X_2, Y_2) = BS'(X, Y)$$

$$= \left(-(X + C') \cosh \Phi + (Y + D') \sinh \Phi, (X + C') \sinh \Phi - (Y + D') \cosh \Phi \right)$$

or

$$(X_2, Y_2) = RT'(X, Y) = (X \cosh \Phi + Y \sinh \Phi + (A' \cosh \Phi + B' \sinh \Phi),$$

$$X \cosh \Phi + Y \sinh \Phi + (A' \cosh \Phi + B' \sinh \Phi)) \quad (5)$$

(respectively

$$(X_2, Y_2) = BS'(X, Y) = (-X \cosh \Phi + Y \sinh \Phi + (D' \cosh \Phi - C' \sinh \Phi), \\ X \sinh \Phi - Y \cosh \Phi + (C' \sinh \Phi - D' \cosh \Phi)). \quad (5')$$

Now, we find A' , B' (respectively C' , D') so that (5) (respectively (5')) is the same transformation as (4) (respectively (4')) i.e. from $TR = RT'$ (respectively $SB = BS'$), we have

$$A' = -K \sinh \Phi + H(\cosh \Phi - 1) \\ B' = -H \sinh \Phi + K(\cosh \Phi - 1)$$

(respectively

$$C' = -K \sinh \Phi - H(\cosh \Phi + 1) \\ D' = -H \sinh \Phi - K(\cosh \Phi + 1).$$

It is readily seen that $T \neq T'$ and $S \neq S'$. Thus we have proved the following:

Theorem 2.2. *Any given dual boost not the identity, through a dual angle about a point other than the origin is the resultant of a dual boost R_Φ (respectively B_Φ) through Φ about the origin followed by a dual translation T , or if a dual translation T' followed by R_Φ (respectively B_Φ). The two dual translations are distinct, uniquely determined, and neither dual translation is I .*

Corollary 1. *If T is a dual translation and R_Φ (respectively B_Φ) is a dual boost through Φ about the origin and neither dual transformation is I , then $R_\Phi T$ (respectively $B_\Phi T$) and TR_Φ (respectively TB_Φ) are distinct dual boosts through Φ about points other than the origin.*

3. RESULTANTS OF DUAL TRANSLATIONS AND DUAL BOOSTS

It is readily checked that the resultant of two dual translations is a dual translation and that the resultant of two dual boosts about origin $O = (0, 0)$ is a dual boost about that point i.e.

$$R_\Phi R_\Omega = R_{\Phi+\Omega}, \quad B_\Phi B_\Omega = R_{\Phi+\Omega}^{-1} = R_{-(\Phi+\Omega)} \\ R_\Phi B_\Omega = B_{\Omega-\Phi}, \quad B_\Omega R_\Phi = B_{\Omega-\Phi}$$

(i) Let R_Φ and R_Ω be two dual boosts about the same point (H, K) through Φ , and Ω respectively. Clearly

$$R_\Phi = TR'_\Phi \quad \text{and} \quad R_\Omega = R''_\Omega T'$$

where R'_Φ , R''_Ω are dual boosts about $O = (0, 0)$ through Φ , and Ω respectively T and T' are dual translations.

Hence $R_\Phi R_\Omega = TR'_\Phi R''_\Omega T'$. From the above discussion $R''_{\Phi+\Omega} = R'_\Phi R''_\Omega$ is a dual boost about $O = (0, 0)$ through $\Phi + \Omega$. Therefore $R_\Phi R_\Omega = TR''_{\Phi+\Omega} T'$.

(ii) Let R_Φ and R_Ω be two dual boosts about different points (H, K) and (H', K') . Again it is easy to see that

$$R_\Phi R_\Omega = TR''_{\Phi+\Omega}T',$$

where $R''_{\Phi+\Omega}$ is a dual boost about $O = (0, 0)$.

(iii) Let R_Φ and B_Ω are two dual boosts about different points (H, K) and (H', K') . Hence we have

$$R_\Phi = TR'_\Phi \text{ and } B_\Omega = B'_\Omega S',$$

where R'_Φ, B'_Ω are dual boosts about $O = (0, 0)$ and T and S' are dual translations.

Therefore $R_\Phi R_\Omega = TR'_\Phi B'_\Omega S'$. Note that $R'_\Phi B'_\Omega = \beta''_{\Omega-\Phi}$ is a dual boost about $O = (0, 0)$. For

$$B_\Omega R_\Phi = (S'' \beta'_\Omega)(R''_\Phi T'),$$

where $B'_\Omega R''_\Phi = \beta''_{\Omega-\Phi}$ is dual boost about $O = (0, 0)$. Note also that

$$R_\Phi = TR'_\Phi \text{ and } B_\Omega = B'_\Omega S'',$$

then $R_\Phi B_\Omega = TR'_\Phi B'_\Omega S''$. $R'_\Phi B'_\Omega = B''_{\Omega-\Phi}$ is a dual boost about $O = (0, 0)$. Thus $R_\Phi B_\Omega = TB''_{\Omega-\Phi} S''$.

