



Remarks on conformal anti-invariant Riemannian maps to cosymplectic manifolds

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Abstract

M.A. Akyol and B. Şahin [Conformal anti-invariant Riemannian maps to Kaehler manifolds, U.P.B. Sci. Bull., Series A, Vol. 80, Iss. 4, 2018] defined and studied the notion of conformal anti-invariant Riemannian maps to Kaehler manifolds. In this paper, as a generalization of totally real submanifolds and anti-invariant Riemannian maps, we extend this notion to almost contact metric manifolds. In this manner, we introduce conformal anti-invariant Riemannian maps from Riemannian manifolds to cosymplectic manifolds. In order to guarantee the existence of this notion, we give a non-trivial example, investigate the geometry of foliations which are arisen from the definition of a conformal Riemannian map and obtain decomposition theorems by using the existence of conformal Riemannian maps. Moreover, we investigate the harmonicity of such maps and find necessary and sufficient conditions for conformal anti-invariant Riemannian maps to be totally geodesic. Finally, we study weakly umbilical conformal Riemannian maps and obtain a classification theorem for conformal anti-invariant Riemannian maps.

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1. Introduction

In 1992, A.E. Fischer introduced Riemannian maps between Riemannian manifolds in [8] as a generalization of the notions of isometric immersions and Riemannian submersions. Let $\psi : (N_1, g_{N_1}) \rightarrow (N_2, g_{N_2})$ be a smooth map between Riemannian manifolds such that $0 < \text{rank}\psi < \min\{n_1, n_2\}$, where $\dim N_1 = n_1$ and $\dim N_2 = n_2$. Then we denote the kernel space of ψ_* by $\ker\psi_*$ and consider the orthogonal complementary space $\mathcal{H} = (\ker\psi_*)^\perp$ to $\ker\psi_*$ in TN_1 . Then the tangent bundle of N_1 has the following decomposition $TN_1 = \ker\psi_* \oplus \mathcal{H}$. We denote the range of ψ_* by $\text{range}\psi_*$ and consider the orthogonal complementary space $(\text{range}\psi_*)^\perp$ to $\text{range}\psi_*$ in the tangent bundle TN_2 of N_2 . Since $\text{rank}\psi < \min\{n_1, n_2\}$, we always have $(\text{range}\psi_*)^\perp$. Thus the tangent bundle TN_2 of N_2 has the following decomposition $\psi^{-1}(TN_2) = \text{range}\psi_* \oplus (\text{range}\psi_*)^\perp$. Now, a smooth map $\psi : (N_1^{n_1}, g_{N_1}) \rightarrow (N_2^{n_2}, g_{N_2})$ is called Riemannian map at $q_1 \in N_1$ if the horizontal

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restriction $\psi_{*q_1}^h : (ker\psi_{*q_1})^\perp \rightarrow (range\psi_{*q_1})$ is a linear isometry between the inner product spaces

$$((ker\psi_{*q_1})^\perp, g_{N_1}(q_1)|_{(ker\psi_{*q_1})^\perp})$$

and

$$(range\psi_{*q_1}, g_{N_2}(q_2)|_{(range\psi_{*q_1})}), q_2 = \psi(q_1).$$

Therefore, A. E. Fischer stated in [8] that a Riemannian map is a map which is as isometric as it can be. In another words, ψ_* satisfies the equation

$$g_{N_2}(\psi_*X_1, \psi_*X_2) = g_{N_1}(X_1, X_2) \quad (1.1)$$

for X_1, X_2 vector fields tangent to \mathcal{H} . It follows that isometric immersions and Riemannian submersions are particular Riemannian maps with $ker\psi_* = \{0\}$ and $(range\psi_*)^\perp = \{0\}$. It is known that a Riemannian map is a subimmersion [5] and this fact implies that the rank of the linear map $\psi_{*q} : T_qN_1 \rightarrow T_{\psi(q)}N_2$ is constant for q in each connected component of N_1 , [1] and [8]. It is also important to note that Riemannian maps satisfy the eikonal equation which is a bridge between geometric optics and physical optics. Different properties of Riemannian maps have been studied widely by many authors, see: [4, 9, 12, 14, 16]. Recent developments in the theory of Riemannian map can be found in the book [17]. Recently, conformal Riemannian maps as a generalization of Riemannian maps have been defined in [15] (see also [18]) and the harmonicity of such maps have been also obtained. One can see that conformal Riemannian maps with $ker\psi_* = \{0\}$ (respectively, $(range\psi_*)^\perp = \{0\}$) are conformal holomorphic submanifolds (respectively, conformal submersions). For conformal anti invariant Riemannian submersions see also ([2, 13]). The second author of the paper and B. Şahin have been defined the notion of conformal anti invariant Riemannian maps and conformal slant Riemannian maps in [3] and [4], respectively. In this paper, we are going to introduce and study the notion of conformal anti-invariant Riemannian maps from Riemannian manifolds to almost contact metric manifolds as a generalization of totally real submanifolds and anti-invariant Riemannian maps.

The paper is organized as follows. Section 2 includes preliminaries. Section 3 contains the definition of conformal Riemannian map, a proper example, the geometry of foliations determined by vertical and horizontal distributions and the geometry of leaves of these distributions.

2. Preliminaries

Let N be an almost contact metric manifold with structure tensors $(\varphi, \xi, \eta, g_N)$ where φ is a tensor field of type (1,1), ξ is a vector field, η is a 1-form and g_N is the Riemannian metric on N . Then these tensors satisfy [7]

$$\varphi\xi = 0, \quad \eta\varphi = 0, \quad \eta(\xi) = 1 \quad (2.1)$$

$$\varphi^2 = -I + \eta \otimes \xi, \quad g_N(\varphi X_1, \varphi X_2) = g_N(X_1, X_2) - \eta(X_1)\eta(X_2), \quad (2.2)$$

where I denotes the identity endomorphism of TN and X_1, X_2 are any vector fields on N . The fundamental 2-form Φ is defined $\Phi(X_1, X_2) = g_N(X_1, \varphi X_2)$.

An almost contact metric structure $(\varphi, \xi, \eta, g_N)$ is said to be cosymplectic, if $\nabla\eta = 0$ and $\nabla\Phi = 0$ are closed ([7, 10]), and the structure equation of a cosymplectic manifold is given by

$$(\nabla_{X_1}\varphi)X_2 = 0, \quad X_1, X_2 \in \chi(N), \quad (2.3)$$

where ∇ denotes the Riemannian connection of the metric g_N on N . Moreover, for a cosymplectic manifold, we know that [6]

$$\nabla_{X_1}\xi = 0. \quad (2.4)$$

We also recall the notion of harmonic maps between Riemannian manifolds. Let (N_1, g_{N_1}) and (N_2, g_{N_2}) be Riemannian manifolds and $\psi : (N_1, g_{N_1}) \rightarrow (N_2, g_{N_2})$ is a

differentiable map. Then the differential ψ_* of ψ can be viewed a section of the bundle $Hom(TN_1, \psi^{-1}TN_2) \rightarrow N_1$, where $\psi^{-1}TN_2$ is the pullback bundle which has fibres $(\psi^{-1}TN_2)_q = T_{\psi(q)}N_2$, $q \in N_1$. $Hom(TN_1, \psi^{-1}TN_2)$ has a connection ∇ induced from the Levi-Civita connection ∇^{N_1} and the pullback connection. The second fundamental form of ψ is given by

$$(\nabla\psi_*)(X_1, X_2) = \nabla_{X_1}^\psi \psi_* X_2 - \psi_*(\nabla_{X_1}^{N_1} X_2) \tag{2.5}$$

for $X_1, X_2 \in \Gamma(N_1)$, where ∇^ψ is the pullback connection. It is known that the second fundamental form is symmetric. Recall that ψ is said to be *harmonic* if $trace(\nabla\psi_*) = 0$. On the other hand, the tension field of ψ is the section $\tau(\psi)$ of $\Gamma(\psi^{-1}TN_2)$ defined by

$$\tau(\psi) = div\psi_* = \sum_{i=1}^{n_1} (\nabla\psi_*)(e_i, e_i), \tag{2.6}$$

where $\{e_1, \dots, e_{n_1}\}$ is the orthonormal frame on N_1 . Then it follows that ψ is harmonic if and only if $\tau(\psi) = 0$ [5].

We denote by ∇^2 both the Levi-Civita connection of (N_2, g_{N_2}) and its pullback along ψ . Then according to [11], for any vector field X_1 on N_1 and any section U_1 of $(range\psi_*)^\perp$, where $(range\psi_*)^\perp$ is the subbundle of $\psi^{-1}TN_2$ with fiber $(\psi_*(T_qN_1))^\perp$ – orthogonal complement of $(\psi_*(T_qN_1))$ for g_{N_2} over q , we have $\nabla_{X_1}^{\psi^\perp} U_1$ which is the orthogonal projection of $\nabla_{X_1}^2 U_1$ on $(\psi_*(T_qN_1))^\perp$ such that $\nabla^{\psi^\perp} g_{N_2} = 0$. We now define \mathcal{A}_{U_1} as

$$\nabla_{X_1}^2 U_1 = -\mathcal{A}_{U_1} \psi_* X_1 + \nabla_{X_1}^{\psi^\perp} U_1 \tag{2.7}$$

where $\mathcal{A}_{U_1} \psi_* X_1$ is tangential component (a vector field along ψ) of $\nabla_{X_1}^2 U_1$. It is easy to see that $\mathcal{A}_{U_1} \psi_* X_1$ is bilinear in U_1 and ψ_* and $\mathcal{A}_{U_1} \psi_* X_1$ at q depends only on U_{1q} and $\psi_{*q} X_{1q}$. By direct computations, we obtain $g_{N_2}(\mathcal{A}_{U_1} \psi_* X_1, \psi_* X_2) = g_{N_2}(U_1, (\nabla\psi_*)(X_1, X_2))$ for $X_1, X_2 \in \Gamma((ker\psi_*^\perp))$ and $U_1 \in \Gamma((range\psi_*^\perp)^\perp)$. Since $(\nabla\psi_*)$ is symmetric, it follows that \mathcal{A}_{U_1} is a symmetric linear transformation of $range\psi_*$.