(iv) Let B_Φ and B_Ω are two dual boosts about different points.

Clearly

$$B_\Phi = SB'_\Phi, B_\Omega = B''_\Omega S',$$

where B'_Φ, B''_Ω are dual boosts about $O = (0, 0)$. Hence

$$B_\Phi B_\Omega = SB'_\Phi B''_\Omega S' = SR_{\Phi+\Omega}^{-1} S' = SR_{-(\Phi+\Omega)} S'.$$

$R_{-(\Phi+\Omega)}$ is a dual boost through $-(\Phi + \Omega)$ about $O = (0, 0)$.

Thus in all cases problem reduces to

$$TR''_{\Phi+\Omega}T', S'' B''_{\Omega-\Phi}T', TB''_{\Omega-\Phi}S'' \text{ and } SR_{-(\Phi+\Omega)}S',$$

where $R''_{\Phi+\Omega}, B''_{\Omega-\Phi}, R_{-(\Phi+\Omega)}$ are dual boosts about $O = (0, 0)$, S, T, S', T', S'' are dual translations. From Corollary 1 we know that the resultant of a dual translation and a dual boosts about $O = (0, 0)$ (when neither is the identity) is a dual boost about a point not O . Hence it remains to determine the nature of the resultant of (a) a dual translation and a dual boost about a point not O , and (b) two dual boosts about any points. In doing this we assume that none of these transformations is the identity.

(a) Let T (respectively S) be a dual translation, R (respectively B) a dual boost about a point not O , and consider TR (respectively SB). By theorem 2, we know that $R = T'R'$ (respectively $B = S'B'$) where T' (respectively S') is a

dual translation and R' (respectively B') is a dual boost about O . Hence using the associative property of transformations, we have that

$$TR = T(T'R') = (TT')R' = T_1R'$$

(respectively

$$SB = S(S'B') = (SS')B' = S_1B')$$

where T_1 (respectively S_1) is a dual translation. Note that T_1R' (respectively S_1B') is simply the dual boost R' (respectively B') if $T_1 = I$ (respectively $S_1 = I$), and by corollary 1 it is a dual boost about a point not O if $T_1 \neq I$ (respectively $S_1 \neq I$). Thus, TR (respectively SB) is always a dual boost. In the same way RT (respectively BS) can be shown to be a dual boost.

(b) Let R, R' (respectively B, B' or respectively R, B) be dual boosts about any points. If neither point is O , then by theorem 2, $R = TR_1$ and $R' = R'_1T'$ (respectively $B = SB_1$ and $B' = B'_1S'$ or respectively $R = TR_1$ and $B = B'_1S'$) where R_1, R'_1, B_1, B'_1 are dual boosts about O and T, T', S, S' are dual translations. These equations are still true if one of the given dual boosts, say R (respectively B), is about O , except that then $T = I$ (respectively $S = I$). In any case then, we have

$$RR' = (TR_1)(R'_1T') = T(R_1R'_1)T' = TR_2T' = (TR_2)T'$$

(respectively

$$BB' = (SB_1)(B'_1S') = S(B_1B'_1)S' = SR_3S',)$$

respectively

$$RB = (TR_1B''_1S') = T(R_1B''_1)S'' = (TB_2)S'',)$$

where R_2 , (respectively R_3) (respectively B_2) is a dual boost about O . If $R_2 = I$ (respectively $R_3 = I$ and respectively $B = I$) which occurs if R_1, R'_1 (respectively B_1, B'_1 , respectively R_1, B''_1) are mutually inverse then RR' (respectively BB' and RB) is clearly a dual translation. If R_2 (respectively R_3 , respectively B_2) $\neq I$ then TR_2 (respectively SR_3 , respectively TB_2) is a dual boost whose center is not O . Unless, $T = I$ (respectively $S = I$ or respectively $T = I$) using the discussion above it follows that TR_2T' (respectively SR_3S' respectively TB_2S''), and hence RR' (respectively BB' and respectively RB) is a dual boost. Same argument works for BR .

Thus have proved:

Theorem 3.1. *The resultant in either order of a dual translation ($\neq I$) and a dual boost ($\neq I$) is a dual boost. The resultant of two dual boosts about any point is a dual boost or a dual translation.*

Considering the fact that the inverses of dual translations and dual boosts are dual translations and dual boosts respectively, it is clear that we have also proved:

Theorem 3.2. *The set of all dual translations and dual boosts is a group. The set off all dual boosts is not a group.*

Remark 3.3. Note that set of all R_Φ 's about $O = (0, 0)$ is a group. Yet set off all B_Φ 's about O is not a group. Note also that a dual translation and a dual boost are generally not commutative. This was already apperant from corollary 1.

The same is true of two dual boosts,

Example 3.4. Let $R_{\pi/2}, B_{\pi/2}$ be dual boosts through $\pi/2 + \varepsilon 0$ about $(0, 0), (0, 1)$ respectively it is easy to see that $R_{\pi/2}B_{\pi/2} \neq B_{\pi/2}R_{\pi/2}$.

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