3. Conformal anti-invariant Riemannian maps

We first recall that, in [15], B. Şahin shows that the second fundamental form $(\nabla\psi_*)(X_1, X_2)$, $\forall X_1, X_2 \in \Gamma((ker\psi_*^\perp)^\perp)$, of a conformal Riemannian map is in the following form

$$\begin{aligned} (\nabla\psi_*)(X_1, X_2)^{range\psi_*} &= X_1(\ln\lambda)\psi_* X_2 + X_2(\ln\lambda)\psi_* X_1 \\ &\quad - g_{N_1}(X_1, X_2)\psi_*(grad\ln\lambda). \end{aligned} \tag{3.1}$$

Thus if we denote the $(range\psi_*)^\perp$ -component of $(\nabla\psi_*)(X_1, X_2)$ by $(\nabla\psi_*)(X_1, X_2)^{range\psi_*^\perp}$, we can write $(\nabla\psi_*)(X_1, X_2)$ as

$$(\nabla\psi_*)(X_1, X_2) = (\nabla\psi_*)(X_1, X_2)^{range\psi_*} + (\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp}, \tag{3.2}$$

for $X_1, X_2 \in \Gamma((ker\psi_*^\perp)^\perp)$. Hence we have

$$\begin{aligned} (\nabla\psi_*)(X_1, X_2) &= X_1(\ln\lambda)\psi_* X_2 + X_2(\ln\lambda)\psi_* X_1 - g_{N_1}(X_1, X_2)\psi_*(grad\ln\lambda) \\ &\quad + (\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp}. \end{aligned} \tag{3.3}$$

We now present the following definition for conformal anti-invariant Riemannian maps as a generalization of totally real submanifolds and anti-invariant Riemannian maps.

Definition 3.1. Let ψ be a conformal Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to an almost contact metric manifold $(N_2, \varphi, \xi, \eta, g_{N_2})$. Then we say that ψ is a conformal anti-invariant Riemannian map at $q \in N_1$ if $\varphi(range\psi_*)_q \subseteq (range\psi_{*q})^\perp$. If ψ is a conformal anti-invariant Riemannian map for $q \in N_1$, then ψ is called a conformal anti-invariant Riemannian map.

Now, we are going to give some examples of conformal anti-invariant Riemannian maps.

Example 3.2. Every anti-invariant submanifold [19] of an almost contact metric manifold is a conformal anti-invariant Riemannian map with $\lambda = 1$ and $\ker\psi_* = \{0\}$.

Example 3.3. Every anti-invariant Riemannian map [16] from a Riemannian manifold to an almost contact metric manifold is a conformal anti-invariant Riemannian map with $\lambda = 1$.

We say that a conformal anti-invariant Riemannian map is proper if $\lambda \neq 1$. We now present an example of a proper conformal anti-invariant Riemannian map.

Note that given an Euclidean space $N_2 = \mathbb{R}^5$ with coordinates (v_1, \dots, v_5) on $N_2 = \mathbb{R}^5$, we can naturally choose an almost contact structure (φ, ξ, η) on \mathbb{R}^5 as follows:

$$\begin{aligned} \eta &= dv_5, \quad \xi = \frac{\partial}{\partial v_5}, \quad \varphi\left(\frac{\partial}{\partial v_1}\right) = \frac{\partial}{\partial v_2}, \quad \varphi\left(\frac{\partial}{\partial v_3}\right) = \frac{\partial}{\partial v_4}, \\ \varphi\left(\frac{\partial}{\partial v_2}\right) &= -\frac{\partial}{\partial v_1}, \quad \varphi\left(\frac{\partial}{\partial v_4}\right) = -\frac{\partial}{\partial v_3}, \quad \varphi(\xi) = 0. \end{aligned}$$

Example 3.4. Consider the following map defined by

$$\psi : \mathbb{R}^5 \rightarrow N_2 = \mathbb{R}^5, \quad \psi(u_1, \dots, u_5) = (e^{u_1} \sin u_2, 0, e^{u_1} \cos u_2, 0, 0).$$

We have

$$\ker\psi_* = \text{span}\left\{U_1 = \frac{\partial}{\partial u_3}, U_2 = \frac{\partial}{\partial u_4}, U_3 = \frac{\partial}{\partial u_5}\right\}$$

and

$$\begin{aligned} (\ker\psi_*)^\perp &= \text{span}\left\{X_1 = e^{u_1} \sin u_2 \frac{\partial}{\partial u_1} + e^{u_1} \cos u_2 \frac{\partial}{\partial u_2}, \right. \\ &\quad \left. X_2 = e^{u_1} \cos u_2 \frac{\partial}{\partial u_1} - e^{u_1} \sin u_2 \frac{\partial}{\partial u_2}\right\}. \end{aligned}$$

By direct computations, we have $\text{range}\psi_* = \text{span}\{\psi_*X_1 = e^{2u_1} \frac{\partial}{\partial v_1}, \psi_*X_2 = e^{2u_1} \frac{\partial}{\partial v_3}\}$ and $(\text{range}\psi_*)^\perp = \text{span}\{\frac{\partial}{\partial v_2}, \frac{\partial}{\partial v_4}, \xi = \frac{\partial}{\partial v_5}\}$. It is also easy to check that

$$g_{N_2}(\psi_*X_1, \psi_*X_1) = e^{2u_1} g_{N_1}(X_1, X_1), \quad g_{N_2}(\psi_*X_2, \psi_*X_2) = e^{2u_1} g_{N_1}(X_2, X_2),$$

which show that ψ is a conformal Riemannian map with $\lambda = e^{u_1}$. Moreover, it is easy to see that $\varphi\psi_*X_1 = e^{2u_1} \frac{\partial}{\partial v_2}$ and $\varphi\psi_*X_2 = e^{2u_1} \frac{\partial}{\partial v_4}$. As a result, ψ is a conformal anti-invariant Riemannian map.

Remark 3.5. In this paper, we suppose that the Reeb vector field $\xi \in (\text{range}\psi_*)^\perp$.

Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to an almost contact metric manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. First of all, from Definition 3.1, we have $\varphi(\text{range}\psi_*) \cap (\text{range}\psi_*)^\perp \neq \{0\}$. We denote the complementary orthogonal distribution to $\varphi(\text{range}\psi_*)$ in $((\text{range}\psi_*)^\perp)$ by μ . Then we have

$$(\text{range}\psi_*)^\perp = \varphi(\text{range}\psi_*) \oplus \mu. \quad (3.4)$$

It is easy to see that μ is an invariant distribution of $(\text{range}\psi_*)^\perp$, under the endomorphism φ . Thus, for $U \in \Gamma((\text{range}\psi_*)^\perp)$, we have

$$\varphi U = \mathcal{D}U + \mathcal{E}U \quad (3.5)$$

where $\mathcal{D}U \in \Gamma(\text{range}\psi_*)$ and $\mathcal{E}U \in \Gamma((\text{range}\psi_*)^\perp)$.

We now investigate the geometry of the leaves of $(\text{range}\psi_*)$ and $(\text{range}\psi_*)^\perp$.

Theorem 3.6. *Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. Then $(range\psi_*)$ defines a totally geodesic foliation on N_2 if and only if*

$$g_{N_2}((\nabla\psi_*)(X_1, X_3)^{range\psi_*}, \varphi\psi_*X_2) = g_{N_2}(\nabla_{X_1}^{\psi\perp}\varphi\psi_*X_2, \mathcal{E}U) \tag{3.6}$$

for any $U \in \Gamma((range\psi_*)^\perp)$ and $X_1, X_2, X_3 \in \Gamma((ker\psi_*)^\perp)$, such that $\psi_*X_3 = \mathcal{D}U$.

Proof. For $U \in \Gamma((range\psi_*)^\perp)$ and $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$, using (2.2), (2.3) and (2.4) we have

$$g_{N_2}(\nabla_{X_1}^2\psi_*X_2, U) = g_{N_2}(\nabla_{X_1}^2\varphi\psi_*X_2, \varphi U).$$

Thus (3.5) we obtain

$$g_{N_2}(\nabla_{X_1}^2\psi_*X_2, U) = -g_{N_2}(\nabla_{X_1}^2\psi_*X_3, \varphi\psi_*X_2) + g_{N_2}(\nabla_{X_1}^2\varphi\psi_*X_2, \mathcal{E}U),$$

where $\psi_*X_3 = \mathcal{D}U$ for $X_3 \in \Gamma((ker\psi_*)^\perp)$. Since the map is a conformal anti-invariant Riemannian map, using (2.5), (2.7) and (3.2) we obtain

$$\begin{aligned} g_{N_2}(\nabla_{X_1}^2\psi_*X_2, U) &= -g_{N_2}((\nabla\psi_*)(X_1, X_3)^{range\psi_*} + (\nabla\psi_*)(X_1, X_3)^{range\psi_*}{}^\perp \\ &\quad + \psi_*(\nabla_{X_1}^{N_1}X_3), \varphi\psi_*X_2) \\ &\quad + g_{N_2}(-A_{\varphi\psi_*X_2}X_1 + \nabla_{X_1}^{\psi\perp}\varphi\psi_*X_2, \mathcal{E}U). \end{aligned}$$

Hence, we arrive at

$$\begin{aligned} g_{N_2}(\nabla_{X_1}^2\psi_*X_2, U) &= -g_{N_2}((\nabla\psi_*)(X_1, X_3)^{range\psi_*}{}^\perp, \varphi\psi_*X_2) \\ &\quad + g_{N_2}(\nabla_{X_1}^{\psi\perp}\varphi\psi_*X_2, \mathcal{E}U). \end{aligned}$$

From above equation, $(range\psi_*)$ defines a totally geodesic foliation on N_2 if and only if (3.6) is satisfied. \square

Theorem 3.7. *Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. Then two of the assertions imply the other one:*

- (a) $(range\psi_*)^\perp$ defines a totally geodesic foliation on N_2 .
- (b) ψ is a horizontally homothetic conformal Riemannian map.
- (c) $g_{N_2}(\mathcal{D}U_1, A_{\mathcal{E}U_1}\psi_*X_1 + \psi_*(\nabla_{X_1}^{N_1}X_2)) = -g_{N_2}(\mathcal{E}U_2, (\nabla\psi_*)(X_1, X_2)^{range\psi_*}{}^\perp + \nabla_{X_1}^{\psi\perp}\mathcal{E}U_1) - g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2U_1)$

for any $U_1, U_2 \in \Gamma((range\psi_*)^\perp)$ and $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$, such that $\psi_*X_2 = \mathcal{D}U_1$.

Proof. For $U_1, U_2 \in \Gamma((range\psi_*)^\perp)$ and $X_1 \in \Gamma((ker\psi_*)^\perp)$, since N_2 is a cosymplectic manifold, using (2.2) and (2.3) we have

$$\begin{aligned} g_{N_2}(\nabla_{U_1}^2U_2, \psi_*X_1) &= -g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2U_1) \\ &\quad - g_{N_2}(\varphi U_2, \nabla_{\psi_*X_1}^2\varphi U_1). \end{aligned}$$

Then using (3.5), (2.5) and (2.7) we obtain

$$\begin{aligned} g_{N_2}(\nabla_{U_1}^2U_2, \psi_*X_1) &= -g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2U_1) \\ &\quad - g_{N_2}(\mathcal{D}U_2, (\nabla\psi_*)(X_1, X_2) + \psi_*(\nabla_{X_1}^{N_1}X_2)) \\ &\quad - g_{N_2}(\mathcal{D}U_2, -A_{\mathcal{E}U_1}\psi_*X_1 \\ &\quad + \nabla_{X_1}^{\psi\perp}\mathcal{E}U_1) - g_{N_2}(\mathcal{E}U_2, (\nabla\psi_*)(X_1, X_2) + \psi_*(\nabla_{X_1}^{N_1}X_2)) \\ &\quad - g_{N_2}(\mathcal{E}U_2, -A_{\mathcal{E}U_1}\psi_*X_1 + \nabla_{X_1}^{\psi\perp}\mathcal{E}U_1) \end{aligned}$$

where $\psi_*X_2 = \mathcal{D}U_1 \in \Gamma(\text{range}\psi_*)$ for $X_2 \in \Gamma((\ker\psi_*)^\perp)$. Since ψ is a conformal anti-invariant Riemannian map, using (3.2), we arrive at

$$\begin{aligned} g_{N_2}(\nabla_{U_1}^2 U_2, \psi_*X_1) &= -g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2 U_1) \\ &\quad - g_{N_2}(\mathcal{D}U_2, (\nabla\psi_*)(X_1, X_2)^{\text{range}\psi_*}) - g_{N_2}(\mathcal{D}U_2, \psi_*(\nabla_{X_1}^{N_1} X_2)) \\ &\quad + g_{N_2}(\mathcal{D}U_2, A_{\mathcal{E}U_1}\psi_*X_1) - g_{N_2}(\mathcal{E}U_2, (\nabla\psi_*)(X_1, X_2)^{\text{range}\psi_*}) \\ &\quad - g_{N_2}(\mathcal{E}U_2, \nabla_{X_1}^{\psi_\perp}\mathcal{E}U_1). \end{aligned}$$

Then from (3.3), we get

$$\begin{aligned} g_{N_2}(\nabla_{U_1}^2 U_2, \psi_*X_1) &= -g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2 U_1) \\ &\quad - g_{N_2}(\mathcal{D}U_2, \psi_*(\nabla_{X_1}^{N_1} X_2)) + g_{N_2}(\mathcal{D}U_2, A_{\mathcal{E}U_1}\psi_*X_1) \\ &\quad - g_{N_2}(\mathcal{E}U_2, (\nabla\psi_*)(X_1, X_2)^{\text{range}\psi_*}) - g_{N_2}(\mathcal{E}U_2, \nabla_{X_1}^{\psi_\perp}\mathcal{E}U_1) \\ &\quad - g_{N_2}(\mathcal{D}U_2, X_1(\ln \lambda)\psi_*X_2 + X_2(\ln \lambda)\psi_*X_1) \\ &\quad - g_{N_1}(X_1, X_2)\psi_*(\text{grad} \ln \lambda) \end{aligned}$$

or

$$\begin{aligned} g_{N_2}(\nabla_{U_1}^2 U_2, \psi_*X_1) &= -g_{N_2}(U_2, [U_1, \psi_*X_1]) - \eta(U_2)\eta(\nabla_{\psi_*X_1}^2 U_1) \\ &\quad - g_{N_2}(\mathcal{D}U_2, \psi_*(\nabla_{X_1}^{N_1} X_2)) + g_{N_2}(\mathcal{D}U_2, A_{\mathcal{E}U_1}\psi_*X_1) \\ &\quad - g_{N_2}(\mathcal{E}U_2, (\nabla\psi_*)(X_1, X_2)^{\text{range}\psi_*}) - g_{N_2}(\mathcal{E}U_2, \nabla_{X_1}^{\psi_\perp}\mathcal{E}U_1) \\ &\quad - g_{N_1}(X_1, \text{grad} \ln \lambda)g_{N_2}(\mathcal{D}U_2, \psi_*X_2) \\ &\quad - g_{N_1}(X_2, \text{grad} \ln \lambda)g_{N_2}(\mathcal{D}U_2, \psi_*X_1) \\ &\quad + g_{N_1}(X_1, X_2)g_{N_2}(\mathcal{D}U_2, \psi_*(\text{grad} \ln \lambda)). \end{aligned}$$

From above equation, we can conclude that the two assertions in Theorem 3.7 imply the third. \square

In the sequel we are going to investigate the harmonicity of conformal anti-invariant Riemannian map.

Theorem 3.8. *Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. Then ψ is harmonic if the following conditions are satisfied;*

- (a) *the fibres are minimal,*
- (b) *$\text{trace}\mathcal{D}\nabla_{(\cdot)}^{\psi_\perp}\varphi\psi_*(\cdot) + \psi_*(\nabla_{(\cdot)}^{N_1}(\cdot)) = 0,$*
- (c) *$\text{trace}\varphi A_{\varphi\psi_*(\cdot)}\psi_*(\cdot) - \mathcal{E}\nabla_{(\cdot)}^{\psi_\perp}\varphi\psi_*(\cdot) = 0.$*

Proof. For $V \in \Gamma(\ker\psi_*)$, using (2.5), we have

$$(\nabla\psi_*)(V, V) = -\psi_*(\nabla_V^{N_1} V). \tag{3.7}$$

For $Y \in \Gamma((\ker\psi_*)^\perp)$, using (2.2), (2.3), (2.4) and (2.5), we have

$$(\nabla\psi_*)(Y, Y) = \nabla_Y^2\psi_*Y - \psi_*(\nabla_Y^{N_1} Y) = -\varphi\nabla_Y^2\varphi\psi_*Y - \psi_*(\nabla_Y^{N_1} Y).$$

From (2.7), (3.2) and (3.5) we obtain

$$\begin{aligned} (\nabla\psi_*)(Y, Y)^{\text{range}\psi_*} + (\nabla\psi_*)(Y, Y)^{\text{range}\psi_*\perp} &= \\ \varphi A_{\varphi\psi_*Y}\psi_*Y - \psi_*(\nabla_Y^{N_1} Y) - \mathcal{D}\nabla_Y^{\psi_\perp}\varphi\psi_*Y - \mathcal{E}\nabla_Y^{\psi_\perp}\varphi\psi_*Y. \end{aligned} \tag{3.8}$$

Then taking the $(\text{range}\psi_*)$ -components and $((\text{range}\psi_*)^\perp)$ -components of above expression (3.8), we arrive at

$$(\nabla\psi_*)(Y, Y)^{\text{range}\psi_*} = -\mathcal{D}\nabla_Y^{\psi_\perp}\varphi\psi_*Y - \psi_*(\nabla_Y^{N_1} Y). \tag{3.9}$$

and

$$(\nabla\psi_*)(Y, Y)^{(range\psi_*)^\perp} = -\mathcal{E}\nabla_Y^{\psi_\perp}\varphi\psi_*Y + \varphi\mathcal{A}_{\varphi\psi_*Y}\psi_*Y. \tag{3.10}$$

Then proof follows from (3.7), (3.9) and (3.10). \square

Now, we give necessary and sufficient conditions for a conformal anti-invariant Riemannian map to be total geodesic.

Theorem 3.9. *Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. Then ψ is totally geodesic if and only if*

- (a) $g_{N_2}(\mathcal{D}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4, \psi_*X_5) = -\lambda^2g_{N_1}(\nabla_{X_1}^{N_1}X_2, X_5)$
- (b) $\varphi\mathcal{A}_{\varphi\psi_*X_4}X_1 = \mathcal{E}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X$

for any $X_1, X_2 = X_3 + X_4, X_5 \in \Gamma(TN_1)$, where $X_4 \in \Gamma((ker\psi_*)^\perp)$, $X_3 \in \Gamma(ker\psi_*)$.

Proof. For $X_1, X_2 \in \Gamma(TN_1)$ and $X_4 \in \Gamma((ker\psi_*)^\perp)$, $X_3 \in \Gamma(ker\psi_*)$, using (2.3), (2.4), (2.5) and (2.7) we have $(\nabla\psi_*)(X_1, X_2) = -\varphi(-\mathcal{A}_{\varphi\psi_*X_4}\psi_*X_1 + \nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4) - \psi_*(\nabla_{X_1}^{N_1}X_2)$. Then from (3.5) we get $(\nabla\psi_*)(X_1, X_2) = \varphi\mathcal{A}_{\varphi\psi_*X_4}\psi_*X_1 - \mathcal{D}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 - \mathcal{E}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 - \psi_*(\nabla_{X_1}^{N_1}X_2)$. Since ψ is conformal anti-invariant Riemannian map, using (3.2), we get

$$\begin{aligned} &(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)} + (\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp} = \\ &\varphi\mathcal{A}_{\varphi\psi_*X_4}\psi_*X_1 - \mathcal{D}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 - \mathcal{E}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 - \psi_*(\nabla_{X_1}^{N_1}X_2). \end{aligned}$$

Then taking the $(range\psi_*)$ and $(range\psi_*)^\perp$ components we arrive at

$$(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)} = -\mathcal{D}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 - \psi_*(\nabla_{X_1}^{N_1}X_2)$$

and

$$(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp} = -\mathcal{E}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 + \varphi\mathcal{A}_{\varphi\psi_*X_4}\psi_*X_1.$$

Thus $(\nabla\psi_*)(X_1, X_2) = 0$ if and only if $(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)} = 0$ and $(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp} = 0$. Hence we have $g_{N_2}(\mathcal{D}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4, \psi_*X_5) = -\lambda^2g_{N_1}(\nabla_{X_1}^{N_1}X_2, X_5)$ and $\varphi\mathcal{A}_{\varphi\psi_*X_4}\psi_*X_1 - \mathcal{E}\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_4 = 0$, which complete the proof. \square

Also, we have the following result for totally geodesic conformal anti-invariant Riemannian maps.

Theorem 3.10. *Let ψ be a conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$. Then ψ is totally geodesic if and only if*

- (a) *The horizontal distribution $(ker\psi_*)^\perp$ defines a totally geodesic foliation on N_1 .*
- (b) *All the fibres $\psi^{-1}(q_2)$ are totally geodesic for $q_2 \in N_2$.*
- (c) $g_{N_2}((\nabla\psi_*)(X_1, X_3)^{(range\psi_*)^\perp}, \varphi\psi_*X_2) = g_{N_2}((\nabla_{X_1}^{\psi_\perp}\varphi\psi_*X_2, \mathcal{E}U)$

for any $X_1, X_2, X_3 \in \Gamma((ker\psi_*)^\perp)$, and $U \in \Gamma(range\psi_*)^\perp$.

Proof. For $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$, and $V \in \Gamma(ker\psi_*)$, using (2.5), we have

$$g_{N_2}((\nabla\psi_*)(X_1, V), \psi_*X_2) = -\lambda^2g_{N_1}(\nabla_{X_1}^{N_1}V, X_2).$$

∇^{N_1} is a Levi-Civita connection, we obtain

$$g_{N_2}((\nabla\psi_*)(X_1, V), \psi_*X_2) = \lambda^2g_{N_1}(\nabla_{X_1}^{N_1}X_2, V).$$

Hence $(\nabla\psi_*)(X_1, V) = 0$ for $X_1 \in \Gamma((ker\psi_*)^\perp)$ and $V \in \Gamma(ker\psi_*)$ if and only if (a). For $Y \in \Gamma((ker\psi_*)^\perp)$ and $U_1, U_2 \in \Gamma(ker\psi_*)$, we have

$$g_{N_2}((\nabla\psi_*)(U_1, U_2), \psi_*Y) = -\lambda^2 g_{N_1}(\nabla_{U_1}^{N_1} U_2, Y).$$

Thus $(\nabla\psi_*)(U_1, U_2) = 0$ for $U_1, U_2 \in \Gamma(ker\psi_*)$ if and only if (b).

For $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$ and $U \in \Gamma(range\psi_*)^\perp$, since N_2 is a cosymplectic manifold, using (2.2), (2.3), (2.5) and (3.5) we have

$$g_{N_2}((\nabla\psi_*)(X_1, X_2), U) = -g_{N_2}((\nabla_{X_1}^2 \psi_* X_3, \varphi\psi_* X_2) + g_{N_2}((\nabla_{X_1}^2 \varphi\psi_* X_2, \mathcal{E}U),$$

where $\psi_* X_3 = \mathcal{D}U$ for $X_3 \in \Gamma((ker\psi_*)^\perp)$. Since ψ is a conformal anti-Riemannian map, using (2.5), (2.7) and (3.2) we obtain

$$g_{N_2}((\nabla\psi_*)(X_1, X_2), U) = -g_{N_2}((\nabla\psi_*)(X_1, X_3)^{(range\psi_*)^\perp}, \varphi\psi_* X_2) + g_{N_2}((\nabla_{X_1}^{\psi^\perp} \varphi\psi_* X_2, \mathcal{E}U).$$

Thus, $(\nabla\psi_*)(X_1, X_2) = 0$ for $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$ if and only if (c). □

Now, we investigate the umbilical case in [11] for the conformal anti-invariant Riemannian maps.

Let ψ be a map from a Riemannian manifold (N_1, g_{N_1}) to a Riemannian manifold (N_2, g_{N_2}) . Then ψ is called a weakly g_{N_1} -umbilical if there exist

- a) a field X_3 along ψ , nowhere, 0, with values in $range\psi_*$,
- b) a field X_4 on N_1 such that for every X_1, X_2 on $\Gamma(TN_1)$ we have

$$(\nabla\psi_*)(X_1, X_2) = g_{N_1}(X_1, X_2)[\psi_* X_4 + X_3]. \tag{3.11}$$

ψ is called strong g_{N_1} -umbilical if $X_4 = 0$.

Using the above definition, we can give the following theorem.

Theorem 3.11. *Let ψ be a weakly g_{N_1} -umbilical conformal anti-Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$ such that $dim(\mathcal{H}) \geq 2$. Then ψ is totally geodesic map.*

Proof. We suppose that ψ is a weakly g_{N_1} -umbilical conformal anti-Riemannian map such that $dim(\mathcal{H}) \geq 2$. Then from (3.3) and (3.11) we have

$$X_1(\ln\lambda)\psi_* X_2 + X_2(\ln\lambda)\psi_* X_1 - g_{N_1}(X_1, X_2)\psi_*(grad \ln \lambda) = g_{N_1}(X_1, X_2)\psi_* X_4 \tag{3.12}$$

and

$$(\nabla\psi_*)(X_1, X_2)^{(range\psi_*)^\perp} = g_{N_1}(X_1, X_2)X_3, \tag{3.13}$$

for $X_1, X_2 \in \Gamma((ker\psi_*)^\perp)$. Since $dim(\mathcal{H}) \geq 2$, we can choose X_1 and X_2 such that $g_{N_1}(X_1, X_2) = 0$. Then we get

$$X_1(\ln\lambda)\psi_* X_2 + X_2(\ln\lambda)\psi_* X_1 = 0.$$

Since X_1 and X_2 are orthogonal and ψ is a conformal anti-Riemannian map, we have $g_{N_2}(\psi_* X_1, \psi_* X_2) = \lambda^2 g_{N_1}(X_1, X_2) = 0$. $\psi_* X_1$ and $\psi_* X_2$ are also orthogonal. Then we get

$$X_1(\ln\lambda)\psi_* X_2 = 0, X_2(\ln\lambda)\psi_* X_1 = 0.$$

Thus ψ is a horizontally homothetic Riemannian map. Since ψ is horizontally homothetic Riemannian map, from (3.12), we get $X_4 = 0$. Thus $(\nabla\psi_*)(X_1, X_2) = g_{N_1}(X_1, X_2)X_3$ for $X_1, X_2 \in \Gamma(TN_1)$. In particular, for $U_1, U_2 \in \Gamma(ker\psi_*)$, we get $-\psi_*(\nabla_{U_1} U_2) = g_{N_1}(U_1, U_2)X_3$. The right side of this equation belongs to $\Gamma((range\psi_*)^\perp)$ while the left side of this equation belongs to $\Gamma(range\psi_*)$. Hence $\psi_*(\nabla_{U_1} U_2) = 0$ and $X_3 = 0$ which proves our assertion. □

From Theorem 3.10 and Theorem 3.11, we have:

Corollary 3.12. *Let ψ be a strong g_{N_1} -umbilical conformal anti-invariant Riemannian map from a Riemannian manifold (N_1, g_{N_1}) to a cosymplectic manifold $(N_2, g_{N_2}, \varphi, \eta, \xi)$ such that $\dim(\mathcal{H}) \geq 2$. Then we have the following:*

- (a) *The horizontal distribution $(\ker \psi_*)^\perp$ defines a totally geodesic foliation on N_1 .*
- (b) *All the fibres $\psi^{-1}(q_2)$ are totally geodesic for $q_2 \in N_2$.*
- (c) *$(\text{range} \psi_*)^\perp$ defines a totally geodesic foliation on N_2 .*

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